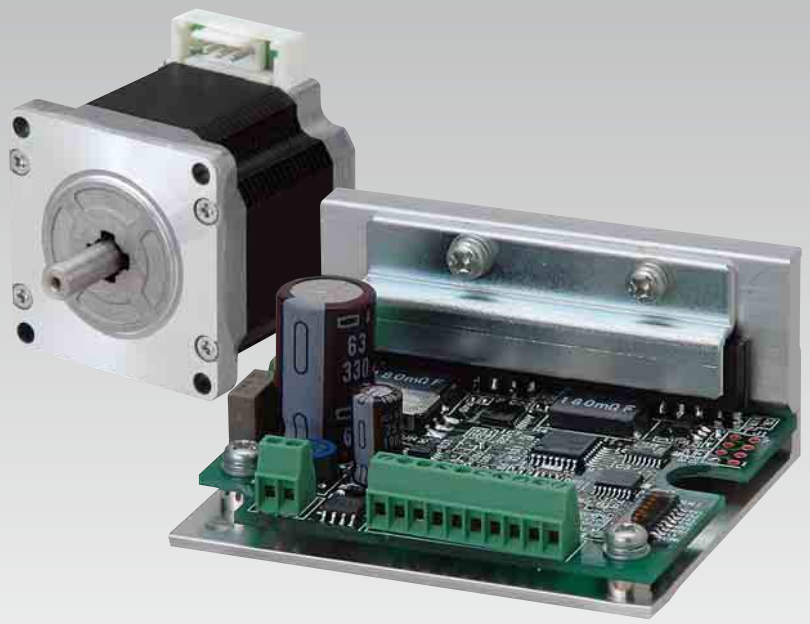
SANMOTION

2-PHASE STEPPING SYSTEMS

F2

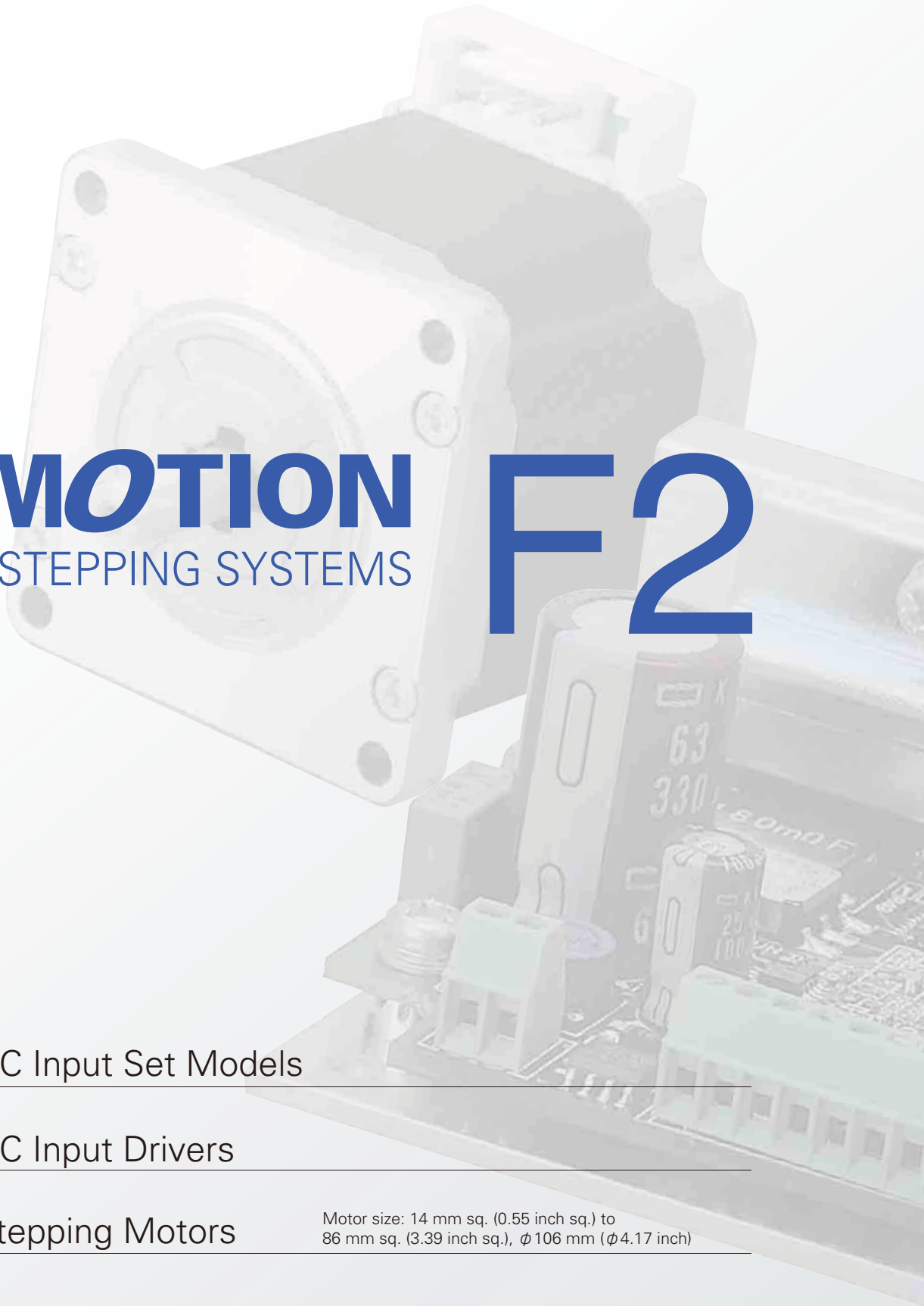


Ver.5

SANYO DENKI

SANMOTION F2

2-PHASE STEPPING SYSTEMS



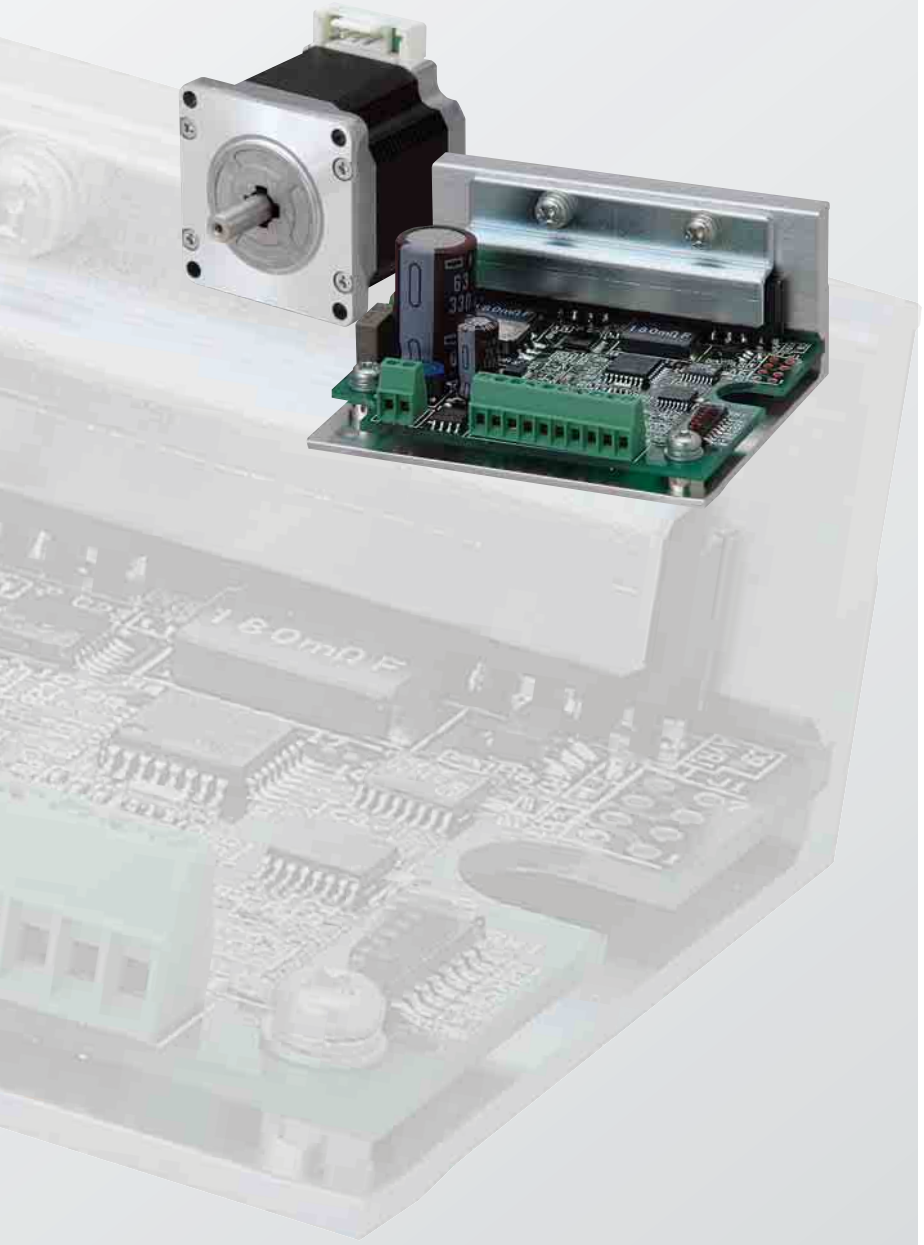
DC Input Set Models

DC Input Drivers

Stepping Motors

Motor size: 14 mm sq. (0.55 inch sq.) to
86 mm sq. (3.39 inch sq.), ϕ106 mm (ϕ4.17 inch)

Stepping Motors with Integrated Drivers · IP65 Splash and Dust Proof Stepping Motors · Stepping Motors for Vacuum Environments · Synchronous Motors

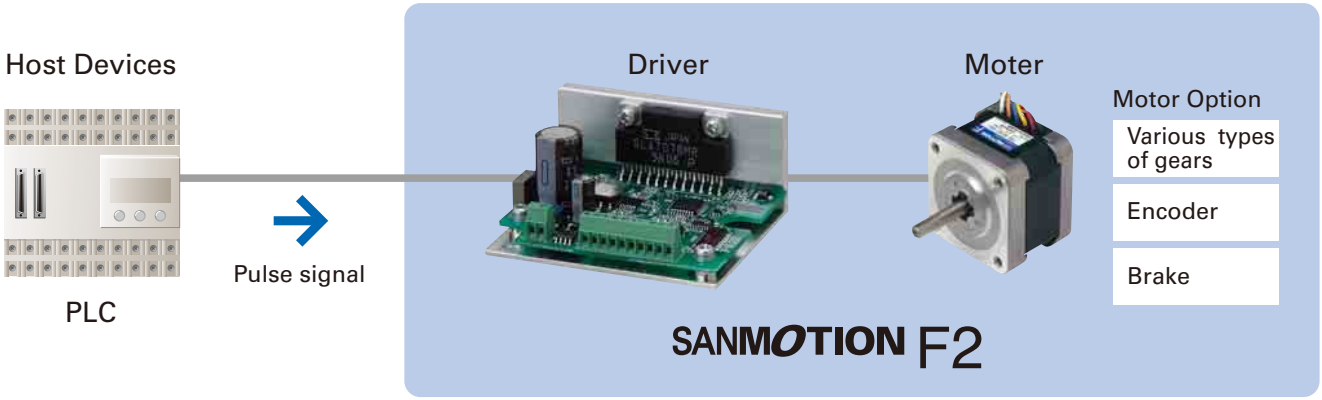


Contents

SANMOTION F2

2-PHASE STEPPING SYSTEMS

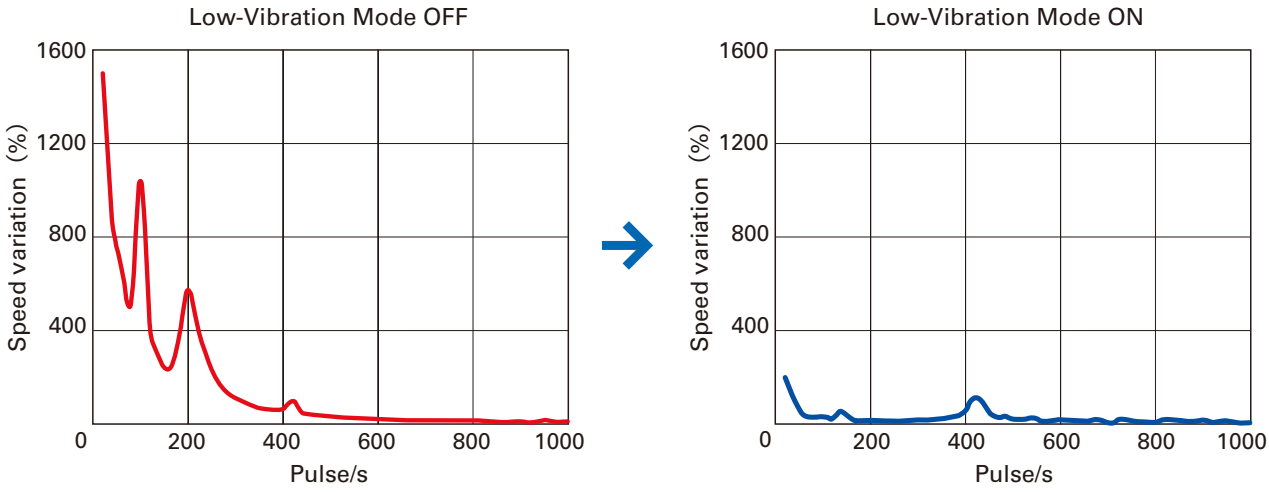
SANMOTION F2 is a 2-phase stepping system that provides precise positioning with easy control. The typical basic step angle is 1.8˚, and accurate control is provided by pulse signals.



Features

- Small driver and motor, yet high torque.
- Fast response provides shorter system cycle time for repetitive operations.
- Holding torque maintains the stop position when engaging power.
- Low-vibration mode

  Smooth driving is achieved even with one-division (full-step) and two-division (half-step) coarse resolution settings. Vibrations are suppressed without control system restrictions.



- Micro-step driving system

  Five 1.8˚ basic step angle resolutions can be selected from 1 to 16 divisions (1.8˚ to 0.1125˚ per pulse). This enables a smooth operation with low vibration.

Safety standards

The SANMOTION F2 drive complies with CE (EN standards) and UL standard specifications.

Lineup

Convenient set models consist of a DC-powered driver and motor.
Aside from the set models it is also possible to select stepping motors separately.
We also provide a selection of stepping motors with integrated drivers as well as models with IP65 Ingress Protection ratings.
Customized stepping motors for vacuum environments and synchronous motors are also available.

Set Models

DC input

Unipolar

These set models consist of a DC-powered driver and motor.
The motor winding specification is unipolar.

Motor size:
28 mm sq. (1.10 inch sq.) / 42 mm sq. (1.65 inch sq.) / 56 mm sq.(2.20 inch sq.)

Bipolar

These set models consist of a DC-powered driver and motor.
The motor winding specification is bipolar.

Motor size:
28 mm sq. (1.10 inch sq.) / 42 mm sq.(1.65 inch sq.) / 50 mm sq (1.97 inch sq.) /
56 mm sq. (2.20 inch sq.) / 60 mm sq. (2.36 inch sq.)

Stepping Motors

High-torque stepping motors. Select from among a broad lineup of products from an ultra-compact 14 mm sq. (0.55 inch sq.) motor size, to a thin 11.4 mm (0.45 inch) motor - the shortest motor length.

A separate driver is required.

Motor size:
14 mm sq. (0.55 inch sq.) / 28 mm sq. (1.10 inch sq.) /
35 mm sq. (1.38 inch sq.) / 42 mm sq. (1.65 inch sq.) /
50 mm sq. (1.97 inch sq.) / 56 mm sq. (2.20 inch sq.) /
60 mm sq. (2.36 inch sq.) / 86 mm sq.
(3.39 inch sq., CE and UL models are available.) /
ϕ106 mm (ϕ4.17 inch)

Stepping Motors with Integrated Drivers

These motors include integrated drivers. This reduces mounting space requirements and wiring complexity. Three separate control modes: pulse train control, general purpose I/O (parallel interface), and RS-485 compliant serial communications can be selected.

Motor size:
42 mm sq. (1.65 inch sq.) /
60 mm sq. (2.36 inch sq.)

IP65 Splash and Dust Proof Stepping Motors

These IP65 rated motors* have superior water and dust resistance, and can be safely utilized in harsh or wet environments such as in food processing machines.
The input voltage range of the motors is up to AC 250 V.

※ Except for the shaft and the cable end.

A separate driver is required.

Motor size:
56 mm sq. (2.20 inch sq.) /
86 mm sq. (3.39 inch sq.)

Stepping Motors for Vacuum Environments Customized Products

We can customize motors for use in low to ultrahigh vacuum environments to suit your system requirements.

A separate driver is required.

Synchronous Motors Customized Products

Synchronous motors rotate at a constant speed in proportion to the AC power frequency. They operate on the commercial (AC) power supply.

Lineup Details

Set Models Page P.8 ~

Series		DC input set models Unipolar 	DC input set models Bipolar 
Input source		DC 24V/36V	DC 24V/36V
Number of divisions		1, 2, 4, 8, 16	1, 2, 4, 8, 16
Step-angle	Motors with 1.8˚ basic step angle	1.8˚ to 0.1125˚ / pulse	1.8˚ to 0.1125˚ / pulse
	Motors with 0.9˚ basic step angle	0.9˚ to 0.05625˚ / pulse	0.9˚ to 0.05625˚ / pulse
Corresponding motor sizes		28 mm sq. (1.10 in sq.) / 42 mm sq. (1.65 in sq.) / 56 mm sq. (2.20 in sq.)	28 mm sq. (1.10 in sq.) / 42 mm sq. (1.65 in sq.) / 50 mm sq. (1.97 in sq.) / 56 mm sq. (2.20 in sq.) / 60 mm sq. (2.36 in sq.)
Control method		Pulse input · Open loop	Pulse input · Open loop
Set model accessories		Driver, Motor, Cable with connector (Supplied only with connector-type motors)	Driver, Motor, Cable with connector (Supplied only with connector-type motors)
Page	System Configuration Diagram	P.8	P.8
	Set Model Configuration Diagram	P.10	P.10
	Specifications / Characteristics Diagram	P.11 to 13	P.14 to 18
	Driver Specifications / Safety Standards	P.19	P.19
	Motor Specifications	P.57	P.57
	Dimensions	P.69 to 75	P.69 to 75

Stepping Motors Page P.24 ～

Basic step angle	Motor size	Holding torque N・m (oz・in)	Model number	Page	
				Specifications / Characteristics diagram	Dimensions
0.9°	42 mm sq. (1.65 in sq.)	0.2 to 0.48 (28.3 to 68.0)	SH142 □ - □□□ 1	P.29 to 30	P.70
0.9°	60 mm sq. (2.36 in sq.)	0.57 to 2.15 (80.7 to 304)	SH160 □ - □□□ 0	P.42 to 43	P.71
1.8°	14 mm sq. (0.55 in sq.)	0.0065 (0.92)	SH2141-55 □ 1	P.24	P.69
1.8°	28 mm sq. (1.10 in sq.)	0.055 to 0.145 (7.79 to 20.5)	SH228 □ -5 □□ 1	P.25 to 26	P.69
1.8°	35 mm sq. (1.38 in sq.)	0.12 to 0.23 (17.0 to 32.6)	SH35 □□ -12U □ 0	P.27	P.69
1.8°	42 mm sq. (1.65 in sq.) Slim form	0.083 to 0.186 (11.8 to 26.3)	SS242 □ -50 □ 1	P.28	P.69
1.8°	42 mm sq. (1.65 in sq.)	0.2 to 0.51 (28.3 to 72.2)	103H52 □□ - □□□ 0	P.31 to 33	P.69 to 70
1.8°	50 mm sq. (1.97 in sq.)	0.28 to 0.53 (39.7 to 75.1)	103H670 □ - □□□ 0	P.34 to 36	P.70
1.8°	50 mm sq. (1.97 in sq.) Slim form	0.1 to 0.215 (14.2 to 30.4)	SS250 □ -80 □ 0	P.37	P.70
1.8°	56 mm sq. (2.20 in sq.)	0.39 to 2.0 (55.2 to 283)	103H712 □ - □□□ 0	P.38 to 41	P.71
1.8°	60 mm sq. (2.36 in sq.)	0.78 to 2.7 (110 to 382)	103H782 □ - □□□ 0	P.44 to 47	P.72
1.8°	86 mm sq. (3.39 in sq., CE and UL models are available.)	2.5 to 9 (358 to 1270)	SH286 □ - □□□ 1 SM286 □ - □□□□	P.48 to 51	P.73
1.8°	ϕ106 mm (ϕ4.17 in)	10.8 to 19 (1530 to 2690)	103H8922 □ - □□□ 1	P.52	P.74
1.8°	56 mm sq. (2.20 in sq., CE Model)	0.39 to 1.27 (55.2 to 179.8)	103H712 □ -6 □□ 0	P.53	P.73
1.8°	ϕ86 mm (ϕ3.39 in, CE Model)	2.74 to 7.44 (388 to 1053.6)	103H822 □ -6 □□ 0	P.54	P.74
1.8°	ϕ106 mm (ϕ4.17 in, CE Model)	13.2 to 19 (1869.2 to 2690.5)	103H8922 □ -63 □ 1	P.55	P.74

・ Contact us for available encoders, gears and motors with brakes.

Stepping Motors with Integrated Drivers Page P.58 ～

Motor size	Input source	Interfaces	Model number	Page	
				Specifications / Characteristics diagram	Dimensions
42 mm sq. (1.65 in sq.)	DC24V	・Pulse input ・General-purpose I/O(Parallel) ・Serial communications (compliant with RS-485)	DB21M142S-01	P.59	P.75
60 mm sq. (1.65 in sq.)			DB22M162S-01	P.59	P.75

IP65 Splash and Dust Proof Stepping Motors Page P.65 ～

Basic step angle	Motor size	Holding torque N・m (oz・in)	Safety standards	Model number	Page	
					Specifications / Characteristics diagram	Dimensions
1.8°	56 mm sq. (2.20 in sq.)	1 to 1.7 (141.6 to 240.7)	CE Model	SP256 □ T-5 □□ 0	P.66	P.76
			CE･UL Model	SP256 □ -5 □ 60	P.66	P.76
1.8°	86 mm sq. (3.39 in sq.)	6.4 to 9 (906.3 to 1274.5)	CE Model	SP286 □ T-5 □□ 0	P.67	P.76
			CE･UL Model	SP286 □ -5 □ 60	P.67	P.76

Stepping Motors for Vacuum Environments Customized Products Page P.68

We can customize motors for use in low to ultra-high vacuum environments to suit your system requirements.
We can handle a wide range of pressures for low, high and ultrahigh vacuums.

Synchronous Motors Customized Products Page P.68

Synchronous motors rotate at a constant speed in proportion to the AC power frequency. They operate on the commercial (AC) power supply.

DC Input Set Models

Unipolar • Bipolar

Set Model Configuration ▶P.10
Specifications / Characteristics Diagram ▶P.11 to 18
Motor Specifications ▶P.57 Driver Specifications ▶P.19
Motor Dimensions ▶P.69 to 72
Driver Dimensions ▶P.75

Features

- These are convenient sets of DC-powered drivers and motors.
- Select from two types of set models: with either unipolar or bipolar motor windings.

Set model configuration items

Driver

Unipolar Model number : US1D200P10 Input source : DC24V/36V
Bipolar Model number : BS1D200P10 Input source : DC24V/36V

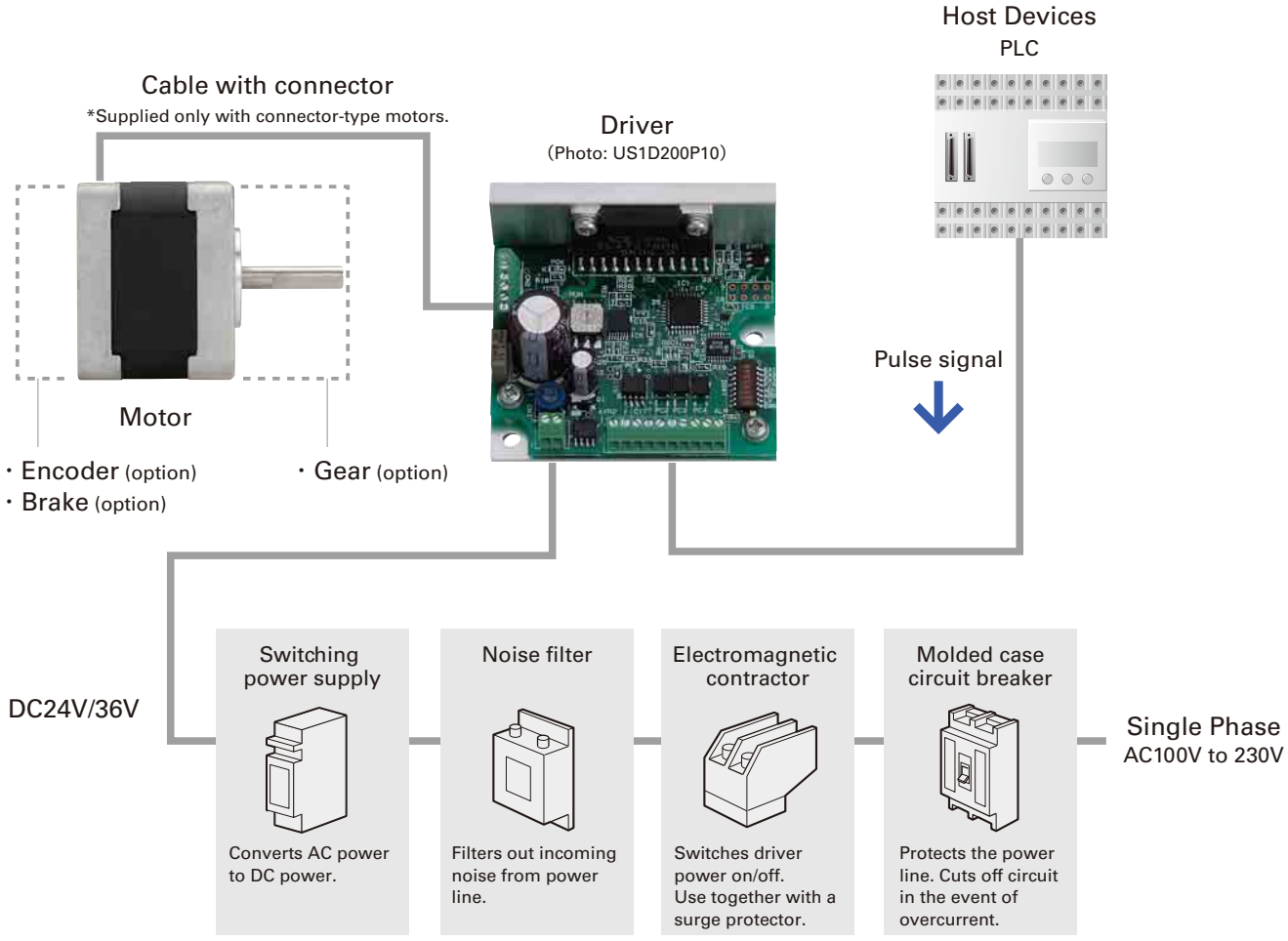
Motor

Unipolar Motor size: 28 mm sq. (1.10 inch sq.), 42 mm sq. (1.65 inch sq.), 56 mm sq. (2.20 inch sq.)
Bipolar Motor size: 28 mm sq. (1.10 inch sq.), 42 mm sq. (1.65 inch sq.), 50 mm sq. (1.97 inch sq.), 56 mm sq. (2.20 inch sq.), 60 mm sq. (2.36 inch sq.)

Cable with connector *Supplied only with connector-type motors

- Instruction manuals can be downloaded from our website.

System Configuration Diagram



Set Model Numbering Convention

Here is the set model number for a DC-powered unipolar driver (Model No. US1D200P10) and motor (Model No. 103H7121-0440). Motor size is 56 mm sq. (2.20 in sq.), and motor length is 41.8 mm (1.65 in.), single-shaft.

Stepping motor shaft specification
S : Single shaft
D : Dual shaft

Stepping motor total length

Code	Stepping motor size													
	28 mm sq. (1.10 in sq.)		**42 mm sq. (1.65 in sq.)**				**50 mm sq. (1.97 in sq.)**		**56 mm sq. (2.20 in sq.)**		**60 mm sq. (2.36 in sq.)**			
	Type code	Motor length : mm (in)	Type code	Motor length : mm (in)	Type code	Motor length : mm (in)	Type code	Motor length : mm (in)	Type code	Motor length : mm (in)	Type code	Motor length : mm (in)	Type code	Motor length : mm (in)
1	SH2281	32 (1.26)	103H5205	33 (1.30)	SH1421	33 (1.30)	103H6701	39.8 (1.57)	103H7121	41.8 (1.65)	103H7821	44.8 (1.76)	SH1601	42 (1.65)
2			103H5208	39 (1.54)	SH1422	39 (1.54)					103H7822	53.8 (2.12)	SH1602	54 (2.12)
3							103H6703	51.3 (2.02)	103H7123	53.8 (2.12)	103H7823	85.8 (3.38)		
4			103H5210	48 (1.89)	SH1424	48 (1.89)								
5	SH2285	51.5 (2.03)												
6									103H7126	75.8 (2.89)				

Stepping motor size — Basic step angle
28 : 28 mm sq. (1.10 inch sq.) 1.8˚
52 : 42 mm sq. (1.65 inch sq.) 1.8˚
14 : 42 mm sq. (1.65 inch sq.) 0.9˚
67 : 50 mm sq. (1.97 inch sq.) 1.8˚
71 : 56 mm sq. (2.20 inch sq.) 1.8˚
78 : 60 mm sq. (2.36 inch sq.) 1.8˚
16 : 60 mm sq. (2.36 inch sq.) 0.9˚

Stepping motor series name
H : H series
S : SH series

Rated current specification
4 : 1 A / phase 5 : 1.2 A / phase 6 : 2 A / phase

Model

Driver specification
U : Unipolar B : Bipolar

D : DC input

Set Model Configuration

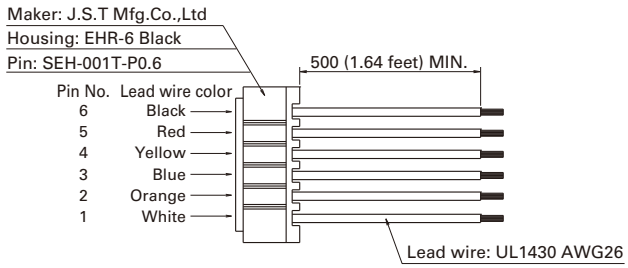
This is a set comprising a driver, motor and cable with motor connector.

Unipolar Bundled driver model number : US1D200P10

Motor size	Single shaft			Dual shaft			Basic step angle	Rated current (A/phase)	Page	
	Set model number	Set configuration items		Set model number	Set configuration items					
		Motor model number	Cable with motor connector model number		Motor model number	Cable with motor connector model number			Specifications	Dimensions
28 mm sq.	DU14S281S	SH2281-5271	—	DU14S281D	SH2281-5231	—	1.8°	1	P.11	P.69
	DU14S285S	SH2285-5271	—	DU14S285D	SH2285-5231	—	1.8°	1	P.11	P.69
42 mm sq.	DU15H521S	103H5205-0440	4835710-1	DU15H521D	103H5205-0410	4835710-1	1.8°	1.2	P.11	P.69
	DU15H522S	103H5208-0440	4835710-1	DU15H522D	103H5208-0410	4835710-1	1.8°	1.2	P.11	P.69
	DU15H524S	103H5210-0440	4835710-1	DU15H524D	103H5210-0410	4835710-1	1.8°	1.2	P.12	P.69
	DU15S141S	SH1421-0441	—	DU15S141D	SH1421-0411	—	0.9°	1.2	P.12	P.70
	DU15S142S	SH1422-0441	—	DU15S142D	SH1422-0411	—	0.9°	1.2	P.12	P.70
	DU15S144S	SH1424-0441	—	DU15S144D	SH1424-0411	—	0.9°	1.2	P.12	P.70
56 mm sq.	DU16H711S	103H7121-0440	—	DU16H711D	103H7121-0410	—	1.8°	2	P.13	P.71
	DU16H713S	103H7123-0440	—	DU16H713D	103H7123-0410	—	1.8°	2	P.13	P.71
	DU16H716S	103H7126-0440	—	DU16H716D	103H7126-0410	—	1.8°	2	P.13	P.71

● Cable with motor connector *Supplied only with connector-type motors

Bundled cable (Unipolar 42 mm sq. (1.65 inch sq.) motors only, model number: 4835710-1)

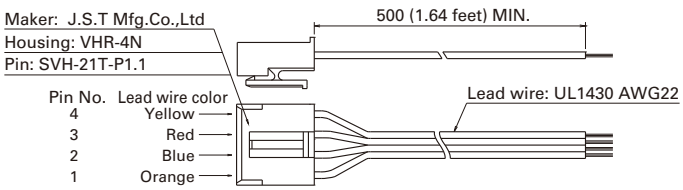


Bipolar Bundled driver model number : BS1D200P10

Motor size	Single shaft			Dual shaft			Basic step angle	Rated current (A/phase)	Page	
	Set model number	Set configuration items		Set model number	Set configuration items					
		Motor model number	Cable with motor connector model number		Motor model number	Cable with motor connector model number			Specifications	Dimensions
28 mm sq.	DB14S281S	SH2281-5771	—	DB14S281D	SH2281-5731	—	1.8°	1	P.14	P.69
	DB14S285S	SH2285-5771	—	DB14S285D	SH2285-5731	—	1.8°	1	P.14	P.69
42 mm sq.	DB14H521S	103H5205-5240	—	DB14H521D	103H5205-5210	—	1.8°	1	P.14	P.70
	DB14H522S	103H5208-5240	—	DB14H522D	103H5208-5210	—	1.8°	1	P.14	P.70
	DB14H524S	103H5210-5240	—	DB14H524D	103H5210-5210	—	1.8°	1	P.15	P.70
	DB16S141S	SH1421-5241	—	DB16S141D	SH1421-5211	—	0.9°	2	P.15	P.70
	DB16S142S	SH1422-5241	—	DB16S142D	SH1422-5211	—	0.9°	2	P.15	P.70
	DB16S144S	SH1424-5241	—	DB16S144D	SH1424-5211	—	0.9°	2	P.15	P.70
50 mm sq.	DB16H671S	103H6701-5040	—	DB16H671D	103H6701-5010	—	1.8°	2	P.16	P.70
	DB16H673S	103H6703-5040	—	DB16H673D	103H6703-5010	—	1.8°	2	P.16	P.70
56 mm sq.	DB16H711S	103H7121-5740	—	DB16H711D	103H7121-5710	—	1.8°	2	P.16	P.71
	DB16H713S	103H7123-5740	—	DB16H713D	103H7123-5710	—	1.8°	2	P.16	P.71
	DB16H716S	103H7126-5740	—	DB16H716D	103H7126-5710	—	1.8°	2	P.17	P.71
60 mm sq.	DB16H781S	103H7821-5740	4837961-1	DB16H781D	103H7821-5710	4837961-1	1.8°	2	P.17	P.72
	DB16H782S	103H7822-5740	4837961-1	DB16H782D	103H7822-5710	4837961-1	1.8°	2	P.17	P.72
	DB16H783S	103H7823-5740	4837961-1	DB16H783D	103H7823-5710	4837961-1	1.8°	2	P.17	P.72
	DB16S161S	SH1601-5240	—	DB16S161D	SH1601-5210	—	0.9°	2	P.18	P.71
	DB16S162S	SH1602-5240	—	DB16S162D	SH1602-5210	—	0.9°	2	P.18	P.71

● Cable with motor connector *Supplied only with connector-type motors

Bundled cable (Bipolar 60 mm sq. (2.36 inch sq.) motors only, model number: 4837961-1)



Unipolar DC input driver (Model No.: US1D200P10) + Motor

Size		28 mm sq. (1.10 in sq.) / Basic step angle 1.8°		42 mm sq. (1.65 in sq.) / Basic step angle 1.8°	
	Motor size				
	Motor length	32 mm (1.26 in)	51.5 mm (2.03 in)	33 mm (1.30 in)	39 mm (1.89 in)
Single shaft	Set model number	DU14S281S	DU14S285S	DU15H521S	DU15H522S
	Configuration item: motor number	SH2281-5271	SH2285-5271	103H5205-0440	103H5208-0440
Dual shaft	Set model number	DU14S281D	DU14S285D	DU15H521D	DU15H522D
	Configuration item: motor number	SH2281-5231	SH2285-5231	103H5205-0410	103H5208-0410
Holding torque	N · m (oz · in)	0.055 (7.79)	0.115 (16.28)	0.2 (28.32)	0.3 (42.48)
Rotor inertia	X 10^{-4}kg · m² (oz · in²)	0.01 (0.05)	0.022 (0.12)	0.036 (0.20)	0.056 (0.31)
Rated current	A/phase	1	1	1.2	1.2
Motor mass *1	kg (lbs)	0.11 (0.24)	0.2 (0.44)	0.23 (0.51)	0.29 (0.64)
Allowable thrust load	N (lbs)	3 (0.67)	3 (0.67)	10 (2.25)	10 (2.25)
Allowable radial load *2	N (lbs)	42 (9.44)	49 (11.02)	30 (6)	30 (6)

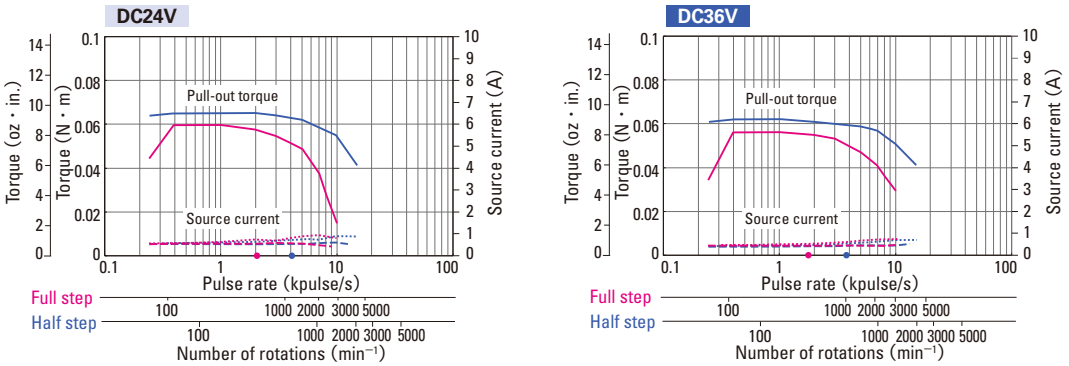
*1 Driver mass ▶ P.19
*2 When load is applied at 1/3 length from output shaft edge.

Characteristics diagram

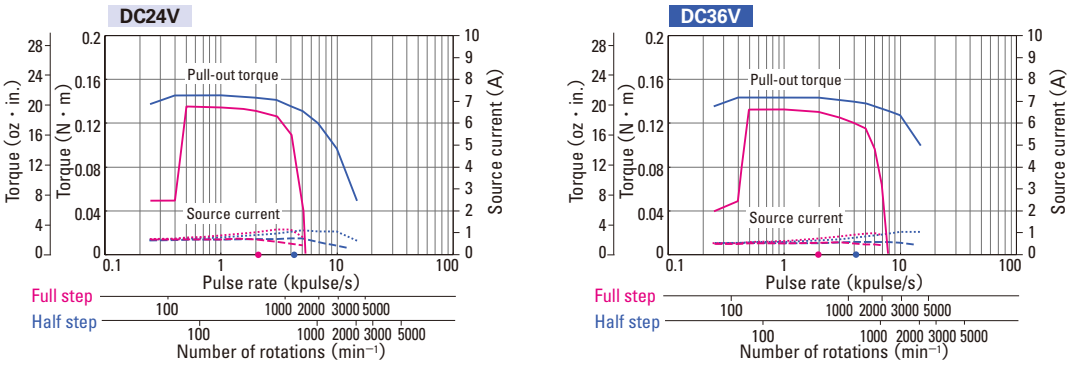
With rubber coupling

Pull-out torque Full step —— Half step —— fs : Maximum self-start frequency when not loaded Full step ● Half step ●
Source current (no load) Full step - - - Half step - - - Source current (load applied) Full step ····· Half step ·····

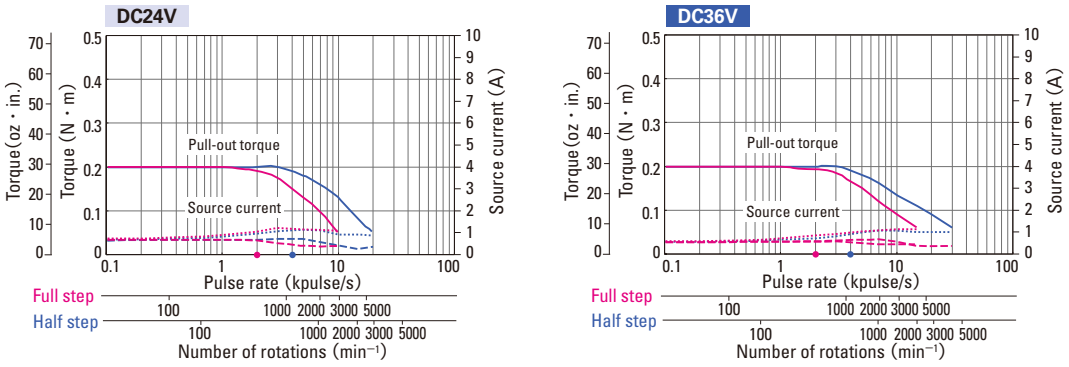
DU14S281S DU14S281D



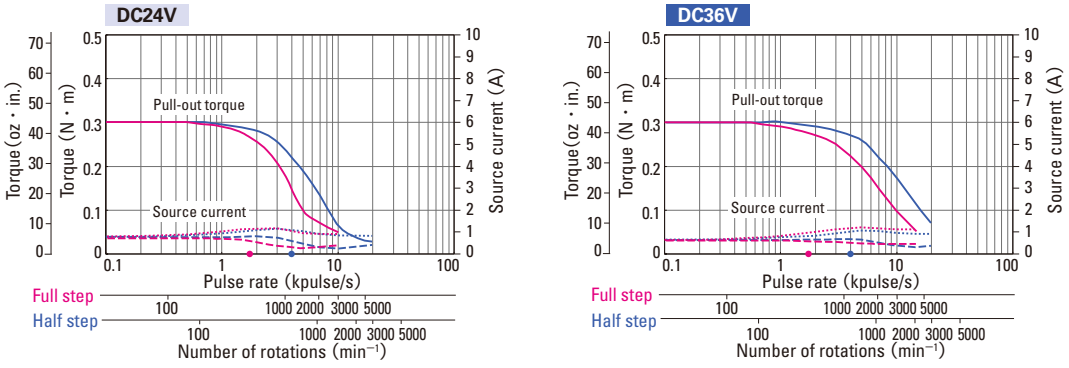
DU14S285S DU14S285D



DU15H521S DU15H521D



DU15H522S DU15H522D



System Configuration Diagram ▶ P.8 Set Model Configuration ▶ P.10 Motor Dimensions ▶ P.69 to 72 Driver Dimensions ▶ P.75
The data are measured under the trial conditions of SANYO DENKI. Driving torque may vary according to actual machine precision.

DC Input Set Models

Unipolar DC input driver (Model No.: US1D200P10) + Motor

Size		42 mm sq. (1.65 in sq.) / Basic step angle 1.8°	42 mm sq. (1.65 in sq.) / Basic step angle 0.9°		
	Motor length	48 mm (1.89 in)	33 mm (1.30 in)	39 mm (1.54 in)	48 mm (1.89 in)
Single shaft	Set model number	DU15H524S	DU15S141S	DU15S142S	DU15S144S
	Configuration item: motor number	103H5210-0440	SH1421-0441	SH1422-0441	SH1424-0441
Dual shaft	Set model number	DU15H524D	DU15S141D	DU15S142D	DU15S144D
	Configuration item: motor number	103H5210-0410	SH1421-0411	SH1422-0411	SH1424-0411
Holding torque	N · m (oz · in)	0.37 (52.39)	0.2 (28.32)	0.29 (41.07)	0.39 (55.23)
Rotor inertia	X 10^{-4}kg · m² (oz · in²)	0.074 (0.40)	0.044 (0.24)	0.066 (0.361)	0.089 (0.487)
Rated current	A/phase	1.2	1.2	1.2	1.2
Motor mass *1	kg (lbs)	0.37 (0.82)	0.24 (0.53)	0.29 (0.64)	0.38 (0.84)
Allowable thrust load	N (lbs)	10 (2.25)	10 (2.25)	10 (2.25)	10 (2.25)
Allowable radial load *2	N (lbs)	30 (6)	30 (6)	30 (6)	30 (6)

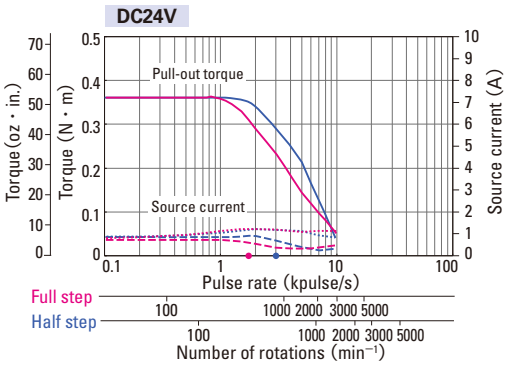
*1 Driver mass ▶ P.19
*2 When load is applied at 1/3 length from output shaft edge.

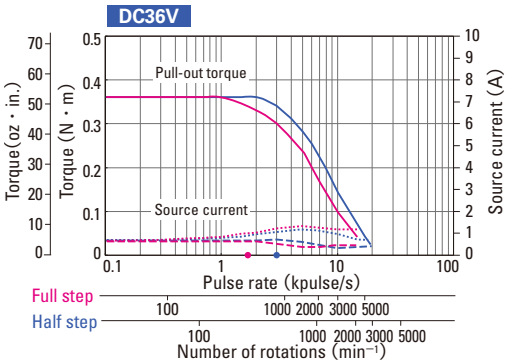
Characteristics diagram

With rubber coupling

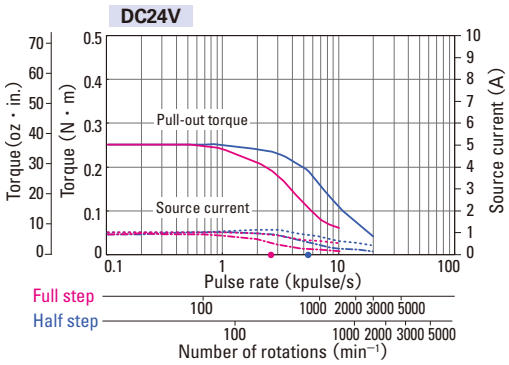
Pull-out torque Full step —— Half step —— fs : Maximum self-start frequency when not loaded Full step ● Half step ●
Source current (no load) Full step - - - Half step - - - Source current (load applied) Full step ····· Half step ·····

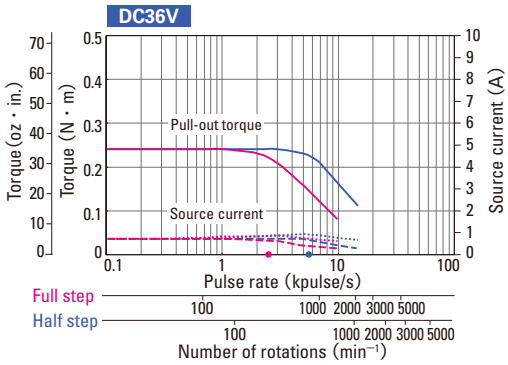
DU15H524S DU15H524D



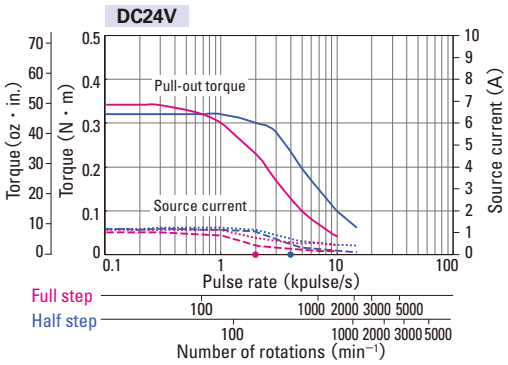


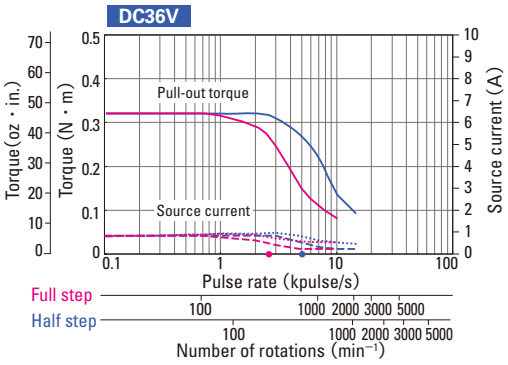
DU15S141S DU15S141D



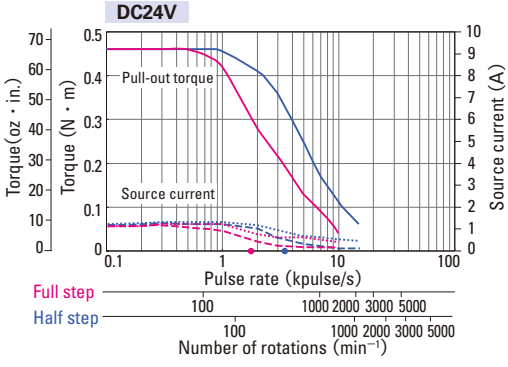


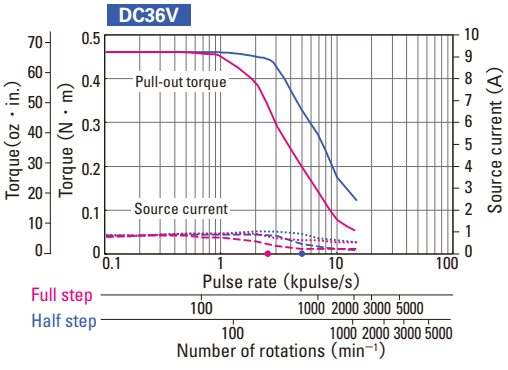
DU15S142S DU15S142D





DU15S144S DU15S144D





System Configuration Diagram ▶ P.8 Set Model Configuration ▶ P.10 Motor Dimensions ▶ P.69 to 72 Driver Dimensions ▶ P.75
The data are measured under the trial conditions of SANYO DENKI. Driving torque may vary according to actual machine precision.

Size	Motor size	56 mm sq. (2.20 in sq.) / Basic step angle 1.8°		
	Motor length	41.8 mm (1.65 in)	53.8 mm (2.12 in)	75.8 mm (2.98 in)
Single shaft	Set model number	DU16H711S	DU16H713S	DU16H716S
	Configuration item: motor number	103H7121-0440	103H7123-0440	103H7126-0440
Dual shaft	Set model number	DU16H711D	DU16H713D	DU16H716D
	Configuration item: motor number	103H7121-0410	103H7123-0410	103H7126-0410
Holding torque	N · m (oz · in)	0.39 (55.23)	0.83 (117.5)	1.27 (179.8)
Rotor inertia	X 10^{-4}kg · m² (oz · in²)	0.1 (0.55)	0.21 (1.15)	0.36 (1.97)
Rated current	A/phase	2	2	2
Motor mass *1	kg (lbs)	0.47 (1.04)	0.65 (1.43)	0.98 (2.16)
Allowable thrust load	N (lbs)	15 (3.37)	15 (3.37)	15 (3.37)
Allowable radial load *2	N (lbs)	71 (15)	71 (15)	71 (15)

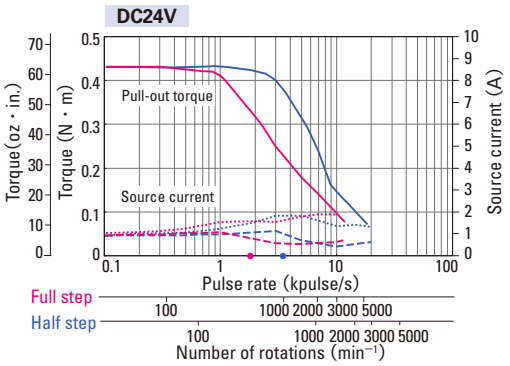
*1 Driver mass ▶ P.19
*2 When load is applied at 1/3 length from output shaft edge.

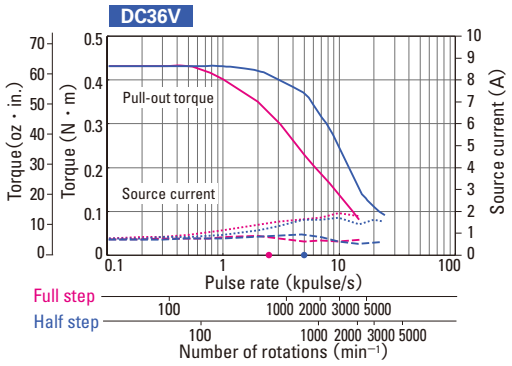
Characteristics diagram

With rubber coupling

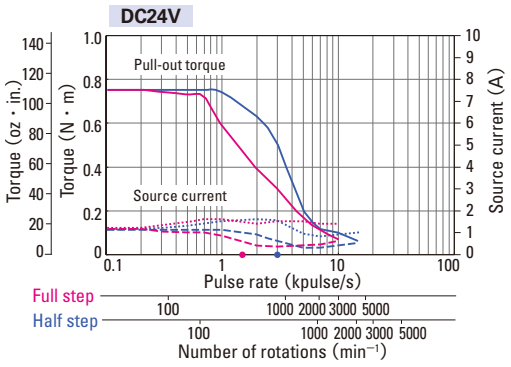
Pull-out torque Full step —— Half step —— fs : Maximum self-start frequency when not loaded Full step ● Half step ●
Source current (no load) Full step - - - Half step - - - Source current (load applied) Full step ····· Half step ·····

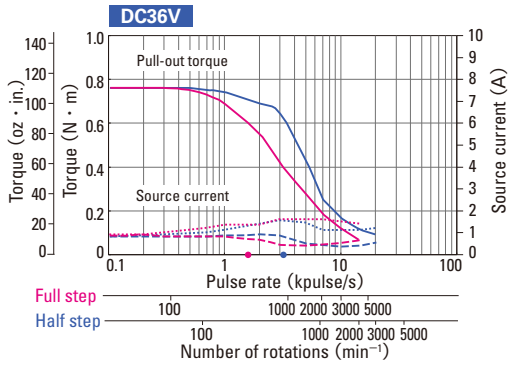
DU16H711S DU16H711D



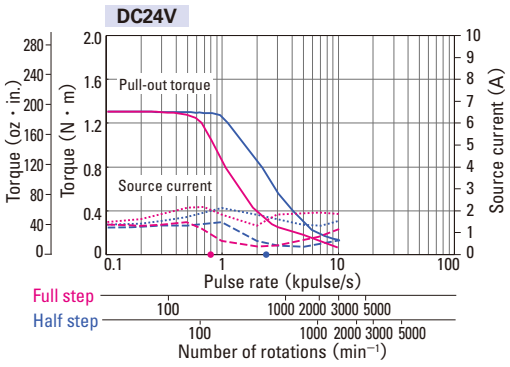


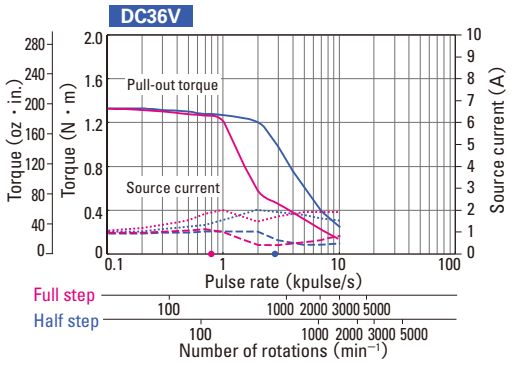
DU16H713S DU16H713D





DU16H716S DU16H716D





System Configuration Diagram ▶ P.8 Set Model Configuration ▶ P.10 Motor Dimensions ▶ P.69 to 72 Driver Dimensions ▶ P.75
The data are measured under the trial conditions of SANYO DENKI. Driving torque may vary according to actual machine precision.

DC Input Set Models

Bipolar DC input driver (Model No.: BS1D200P10) + Motor

Size			28 mm sq. (1.10 in sq.) / Basic step angle1.8°		42 mm sq. (1.65 in sq.) / Basic step angle1.8°	
	Motor size					
	Motor length		32 mm (1.26 in)	51.5 mm (2.03 in)	33 mm (1.30 in)	39 mm (1.54 in)
Single shaft	Set model number		DB14S281S	DB14S285S	DB14H521S	DB14H522S
	Configuration item: motor number		SH2281-5771	SH2285-5771	103H5205-5240	103H5208-5240
Dual shaft	Set model number		DB14S281D	DB14S285D	DB14H521D	DB14H522D
	Configuration item: motor number		SH2281-5731	SH2285-5731	103H5205-5210	103H5208-5210
Holding torque		N · m (oz · in)	0.07 (9.91)	0.145 (20.53)	0.265 (37.53)	0.39 (55.23)
Rotor inertia		X 10^{-4}kg · m² (oz · in²)	0.01 (0.05)	0.022 (0.12)	0.036 (0.20)	0.056 (0.31)
Rated current		A/phase	1	1	1	1
Motor mass *1		kg (lbs)	0.11 (0.24)	0.2 (0.44)	0.23 (0.51)	0.29 (0.64)
Allowable thrust load		N (lbs)	3 (0.67)	3 (0.67)	10 (2.25)	10 (2.25)
Allowable radial load *2		N (lbs)	42 (9.44)	49 (9.44)	30 (6)	30 (6)

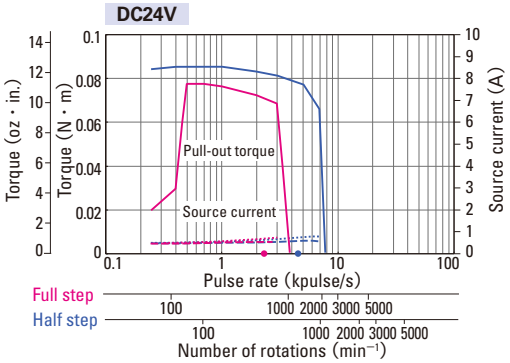
*1 Driver mass ▶ P.19
*2 When load is applied at 1/3 length from output shaft edge.

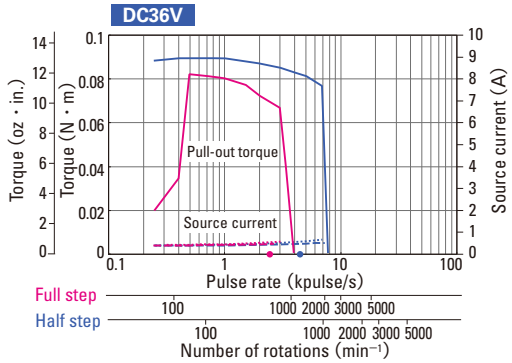
Characteristics diagram

With rubber coupling

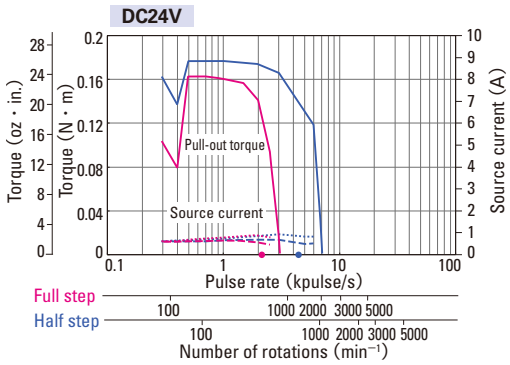
Pull-out torque Full step —— Half step —— fs : Maximum self-start frequency when not loaded Full step ● Half step ●
Source current (no load) Full step - - - Half step - - - Source current (load applied) Full step ····· Half step ·····

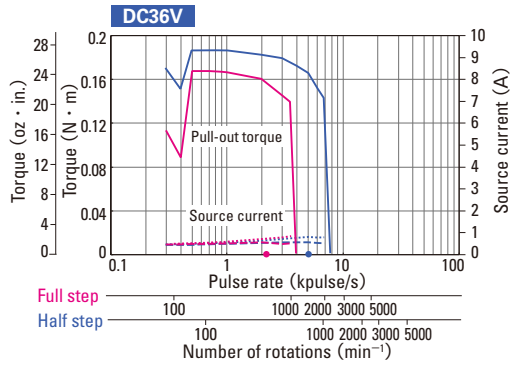
DB14S281S DB14S281D



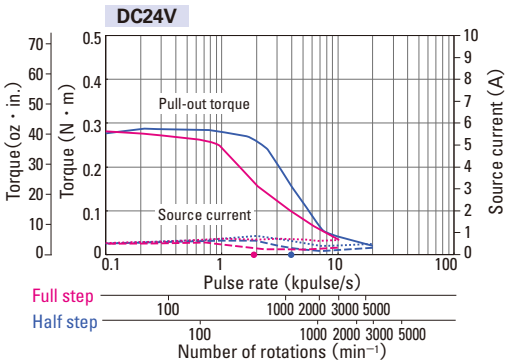


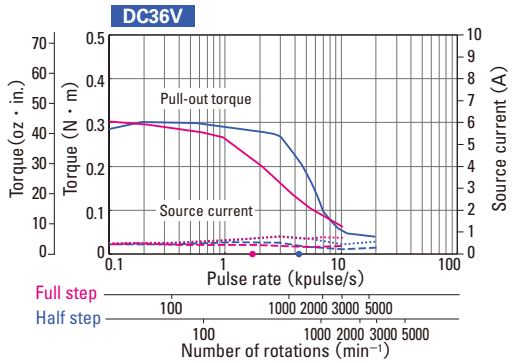
DB14S285S DB14S285D



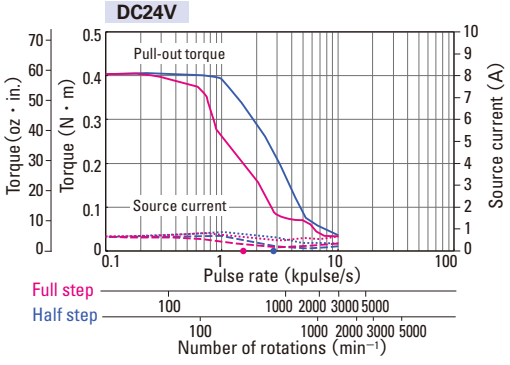


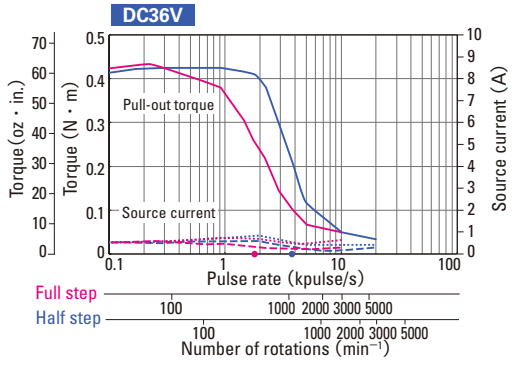
DB14H521S DB14H521D





DB14H522S DB14H522D





System Configuration Diagram ▶ P.8 Set Model Configuration ▶ P.10 Motor Dimensions ▶ P.69 to 72 Driver Dimensions ▶ P.75
The data are measured under the trial conditions of SANYO DENKI. Driving torque may vary according to actual machine precision.

Size	Motor size	42 mm sq. (1.65 in sq.) / Basic step angle1.8°	42 mm sq. (1.65 in sq.) / Basic step angle 0.9°		
	Motor length	48 mm (1.89 in)	33 mm (1.30 in)	39 mm (1.54 in)	48 mm (1.89 in)
Single shaft	Set model number	DB14H524S	DB16S141S	DB16S142S	DB16S144S
	Configuration item: motor number	103H5210-5240	SH1421-5241	SH1422-5241	SH1424-5241
Dual shaft	Set model number	DB14H524D	DB16S141D	DB16S142D	DB16S144D
	Configuration item: motor number	103H5210-5210	SH1421-5211	SH1422-5211	SH1424-5211
Holding torque	N · m (oz · in)	0.51 (72.22)	0.23 (32.57)	0.34 (48.15)	0.48 (67.97)
Rotor inertia	X 10^{-4}kg · m² (oz · in²)	0.074 (0.40)	0.044 (0.24)	0.066 (0.361)	0.089 (0.487)
Rated current	A/phase	1	2	2	2
Motor mass *1	kg (lbs)	0.37 (0.82)	0.24 (0.53)	0.29 (0.64)	0.38 (0.84)
Allowable thrust load	N (lbs)	10 (2.25)	10 (2.25)	10 (2.25)	10 (2.25)
Allowable radial load *2	N (lbs)	30 (6)	30 (6)	30 (6)	30 (6)

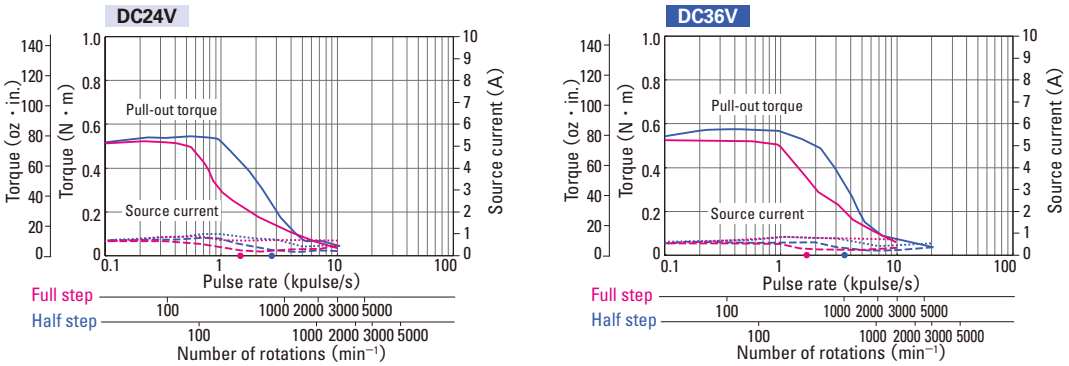
*1 Driver mass ▶ P.19
*2 When load is applied at 1/3 length from output shaft edge.

Characteristics diagram

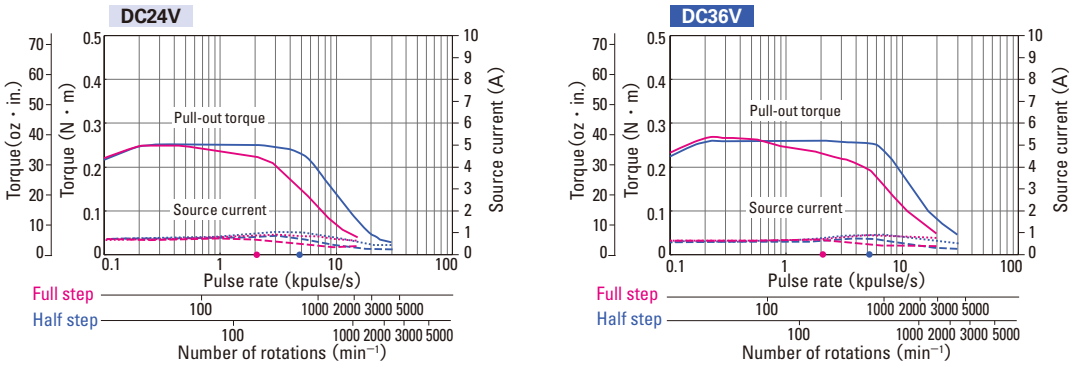
With rubber coupling

Pull-out torque Full step —— Half step —— fs : Maximum self-start frequency when not loaded Full step ● Half step ●
Source current (no load) Full step - - - Half step - - - Source current (load applied) Full step ····· Half step ·····

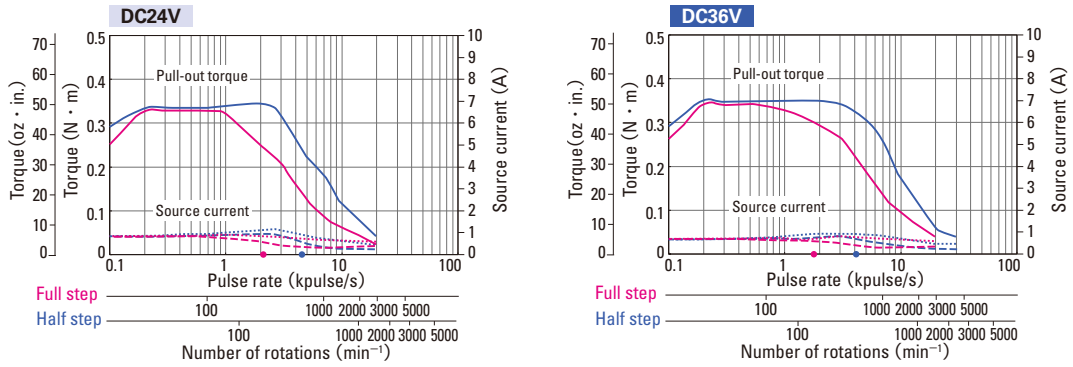
DB14H524S DB14H524D



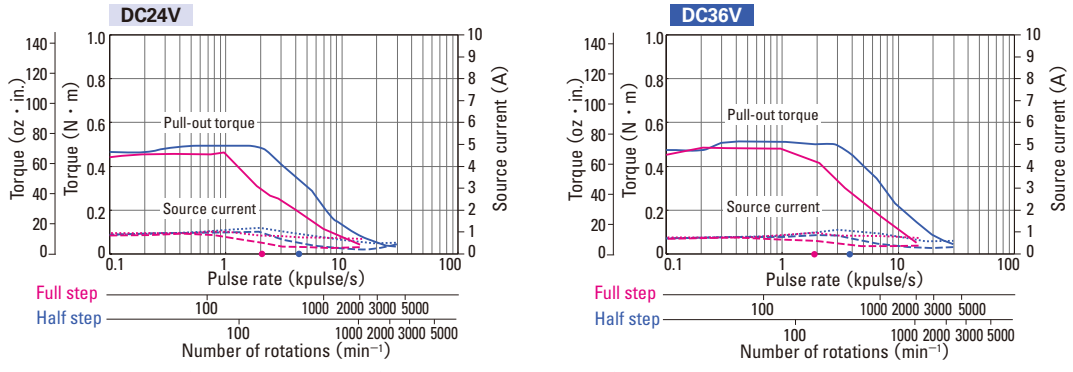
DB16S141S DB16S141D



DB16S142S DB16S142D



DB16S144S DB16S144D



System Configuration Diagram ▶ P.8 Set Model Configuration ▶ P.10 Motor Dimensions ▶ P.69 to 72 Driver Dimensions ▶ P.75
The data are measured under the trial conditions of SANYO DENKI. Driving torque may vary according to actual machine precision.

DC Input Set Models

Bipolar DC input driver (Model No.: BS1D200P10) + Motor

Size			50 mm sq. (1.97 in sq.) / Basic step angle 1.8°		56 mm sq. (2.20 in sq.) / Basic step angle 1.8°	
	Motor size					
	Motor length		39.8 mm (1.57 in)	51.3 mm (2.02 in)	41.8 mm (1.65 in)	53.8 mm (2.12 in)
Single shaft	Set model number		DB16H671S	DB16H673S	DB16H711S	DB16H713S
	Configuration item: motor number		103H6701-5040	103H6703-5040	103H7121-5740	103H7123-5740
Dual shaft	Set model number		DB16H671D	DB16H673D	DB16H711D	DB16H713D
	Configuration item: motor number		103H6701-5010	103H6703-5010	103H7121-5710	103H7123-5710
Holding torque		N · m (oz · in)	0.28 (39.6)	0.49 (69.4)	0.55 (77.9)	1.0 (141.6)
Rotor inertia		X 10^{-4}kg · m² (oz · in²)	0.057 (0.31)	0.118 (0.65)	0.1 (0.55)	0.21 (1.15)
Rated current		A/phase	2	2	2	2
Motor mass *1		kg (lbs)	0.35 (0.77)	0.5 (1.10)	0.47 (1.04)	0.65 (1.43)
Allowable thrust load		N (lbs)	15 (3.37)	15 (3.37)	15 (3.37)	15 (3.37)
Allowable radial load *2		N (lbs)	99 (22)	99 (22)	71 (15)	71 (15)

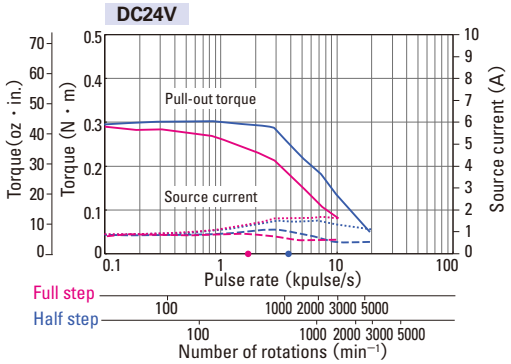
*1 Driver mass ▶ P.19
*2 When load is applied at 1/3 length from output shaft edge.

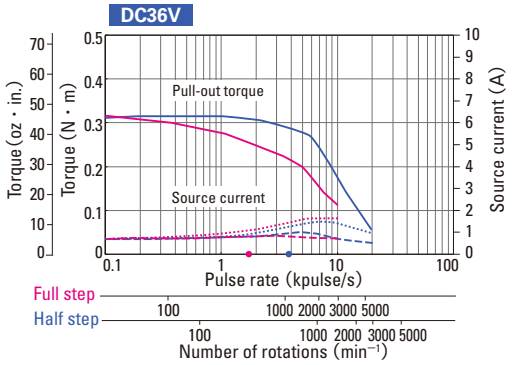
Characteristics diagram

With rubber coupling

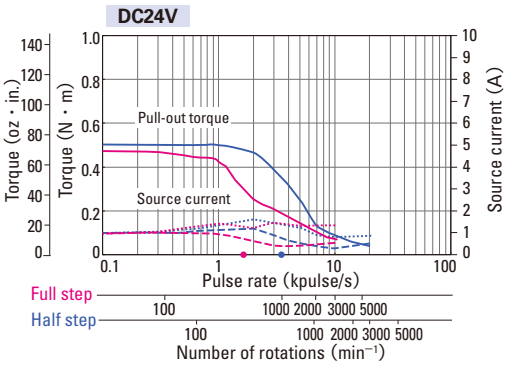
Pull-out torque Full step —— Half step ——
Source current (no load) Full step - - - Half step - - -
fs : Maximum self-start frequency when not loaded Full step ● Half step ●
Source current (load applied) Full step ····· Half step ·····

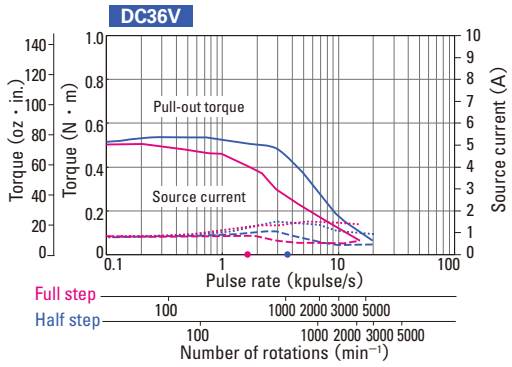
DB16H671S DB16H671D



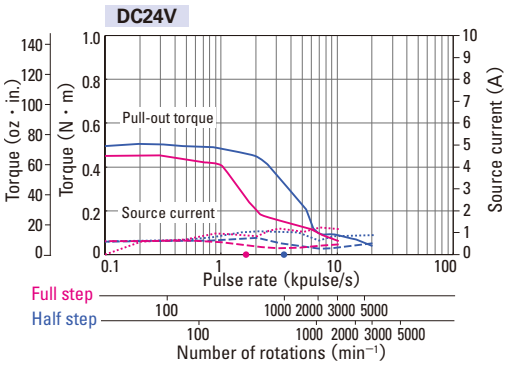


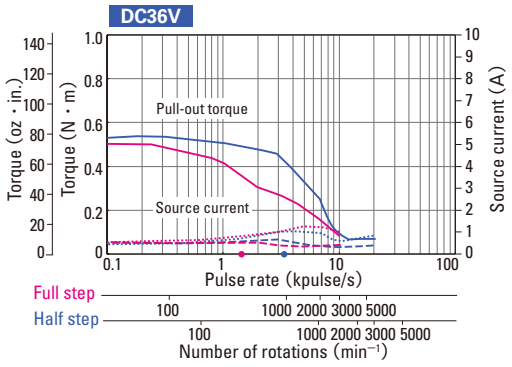
DB16H673S DB16H673D



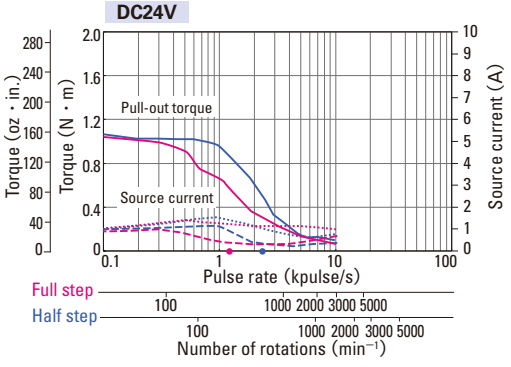


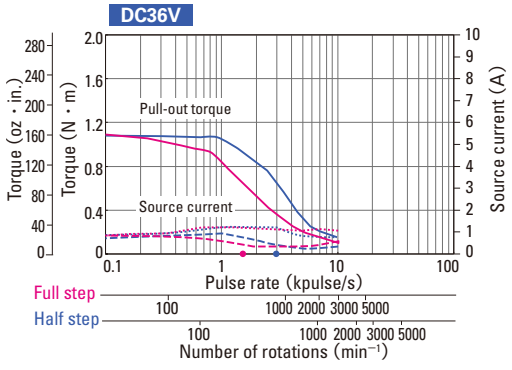
DB16H711S DB16H711D





DB16H713S DB16H713D





System Configuration Diagram ▶ P.8 Set Model Configuration ▶ P.10 Motor Dimensions ▶ P.69 to 72 Driver Dimensions ▶ P.75
The data are measured under the trial conditions of SANYO DENKI. Driving torque may vary according to actual machine precision.

Size		56 mm sq. (2.20 in sq.) / Basic step angle 1.8°	60 mm sq. (2.36 in sq.) / Basic step angle 1.8°		
	Motor length	75.8 mm (2.98 in)	44.8 mm (1.76 in)	53.8 mm (2.12 in)	85.8 mm (3.38 in)
Single shaft	Set model number	DB16H716S	DB16H781S	DB16H782S	DB16H783S
	Configuration item: motor number	103H7126-5740	103H7821-5740	103H7822-5740	103H7823-5740
Dual shaft	Set model number	DB16H716D	DB16H781D	DB16H782D	DB16H783D
	Configuration item: motor number	103H7126-5710	103H7821-5710	103H7822-5710	103H7823-5710
Holding torque	N · m (oz · in)	1.6 (226.6)	0.88 (124.6)	1.37 (194.0)	2.7 (382.3)
Rotor inertia	X 10^{-4}kg · m² (oz · in²)	0.36 (1.97)	0.275 (1.50)	0.4 (2.19)	0.84 (4.59)
Rated current	A/phase	2	2	2	2
Motor mass *1	kg (lbs)	0.98 (2.16)	0.6 (1.32)	0.77 (1.70)	1.34 (2.95)
Allowable thrust load	N (lbs)	15 (3.37)	15 (3.37)	15 (3.37)	15 (3.37)
Allowable radial load *2	N (lbs)	71 (15)	95 (21)	95 (21)	95 (21)

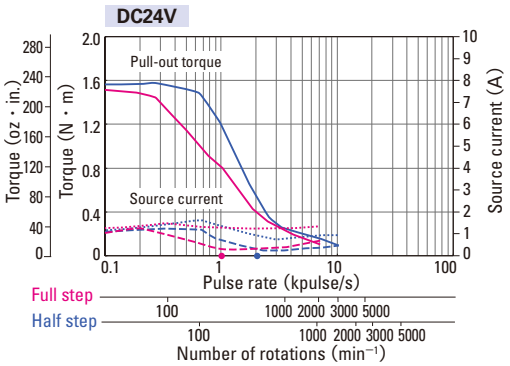
*1 Driver mass ▶ P.19
*2 When load is applied at 1/3 length from output shaft edge.

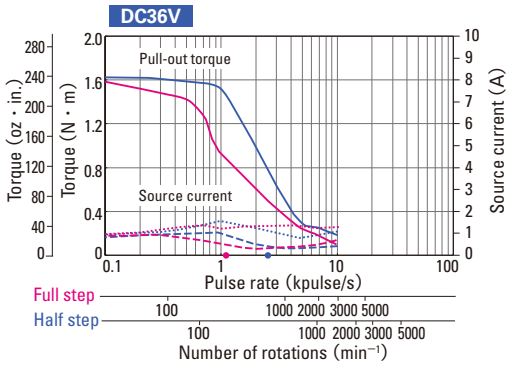
Characteristics diagram

With rubber coupling

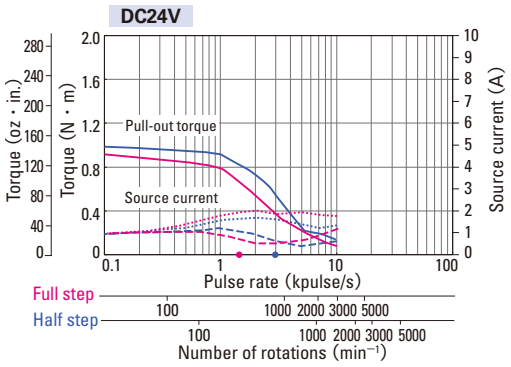
Pull-out torque Full step —— Half step —— fs : Maximum self-start frequency when not loaded Full step ● Half step ●
Source current (no load) Full step - - - Half step - - - Source current (load applied) Full step ····· Half step ·····

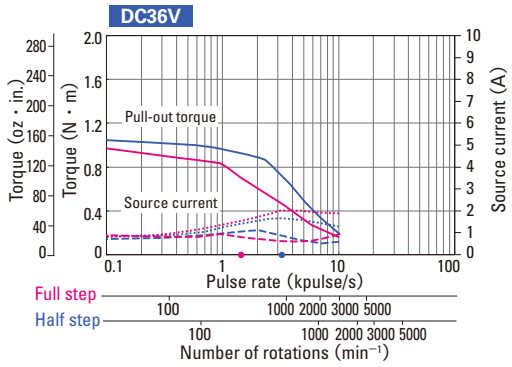
DB16H716S DB16H716D



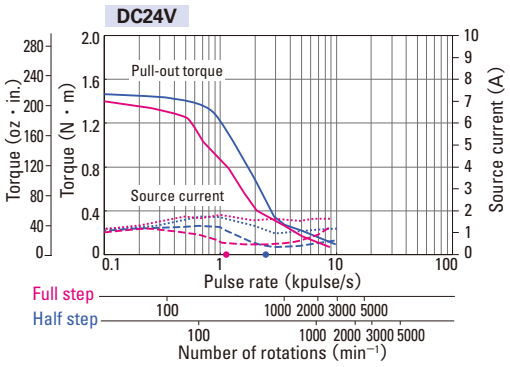


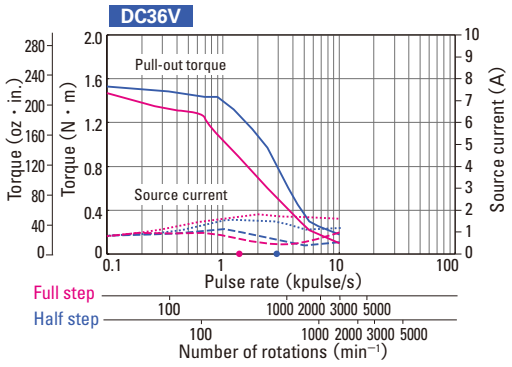
DB16H781S DB16H781D



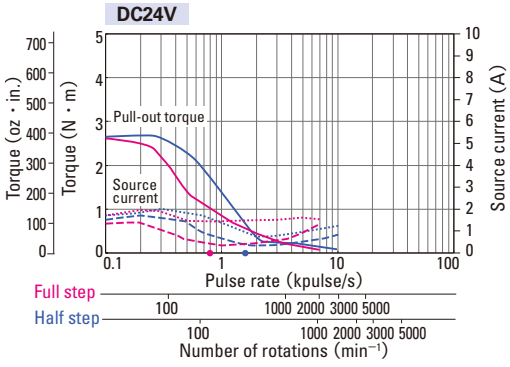


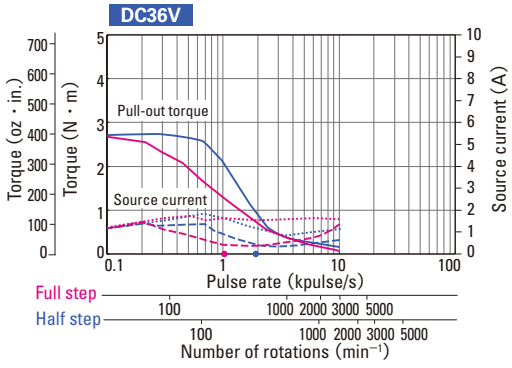
DB16H782S DB16H782D





DB16H783S DB16H783D





System Configuration Diagram ▶ P.8 Set Model Configuration ▶ P.10 Motor Dimensions ▶ P.69 to 72 Driver Dimensions ▶ P.75
The data are measured under the trial conditions of SANYO DENKI. Driving torque may vary according to actual machine precision.

Bipolar DC input driver (Model No.: BS1D200P10) + Motor

Size		60 mm sq. (2.36 in sq.) / Basic step angle 0.9°	
	Motor length	42 mm (16.54 in)	54 mm (21.26 in)
Single shaft	**Set model number**	**DB16S161S**	**DB16S162S**
	Configuration item: motor number	SH1601-5240	SH1602-5240
Dual shaft	**Set model number**	**DB16S161D**	**DB16S162D**
	Configuration item: motor number	SH1601-5210	SH1602-5210
Holding torque	N · m (oz · in)	0.69 (97.71)	1.28 (181.26)
Rotor inertia	X 10^{-4}kg · m² (oz · in²)	0.24 (1.312)	0.4 (2.187)
Rated current	A/phase	2	2
Motor mass *1	kg (lbs)	0.55 (1.21)	0.8 (1.76)
Allowable thrust load	N (lbs)	15 (3.37)	15 (3.37)
Allowable radial load *2	N (lbs)	79 (18)	79 (18)

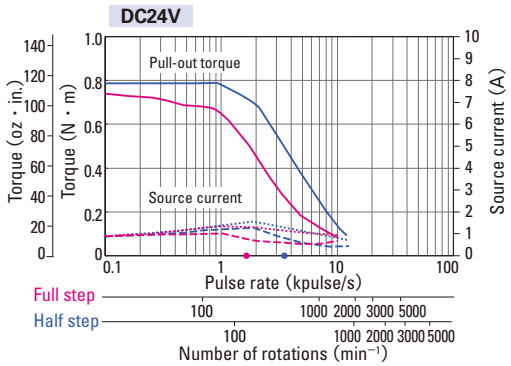
*1 Driver mass ▶ P.19
*2 When load is applied at 1/3 length from output shaft edge.

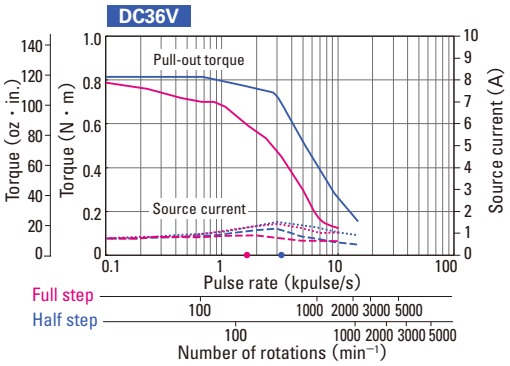
Characteristics diagram

With rubber coupling

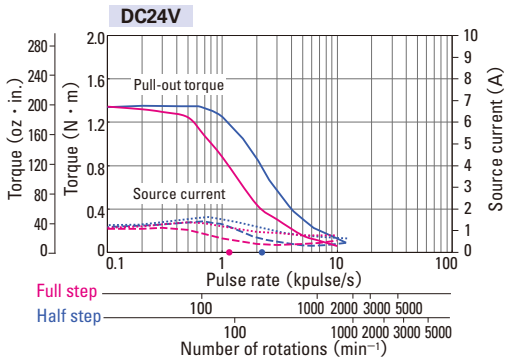
Pull-out torque Full step —— Half step —— fs : Maximum self-start frequency when not loaded Full step ● Half step ●
Source current (no load) Full step - - - Half step - - - Source current (load applied) Full step ····· Half step ·····

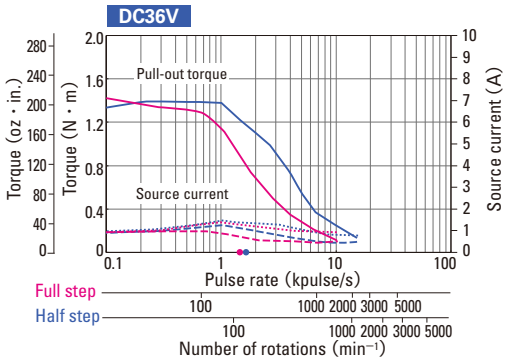
DB16S161S DB16S161D





DB16S162S DB16S162D





System Configuration Diagram ▶ P.8 Set Model Configuration ▶ P.10 Motor Dimensions ▶ P.69 to 72 Driver Dimensions ▶ P.75
The data are measured under the trial conditions of SANYO DENKI. Driving torque may vary according to actual machine precision.

Driver specifications Motor Specifications ▶ P.57

General Specifications

			Unipolar	Bipolar
Basic specifications	Model number		**US1D200P10**	**BS1D200P10**
	Input source		DC24 V/36 V ± 10 %	
	Source current		3 A	
	Environment	Protection class	Class Ⅲ	
		Operation environment	Installation category（over-voltage category）: Ⅰ, pollution degree : 2	
		Ambient operation temperature	0 to ＋50℃	
		Conservation temperature	－ 20 to ＋70℃	
		Operating ambient humidity	35 to 85% RH（no condensation）	
		Conservation humidity	10 to 90% RH（no condensation）	
		Operation altitude	1000 m（3281 feet）or less above sea level	
		Vibration resistance	Tested under the following conditions: 5 m/s² frequency range 10 to 55Hz, direction along X, Y and Z axes, for 2 hours each	
		Impact resistance	Not influenced at NDS-C-0110 standard section 3.2.2 division “C”.	
		Withstand voltage	Not influenced when 0.5 kV AC is applied between power input terminal and cabinet for one minute.	
		Insulation resistance	10 MΩ MIN. when measured with 500V DC megohmmeter between input terminal and cabinet.	
	Mass（Weight）		0.09 kg（0.20 lbs）	
Functions	Selection functions		Step angle, Pulse input mode, Low vibration mode, Step current, Operating current, Original excitation phase	
	Protection functions		Open phase protection, Main circuit power source voltage decrease	
	LED indication		Power monitor, alarm display	
I/O signals	Command pulse input signal		Photocoupler input system, input resistance : 220 Ω input-signal “H” level : 4.0 to 5.5 V, input-signal “L” level : 0 to 0.5 V Maximum input frequency : 150 kpulse/s	
	Poweer down input signal		Photocoupler input system, input resistance : 220 Ω input-signal “H” level : 4.0 to 5.5V, input-signal “L” level : 0 to 0.5 V	
	Phase origin monitor output signal		From the photocoupler by the open collector output Output specification : Vceo = 40 V MAX., Ic = 10 mA MAX.	
	Rotation monitor output signal		From the photocoupler by the open collector output Output specification : Vceo = 40 V MAX., Ic = 10 mA MAX.	

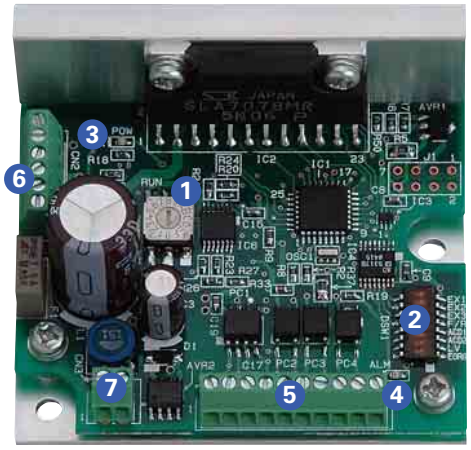
Safety standards

	Directives	Category	Standard cord	Name
CE（TÜV）	Low-voltage directives	－	EN61010-1	－
	EMC directives	Emission	EN55011-A	Terminal disturbance voltage
			EN55011-A	Electromagnetic radiation disturbance
		Immunity	EN61000-4-2	ESD（Electrostatic discharge）
			EN61000-4-3	RS（Radio-frequency amplitude modulated electromagnetic field）
			EN61000-4-4	Fast transients / burst
			EN61000-4-6	Conducted disturbances
UL	Acquired standards		Standard part	File No.
	UL		UL508C	E179775
	UL for Canada			

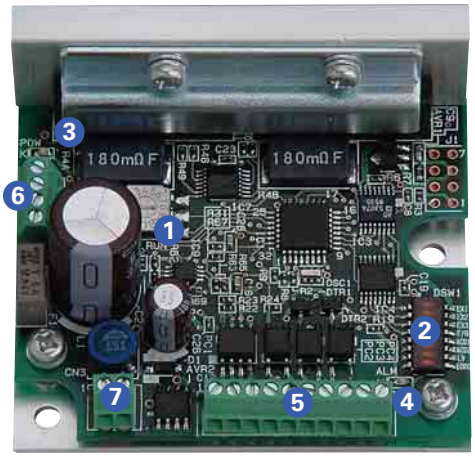
・EMC characteristics may vary depending on the configuration of the users' control panel, which contains the driver or stepping motor, or the arrangement and wiring of other electrical devices.
Parts for EMC noise suppression like noise filters and toroidal type ferrite cores may be required depending on circumstances.
・Validation test of driver has been performed for low-voltage EMC directives at TÜV (TÜV product service) for self-declaration of CE marking.

Driver Controls and Connectors

Unipolar



Bipolar



1 Operating current selection switch (RUN)

The value of the motor current can be set when operating.

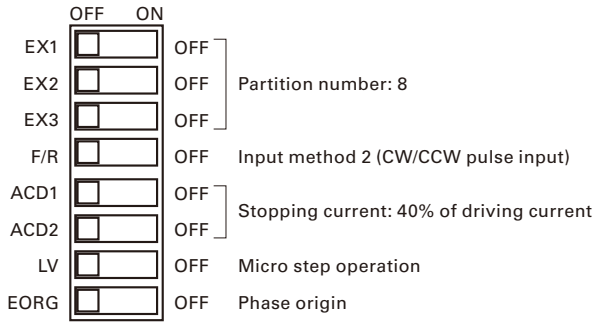
Dial	0	1	2	3	4	5	6	7
Stepping motor current (A)	2.0	1.9	1.8	1.7	1.6	1.5	1.4	1.3
Dial	8	9	A	B	C	D	E	F
Stepping motor current (A)	1.2	1.1	1.0	0.9	0.8	0.7	0.6	0.5

- The factory setting is F (0.5A).
  Select the current after checking the rated current of the combination motor.

2 Function selection DIP switchpack

Select the function depending on your specification.

Factory settings



1, Step angle select (EX1, EX2, EX3)

Select the partition number of the basic step angle.

EX1	EX2	EX3	Partition number
ON	ON	ON	1-division
OFF	ON	OFF	2-division
ON	OFF	OFF	4-division
OFF	OFF	OFF	8-division
OFF	OFF	ON	16-division

2, Input method select (F/R)

Select input pulse type.

F/R	Input pulse type
ON	1 input (CK, U/D)
OFF	2 input (CW, CCW)

3, Current selection when stopping (ACD1, ACD2)

Select the current value of the motor when stopping.

ACD2	ACD1	Current value of the motor
ON	ON	100% of driving current
ON	OFF	60% of driving current
OFF	ON	50% of driving current
OFF	OFF	40% of driving current

- Initial configuration of factory shipment is set to 40% of rated value. Driver and motor should be operated at around 50% of rated value to reduce heat.

4, Low-vibration mode select (LV)

Provides low-vibration, smooth operation even if resolution is coarse (1-division, 2-division, etc).

LV	Operation
ON	Auto-micro function
OFF	Micro-step

5, Excitation select (EORG)

The excitation phase when the power supply is engaged is selected.

EORG	Original excitation phase
ON	Excitation phase at power shut off
OFF	Phase origin

- By turning on the EORG, excitation phase when power OFF will be saved. Therefore, there will be no shaft displacement when turning the power ON.

3 LED for power supply monitor (POW)

Lit up when the main circuit power supply is connected.

4 LED for alarm display (ALM)

Lights in the following conditions:

- Motor cable is broken.
- Switching element in driver is faulty.
- The main circuit voltage is out of specifications range (DC19V MAX.).

When "ALM" is displayed, the winding current of the stepping motor is cut off and it is in a "non-excitation" state. At the same time, an output signal (photocoupler ON) is transmitted from the alarm output terminal (AL) to an external source. When the alarm circuit is operating, this state is maintained until it is reset by switching on the power supply again. When an alarm condition has occurred, please take corrective actions to rectify the cause of the alarm before switching on the power supply again.

5 I/O signal terminal block (CN1)

Connect the I/O signal.

6 Motor terminal block (CN2)

Connect the motor's power line.

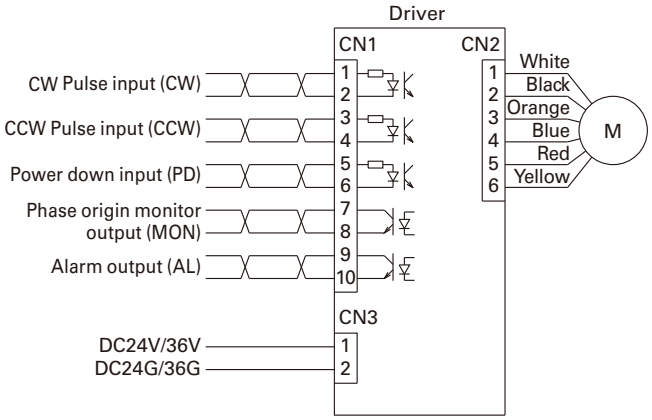
7 Power supply terminal block (CN3)

Connect the main circuit power supply.

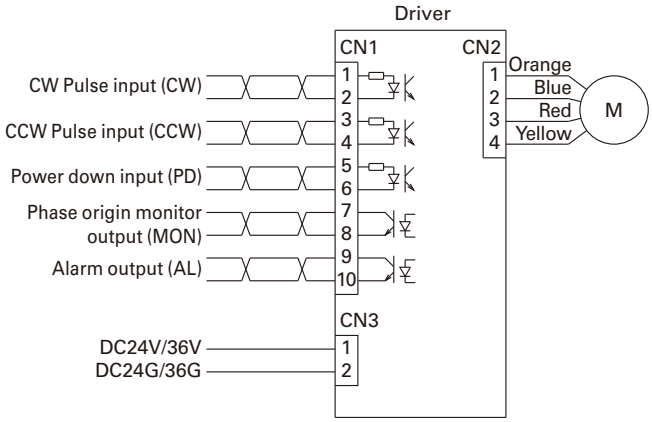
Connections and Signals

External wiring diagram

Unipolar



Bipolar



Applicable wire sizes

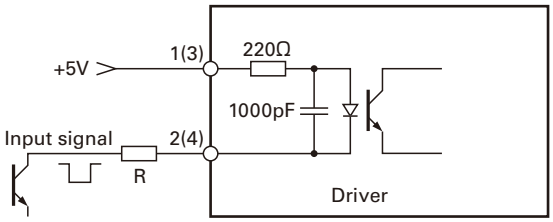
Part	Wire Sizes	Allowable wire length
For power supply	AWG22 (0.3 mm²)	2 m MAX.
For input/output signal	AWG24 (0.2 mm²) to AWG22 (0.3 mm²)	2 m MAX.
For motor	AWG22 (0.3 mm²)	Under 3 m

Specification summary of input/output signals

Signal	CN1 Pin Number	Function summary
CW pulse input (CW) (Standard)	1 2	When "2 input mode", Input drive pulse rotating CW direction.
Pulse train input (CK)	1 2	When "1 input mode", Input drive pulse train for motor rotation.
CCW pulse input (CCW) (Standard)	3 4	When "2 input mode", Input drive pulse rotating CCW direction.
Rotational direction input (U/D)	3 4	When "1 input mode", Input motor rotational direction signal. Internal photocoupler ON ··· CW direction Internal photocoupler OFF ··· CCW direction
Power down input (PD)	5 6	Inputting PD signal will cut off (power off) the current flowing to the motor (With dip switch select, change to the Power low function is possible). PD input signal on (internal photocoupler on) ··· PD function is valid. PD input signal off (internal photocoupler off) ··· PD function is invalid.
Phase origin monitor output (MON)	7 8	When the excitation phase is at the origin (in power on) it turns on. When FULL step, ON once for 4 pulses, when HALF step, ON once for 8 pulses.
Alarm output (AL)	9 10	When alarm circuits actuated inside the driver, outputs signals to outside. Then the stepping motor becomes unexcited status.

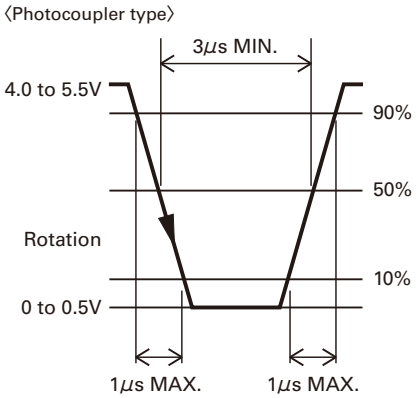
※ As for the Motor rotational direction, CW direction is regarded as the clockwise revolution, and CCW direction is regarded as the counterclockwise revolution by viewing the motor from output shaft side.

Circuit Configuration of Pulse Input CW (CK), CCW (U/D)



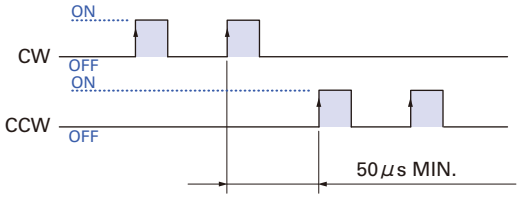
- Pulse duty 50% MAX.
- Maximum input frequency:150kpulse/s
- When the crest value of the input signal exceeds 5V, use the external limit resistance R to limit the input current to approximately 15mA.

Input signal specifications



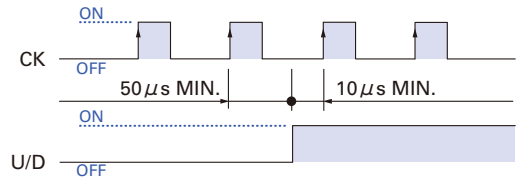
Timing of the command pulse

2 input mode (CW, CCW)



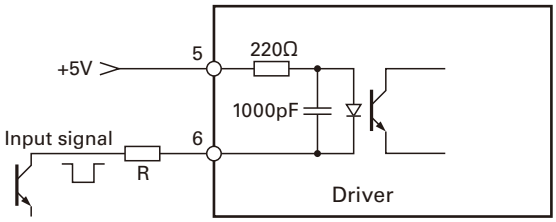
- Shaded area indicates internal photocoupler "ON". Internal circuit (motor) starts operating at leading edge of the photocoupler "ON".
- To apply pulse to CW, set CCW side internal photocoupler to "OFF".
- To apply pulse to CCW, set CW side internal photocoupler to "OFF".

1 input mode (CK, U/D)



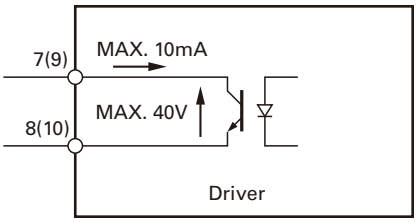
- Shaded area indicates internal photocoupler "ON". Internal circuit (motor) starts operating at leading edge of CK side photocoupler "ON".
- Switching of U/D input signal must be done while CK side internal photocoupler is "OFF".

Input Circuit Configuration of Power Down Input (PD)

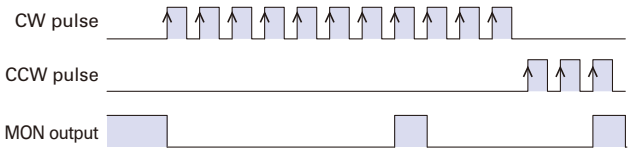


- When the crest value of the input signal exceeds 5V, use the external limit resistance R to limit the input current to approximately 15mA.

Output Signal Configuration of Phase Origin Monitor Output (MON) and Alarm Output (AL)



MON output



- Photocoupler is set to "ON" at phase origin of motor excitation. (setting when number of divisions is 2)
- MON output is taken at every 7.2 degrees of motor output shaft from phase origin.

Stepping Motors

Allowable Load · Internal Wiring · Rotation Direction ▶ P.56
General Specifications ▶ P.57
Motor Dimensions ▶ P.69 to 74

14 mm sq. (0.55 inch sq.)

1.8˚ /step

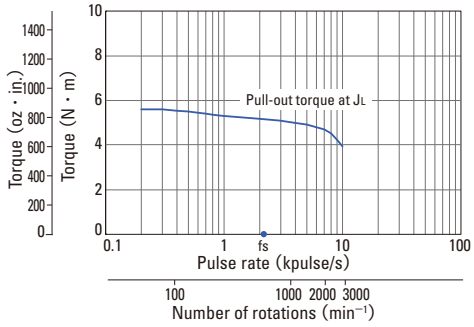
Bipolar winding · Lead wire type

Bipolar winding • Lead wire type

Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
SH2141-5541	**SH2141-5511**	0.0065 (0.92)	0.3	21	4.2	0.00058 (0.0032)	0.028 (0.062)

Characteristics diagram

SH2141-5541
SH2141-5511



Constant current circuit
Source voltage : DC24V · Operating current : 0.3A/phase,
2-phase energization (full-step)
J_L=[0.01 × 10⁻⁴kg · m² (1.80 oz · in²) pulley balancer method]
fs: Maximum self-start frequency when not loaded

28 mm sq. (1.10 inch sq.)

1.8˚ /step

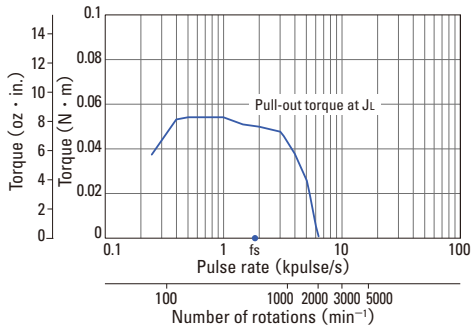
Unipolar winding · Lead wire type
Bipolar winding · Lead wire type ▶ P.26

Unipolar winding • Lead wire type

Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
SH2281-5171	**SH2281-5131**	0.055 (7.79)	0.5	10.5	3.7	0.01 (0.05)	0.11 (0.24)
SH2281-5271	**SH2281-5231**	0.055 (7.79)	1	2.85	1	0.01 (0.05)	0.11 (0.24)
SH2285-5171	**SH2285-5131**	0.115 (16.28)	0.5	17	7	0.022 (0.12)	0.2 (0.44)
SH2285-5271	**SH2285-5231**	0.115 (16.28)	1	4.1	1.9	0.022 (0.12)	0.2 (0.44)

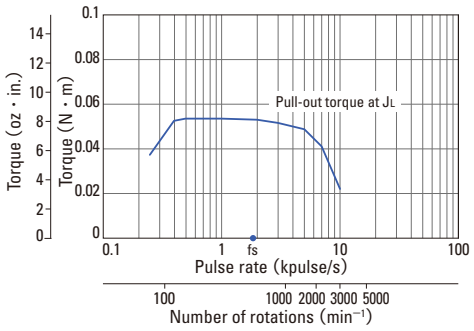
Characteristics diagram

SH2281-5171
SH2281-5131



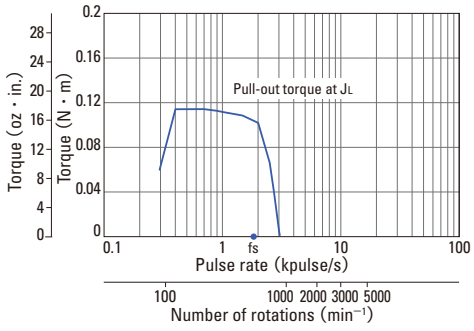
Constant current circuit
Source voltage : DC24V · Operating current : 0.5A/phase, 2-phase energization (full-step)
J_L=[0.01 × 10⁻⁴kg · m² (1.80 oz · in²) pulley balancer method]
fs: Maximum self-start frequency when not loaded

SH2281-5271
SH2281-5231



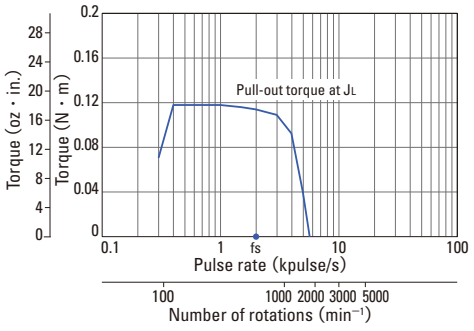
Constant current circuit
Source voltage : DC24V · Operating current : 1A/phase, 2-phase energization (full-step)
J_L=[0.01 × 10⁻⁴kg · m² (1.80 oz · in²) pulley balancer method]
fs: Maximum self-start frequency when not loaded

SH2285-5171
SH2285-5131



Constant current circuit
Source voltage : DC24V · Operating current : 0.5A/phase, 2-phase energization (full-step)
J_L=[0.01 × 10⁻⁴kg · m² (1.80 oz · in²) pulley balancer method]
fs: Maximum self-start frequency when not loaded

SH2285-5271
SH2285-5231



Constant current circuit
Source voltage : DC24V · Operating current : 1A/phase, 2-phase energization (full-step)
J_L=[0.01 × 10⁻⁴kg · m² (1.80 oz · in²) pulley balancer method]
fs: Maximum self-start frequency when not loaded

28 mm sq. (1.10 inch sq.)

1.8˚ /step

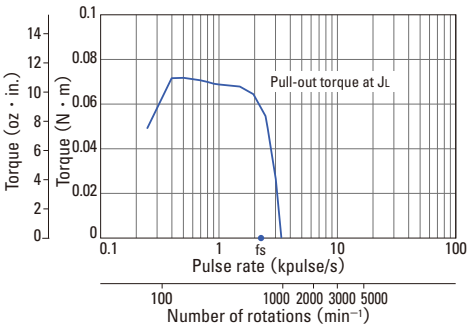
Unipolar winding · Lead wire type ▶ P.25
Bipolar winding · Lead wire type

Bipolar winding • Lead wire type

Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
SH2281-5671	**SH2281-5631**	0.07 (9.91)	0.5	10.5	7.2	0.01 (0.05)	0.11 (0.24)
SH2281-5771	**SH2281-5731**	0.07 (9.91)	1	2.6	1.85	0.01 (0.05)	0.11 (0.24)
SH2285-5671	**SH2285-5631**	0.145 (20.53)	0.5	15	13.5	0.022 (0.12)	0.2 (0.44)
SH2285-5771	**SH2285-5731**	0.145 (20.53)	1	3.75	3.4	0.022 (0.12)	0.2 (0.44)

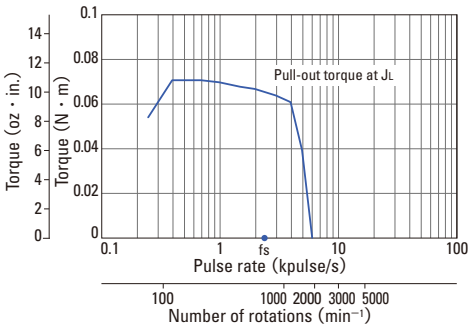
Characteristics diagram

SH2281-5671
SH2281-5631



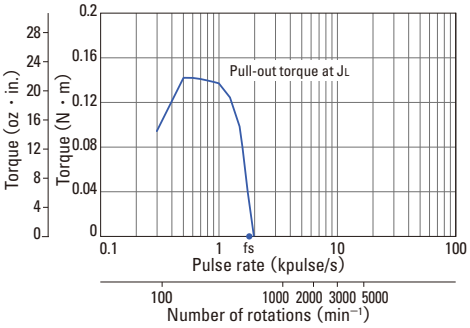
Constant current circuit
Source voltage : DC24V · Operating current : 0.5A/phase, 2-phase energization (full-step)
J_L=[0.01 × 10⁻⁴kg · m² (1.80 oz · in²) pulley balancer method]
fs: Maximum self-start frequency when not loaded

SH2281-5771
SH2281-5731



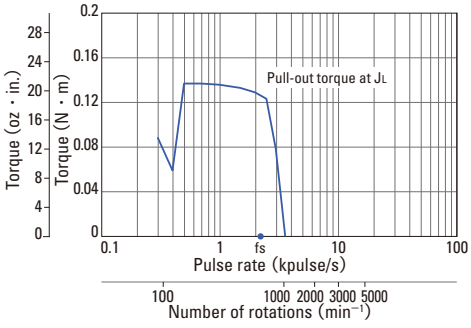
Constant current circuit
Source voltage : DC24V · Operating current : 1A/phase, 2-phase energization (full-step)
J_L=[0.01 × 10⁻⁴kg · m² (1.80 oz · in²) pulley balancer method]
fs: Maximum self-start frequency when not loaded

SH2285-5671
SH2285-5631



Constant current circuit
Source voltage : DC24V · Operating current : 0.5A/phase, 2-phase energization (full-step)
J_L=[0.01 × 10⁻⁴kg · m² (1.80 oz · in²) pulley balancer method]
fs: Maximum self-start frequency when not loaded

SH2285-5771
SH2285-5731



Constant current circuit
Source voltage : DC24V · Operating current : 1A/phase, 2-phase energization (full-step)
J_L=[0.01 × 10⁻⁴kg · m² (1.80 oz · in²) pulley balancer method]
fs: Maximum self-start frequency when not loaded

Allowable Load · Internal Wiring · Rotation Direction ▶ P.56 General Specifications ▶ P.57 Motor Dimensions ▶ P.69 The data are measured under the trial conditions of SANYO DENKI.
Driving torque may vary according to actual machine precision.

35 mm sq. (1.38 inch sq.)

1.8˚ /step

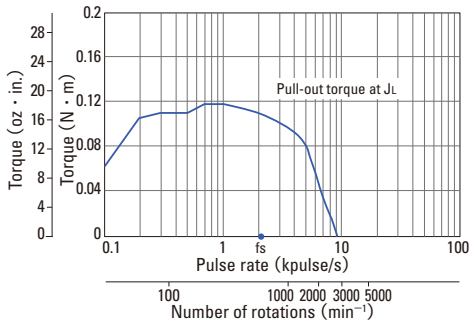
Unipolar winding · Lead wire type

Unipolar winding • Lead wire type

Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
SH3533-12U40	**SH3533-12U10**	0.12 (16.99)	1.2	2.4	1.3	0.02 (1.09)	0.17 (0.37)
SH3537-12U40	**SH3537-12U10**	0.15 (21.24)	1.2	2.7	2	0.025 (1.37)	0.2 (0.44)
SH3552-12U40	**SH3552-12U10**	0.23 (32.57)	1.2	3.4	2.8	0.043 (2.35)	0.3 (0.66)

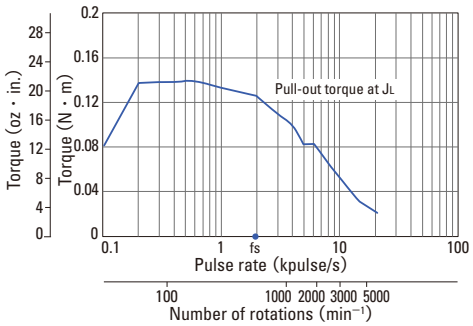
Characteristics diagram

SH3533-12U40
SH3533-12U10



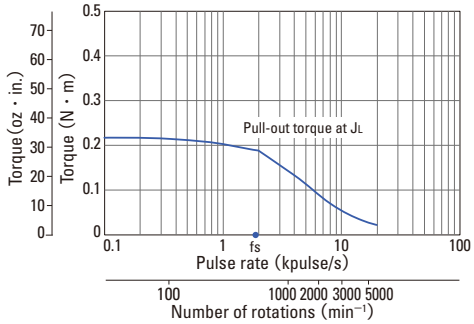
Constant current circuit
Source voltage : DC24V · Operating current : 1.2A/phase, 2-phase energization (full-step)
J_L=[0.33 × 10⁻⁴kg · m² (1.80 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SH3537-12U40
SH3537-12U10



Constant current circuit
Source voltage : DC24V · Operating current : 1.2A/phase, 2-phase energization (full-step)
J_L=[0.33 × 10⁻⁴kg · m² (1.80 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SH3552-12U40
SH3552-12U10



Constant current circuit
Source voltage : DC24V · Operating current : 1.2A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

42 mm sq. (1.65 inch sq.)

1.8˚ /step **Slim form**

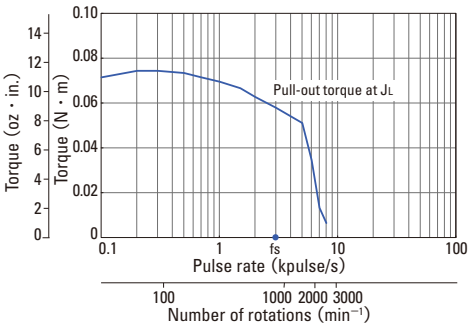
Bipolar winding · Lead wire type

Bipolar winding • Lead wire type

Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
SS2421-5041	**SS2421-5011**	0.083 (11.75)	1	3.5	1.2	0.015 (0.082)	0.07 (0.15)
SS2422-5041	**SS2422-5011**	0.186 (26.33)	1	5.4	2.9	0.028 (0.153)	0.14 (0.31)

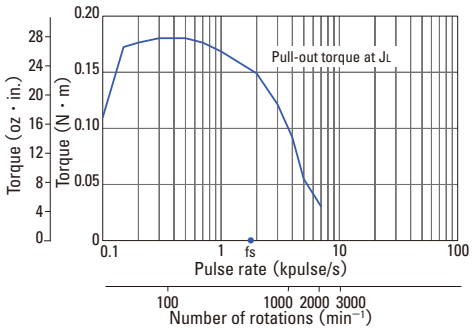
Characteristics diagram

SS2421-5041
SS2421-5011



Constant current circuit
Source voltage : DC24V · Operating current : 1A/phase, 2-phase energization (full-step)
J_L=[0.33 × 10⁻⁴kg · m² (1.80 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SS2422-5041
SS2422-5011



Constant current circuit
Source voltage : DC24V · Operating current : 1A/phase, 2-phase energization (full-step)
J_L=[0.33 × 10⁻⁴kg · m² (1.80 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

Allowable Load · Internal Wiring · Rotation Direction ▶ P.56 General Specifications ▶ P.57 Motor Dimensions ▶ P.69 The data are measured under the trial conditions of SANYO DENKI.
Driving torque may vary according to actual machine precision.

42 mm sq. (1.65 inch sq.)

0.9˚ /step

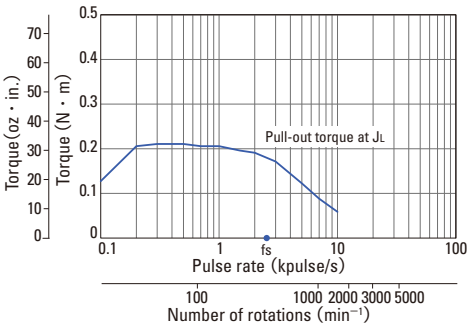
Unipolar winding · Lead wire type
Bipolar winding · Lead wire type ▶ P.30

Unipolar winding • Lead wire type

Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
SH1421-0441	**SH1421-0411**	0.20 (28.32)	1.2	2.7	3.2	0.044 (0.241)	0.24 (0.53)
SH1422-0441	**SH1422-0411**	0.29 (41.07)	1.2	3.1	5.3	0.066 (0.361)	0.29 (0.64)
SH1424-0441	**SH1424-0411**	0.39 (55.23)	1.2	3.5	5.3	0.089 (0.487)	0.38 (0.84)

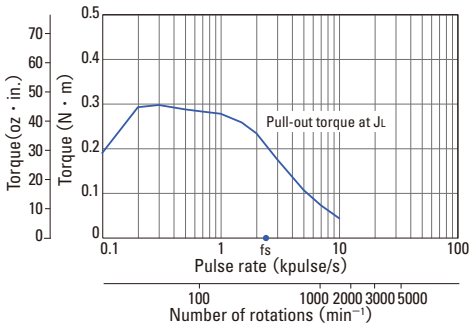
Characteristics diagram

SH1421-0441
SH1421-0411



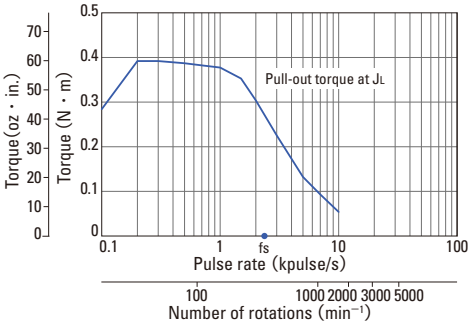
Constant current circuit
Source voltage : DC24V · Operating current : 1.2A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SH1422-0441
SH1422-0411



Constant current circuit
Source voltage : DC24V · Operating current : 1.2A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SH1424-0441
SH1424-0411



Constant current circuit
Source voltage : DC24V · Operating current : 1.2A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

42 mm sq. (1.65 inch sq.)

0.9˚ /step

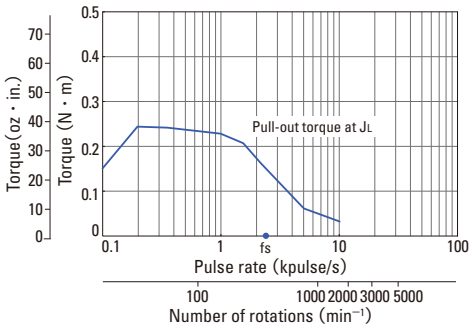
Unipolar winding · Lead wire type ▶ P.29
Bipolar winding · Lead wire type

Bipolar winding • Lead wire type

Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
SH1421-5041	**SH1421-5011**	0.23 (32.5)	1	3.3	8.0	0.044 (0.24)	0.24 (0.53)
SH1421-5241	**SH1421-5211**	0.23 (32.5)	2	0.85	2.1	0.044 (0.24)	0.24 (0.53)
SH1422-5041	**SH1422-5011**	0.34 (48.1)	1	4.0	14.0	0.066 (0.36)	0.29 (0.64)
SH1422-5241	**SH1422-5211**	0.34 (48.1)	2	1.05	3.6	0.066 (0.36)	0.29 (0.64)
SH1424-5041	**SH1424-5011**	0.48 (67.9)	1	4.7	15.0	0.089 (0.49)	0.38 (0.84)
SH1424-5241	**SH1424-5211**	0.48 (67.9)	2	1.25	3.75	0.089 (0.49)	0.38 (0.84)

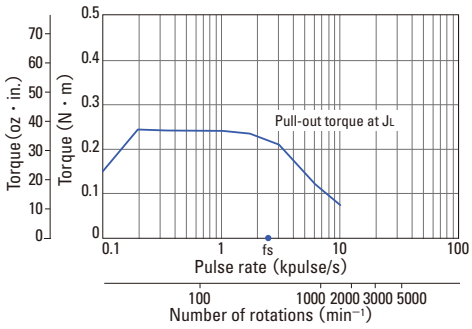
Characteristics diagram

SH1421-5041
SH1421-5011



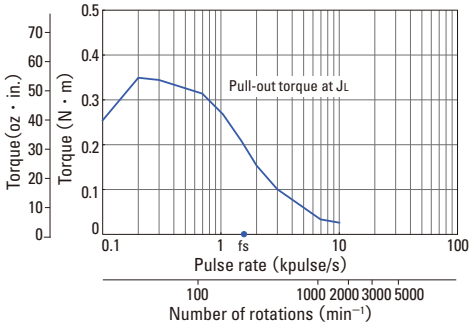
Constant current circuit
Source voltage : DC24V · Operating current : 1A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SH1421-5241
SH1421-5211



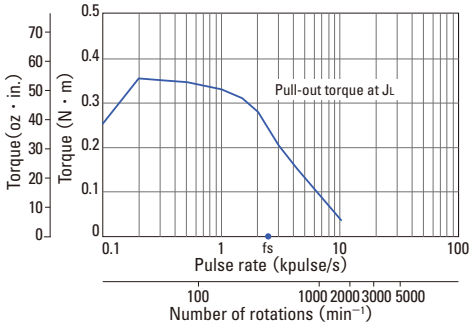
Constant current circuit
Source voltage : DC24V · Operating current : 2A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SH1422-5041
SH1422-5011



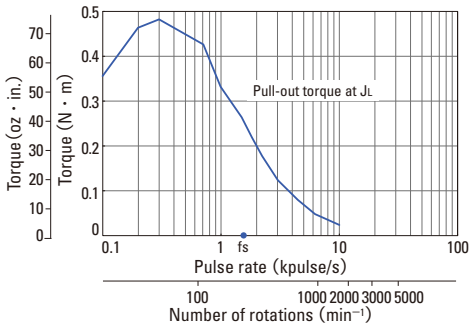
Constant current circuit
Source voltage : DC24V · Operating current : 1A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SH1422-5241
SH1422-5211



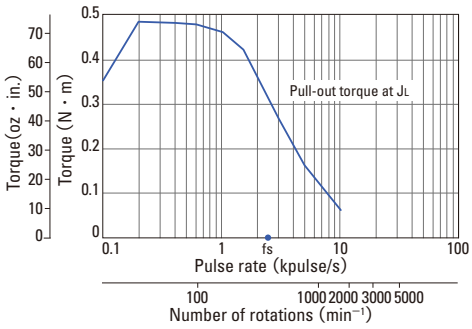
Constant current circuit
Source voltage : DC24V · Operating current : 2A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SH1424-5041
SH1424-5011



Constant current circuit
Source voltage : DC24V · Operating current : 1A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SH1424-5241
SH1424-5211



Constant current circuit
Source voltage : DC24V · Operating current : 2A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

Allowable Load · Internal Wiring · Rotation Direction ▶ P.56 General Specifications ▶ P.57 Motor Dimensions ▶ P.70 The data are measured under the trial conditions of SANYO DENKI.
Driving torque may vary according to actual machine precision.

42 mm sq. (1.65 inch sq.)

1.8˚ /step

Unipolar winding · Connector type
Bipolar winding · Lead wire type ▶ P.32

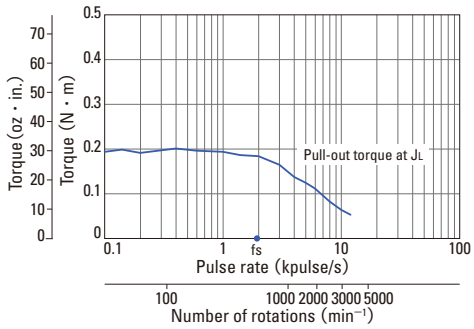
Unipolar winding • Connector type

Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
103H5205-0440	**103H5205-0410**	0.2 (28.32)	1.2	2.4	2.3	0.036 (0.20)	0.23 (0.51)
103H5208-0440	**103H5208-0410**	0.3 (42.48)	1.2	2.9	3.4	0.056 (0.31)	0.29 (0.64)
103H5209-0440	**103H5209-0410**	0.32 (45.31)	1.2	3	3.9	0.062 (0.34)	0.31 (0.68)
103H5210-0440	**103H5210-0410**	0.37 (52.39)	1.2	3.3	3.4	0.074 (0.40)	0.37 (0.82)

Motor cable : Model No.4835710-1

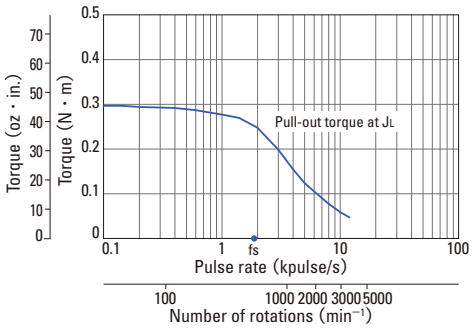
Characteristics diagram

103H5205-0440
103H5205-0410



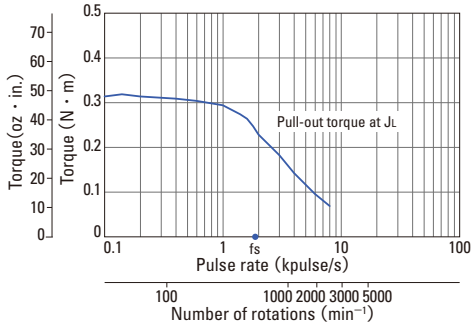
Constant current circuit
Source voltage : DC24V · Operating current : 1.2A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H5208-0440
103H5208-0410



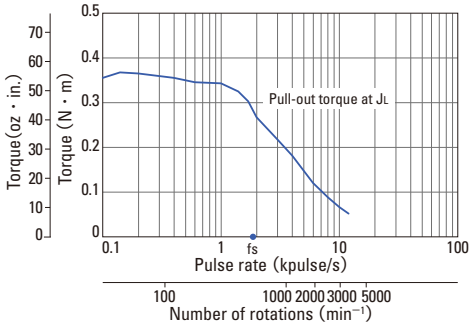
Constant current circuit
Source voltage : DC24V · Operating current : 1.2A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H5209-0440
103H5209-0410



Constant current circuit
Source voltage : DC24V · Operating current : 1.2A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H5210-0440
103H5210-0410



Constant current circuit
Source voltage : DC24V · Operating current : 1.2A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

42 mm sq. (1.65 inch sq.)

1.8˚ /step

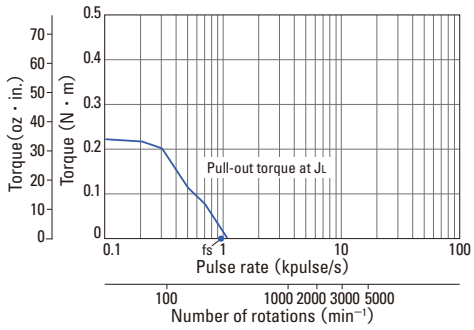
Unipolar winding · Connector type ▶ P.31
Bipolar winding · Lead wire type

Bipolar winding • Lead wire type

Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
103H5205-5040	**103H5205-5010**	0.23 (32.57)	0.25	54	78	0.036 (0.20)	0.23 (0.51)
103H5205-5140	**103H5205-5110**	0.25 (35.40)	0.5	13.4	23.4	0.036 (0.20)	0.23 (0.51)
103H5205-5240	**103H5205-5210**	0.265 (37.53)	1	3.4	6.5	0.036 (0.20)	0.23 (0.51)
103H5208-5040	**103H5208-5010**	0.35 (49.56)	0.25	66	116	0.056 (0.31)	0.29 (0.64)
103H5208-5140	**103H5208-5110**	0.38 (53.81)	0.5	16.5	34	0.056 (0.31)	0.29 (0.64)
103H5208-5240	**103H5208-5210**	0.39 (55.23)	1	4.1	9.5	0.056 (0.31)	0.29 (0.64)
103H5209-5040	**103H5209-5010**	0.38 (53.81)	0.25	71.4	133	0.062 (0.34)	0.31 (0.68)
103H5209-5140	**103H5209-5110**	0.41 (58.06)	0.5	18.2	39	0.062 (0.34)	0.31 (0.68)
103H5209-5240	**103H5209-5210**	0.425 (60.18)	1	4.4	11	0.062 (0.34)	0.31 (0.68)
103H5210-5040	**103H5210-5010**	0.465 (65.85)	0.25	80	123.3	0.074 (0.40)	0.37 (0.82)
103H5210-5140	**103H5210-5110**	0.49 (69.39)	0.5	20	35	0.074 (0.40)	0.37 (0.82)
103H5210-5240	**103H5210-5210**	0.51 (72.22)	1	4.8	9.5	0.074 (0.40)	0.37 (0.82)

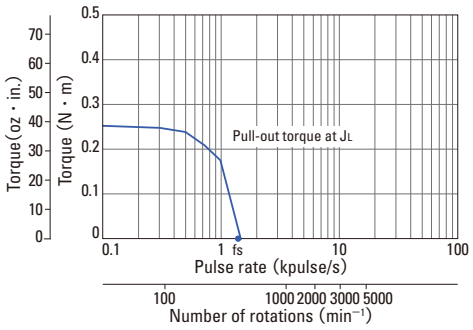
Characteristics diagram

103H5205-5040
103H5205-5010



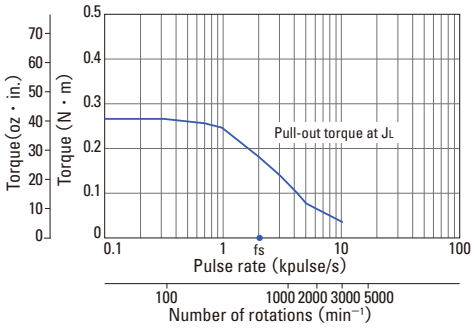
Constant current circuit
Source voltage : DC24V · Operating current : 0.25A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H5205-5140
103H5205-5110



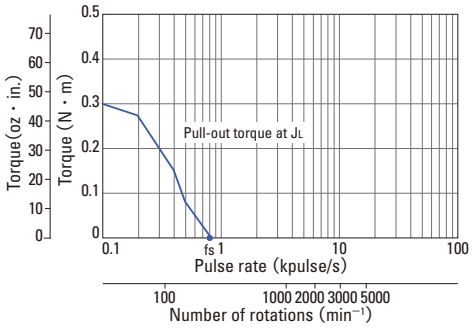
Constant current circuit
Source voltage : DC24V · Operating current : 0.5A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H5205-5240
103H5205-5210



Constant current circuit
Source voltage : DC24V · Operating current : 1A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H5208-5040
103H5208-5010

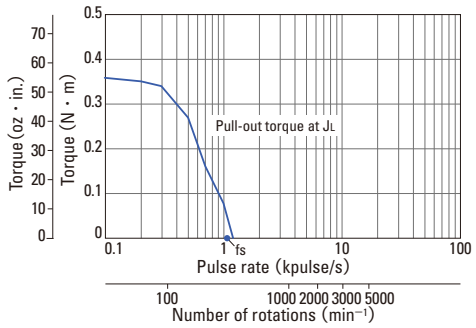


Constant current circuit
Source voltage : DC24V · Operating current : 0.25A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

Allowable Load · Internal Wiring · Rotation Direction ▶ P.56 General Specifications ▶ P.57 Motor Dimensions ▶ P.70 The data are measured under the trial conditions of SANYO DENKI.
Driving torque may vary according to actual machine precision.

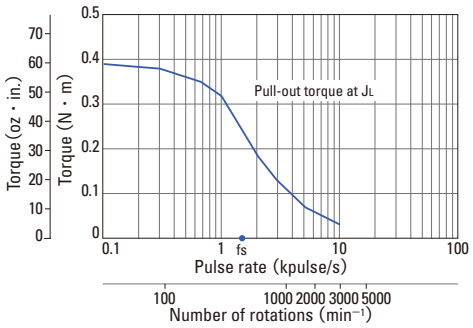
Characteristics diagram

103H5208-5140 / 103H5208-5110



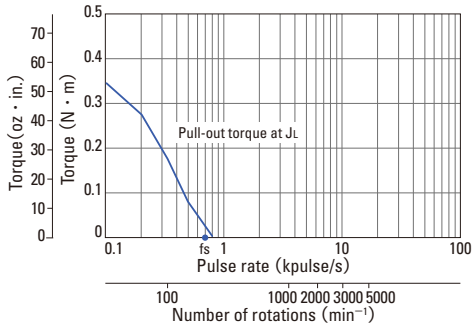
Constant current circuit
Source voltage : DC24V・Operating current : 0.5A/phase,
2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg・m² (5.14 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H5208-5240 / 103H5208-5210



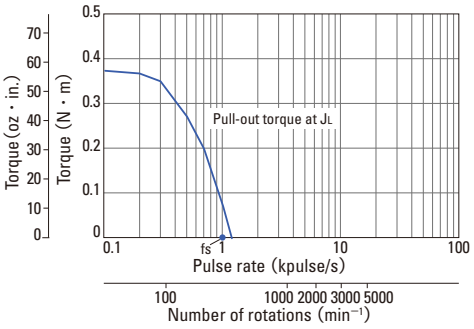
Constant current circuit
Source voltage : DC24V・Operating current : 1A/phase,
2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg・m² (5.14 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H5209-5040 / 103H5209-5010



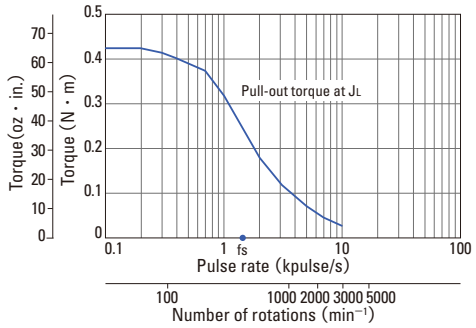
Constant current circuit
Source voltage : DC24V・Operating current : 0.25A/phase,
2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg・m² (5.14 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H5209-5140 / 103H5209-5110



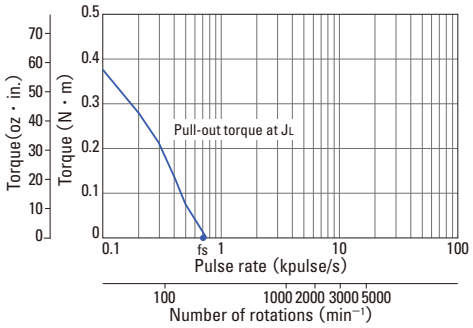
Constant current circuit
Source voltage : DC24V・Operating current : 0.5A/phase,
2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg・m² (5.14 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H5209-5240 / 103H5209-5210



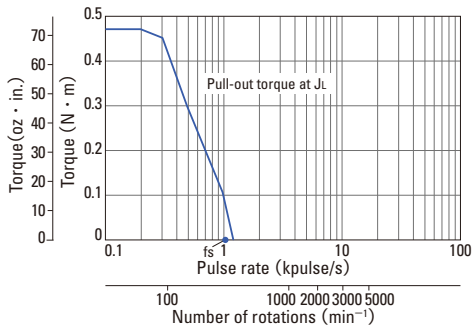
Constant current circuit
Source voltage : DC24V・Operating current : 1A/phase,
2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg・m² (5.14 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H5210-5040 / 103H5210-5010



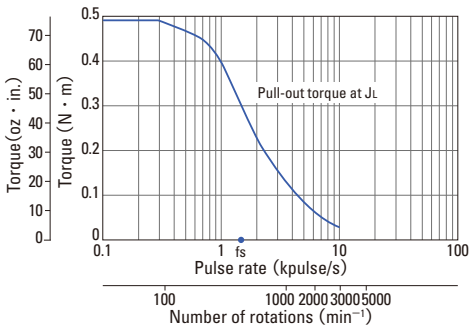
Constant current circuit
Source voltage : DC24V・Operating current : 0.25A/phase,
2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg・m² (5.14 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H5210-5140 / 103H5210-5110



Constant current circuit
Source voltage : DC24V・Operating current : 0.5A/phase,
2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg・m² (5.14 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H5210-5240 / 103H5210-5210



Constant current circuit
Source voltage : DC24V・Operating current : 1A/phase,
2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg・m² (5.14 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

50 mm sq. (1.97 inch sq.)

1.8˚ /step

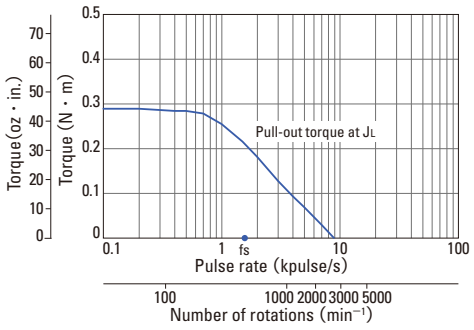
Unipolar winding · Lead wire type
Bipolar winding · Lead wire type ▶ P.36

Unipolar winding • Lead wire type

Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
103H6701-0140	**103H6701-0110**	0.28 (39.6)	1	4.3	6.8	0.057 (0.31)	0.35 (0.77)
103H6701-0440	**103H6701-0410**	0.28 (39.6)	2	1.1	1.6	0.057 (0.31)	0.35 (0.77)
103H6701-0740	**103H6701-0710**	0.28 (39.6)	3	0.6	0.7	0.057 (0.31)	0.35 (0.77)
103H6703-0140	**103H6703-0110**	0.49 (69.4)	1	6	13	0.118 (0.65)	0.5 (1.10)
103H6703-0440	**103H6703-0410**	0.49 (69.4)	2	1.6	3.2	0.118 (0.65)	0.5 (1.10)
103H6703-0740	**103H6703-0710**	0.49 (69.4)	3	0.83	1.4	0.118 (0.65)	0.5 (1.10)
103H6704-0140	**103H6704-0110**	0.53 (75.1)	1	6.5	16.5	0.14 (0.77)	0.55 (1.21)
103H6704-0440	**103H6704-0410**	0.52 (73.6)	2	1.7	3.8	0.14 (0.77)	0.55 (1.21)
103H6704-0740	**103H6704-0710**	0.53 (75.1)	3	0.9	1.7	0.14 (0.77)	0.55 (1.21)

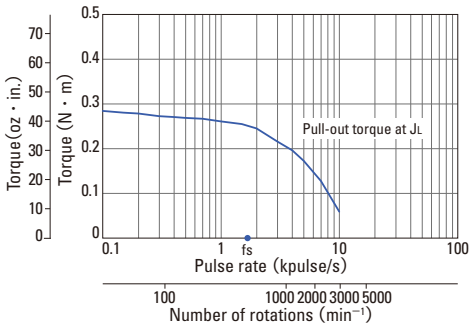
Characteristics diagram

103H6701-0140
103H6701-0110



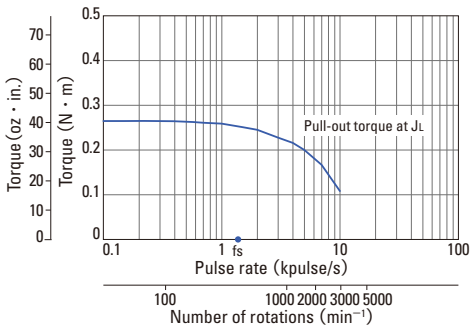
Constant current circuit
Source voltage : DC24V · Operating current : 1A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H6701-0440
103H6701-0410



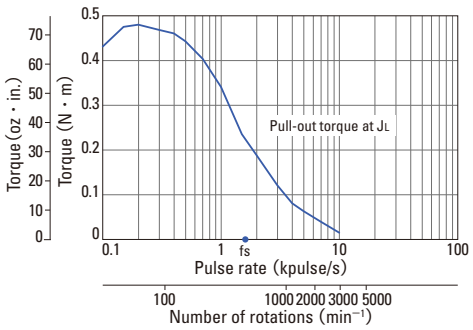
Constant current circuit
Source voltage : DC24V · Operating current : 2A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H6701-0740
103H6701-0710



Constant current circuit
Source voltage : DC24V · Operating current : 3A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H6703-0140
103H6703-0110

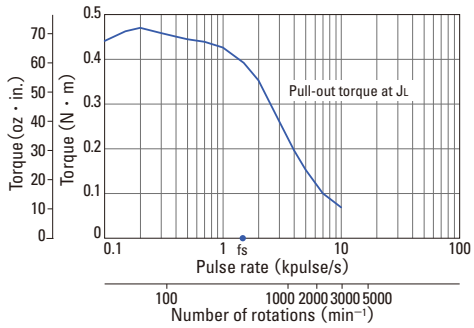


Constant current circuit
Source voltage : DC24V · Operating current : 1A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

Allowable Load · Internal Wiring · Rotation Direction ▶ P.56 General Specifications ▶ P.57 Motor Dimensions ▶ P.70 The data are measured under the trial conditions of SANYO DENKI.
Driving torque may vary according to actual machine precision.

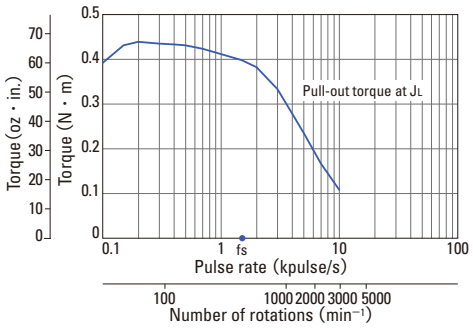
Characteristics diagram

103H6703-0440
103H6703-0410



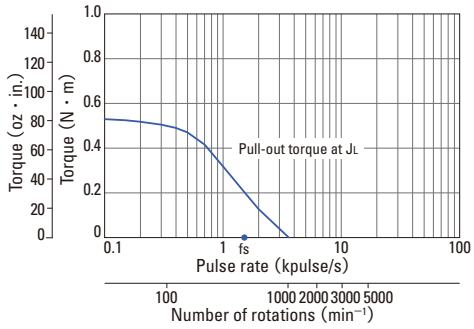
Constant current circuit
Source voltage : DC24V・Operating current : 2A/phase,
2-phase energization (full-step)
J_L=[0.94 × 10^{-4}kg・m^2 (5.14 oz・in^2) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H6703-0740
103H6703-0710



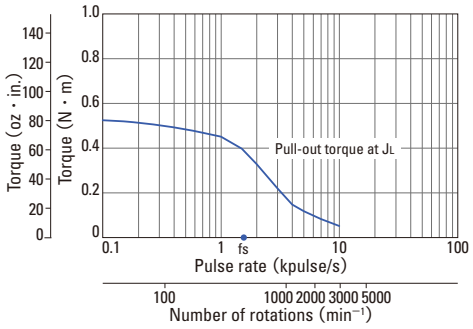
Constant current circuit
Source voltage : DC24V・Operating current : 3A/phase,
2-phase energization (full-step)
J_L=[0.94 × 10^{-4}kg・m^2 (5.14 oz・in^2) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H6704-0140
103H6704-0110



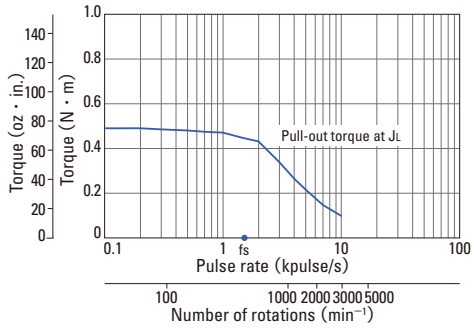
Constant current circuit
Source voltage : DC24V・Operating current : 1A/phase,
2-phase energization (full-step)
J_L=[0.94 × 10^{-4}kg・m^2 (5.14 oz・in^2) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H6704-0440
103H6704-0410



Constant current circuit
Source voltage : DC24V・Operating current : 2A/phase,
2-phase energization (full-step)
J_L=[0.94 × 10^{-4}kg・m^2 (5.14 oz・in^2) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H6704-0740
103H6704-0710



Constant current circuit
Source voltage : DC24V・Operating current : 3A/phase,
2-phase energization (full-step)
J_L=[0.94 × 10^{-4}kg・m^2 (5.14 oz・in^2) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

50 mm sq. (1.97 inch sq.)

1.8˚ /step

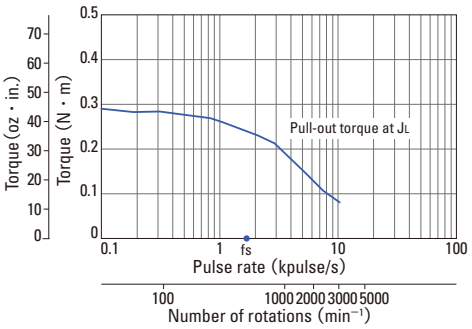
Unipolar winding · Lead wire type ▶ P.34
Bipolar winding · Lead wire type

Bipolar winding • Lead wire type

Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
103H6701-5040	**103H6701-5010**	0.28 (39.6)	2	0.6	1.6	0.057 (0.31)	0.35 (0.77)
103H6703-5040	**103H6703-5010**	0.49 (69.4)	2	0.8	3.2	0.118 (0.65)	0.5 (1.10)
103H6704-5040	**103H6704-5010**	0.52 (73.6)	2	0.9	3.8	0.14 (0.77)	0.55 (1.21)

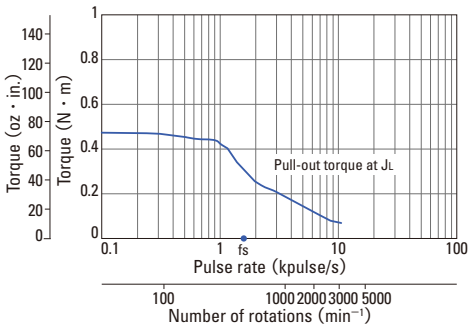
Characteristics diagram

103H6701-5040
103H6701-5010



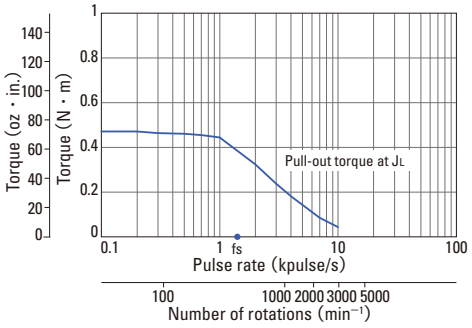
Constant current circuit
Source voltage : DC24V · Operating current : 2A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H6703-5040
103H6703-5010



Constant current circuit
Source voltage : DC24V · Operating current : 2A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H6704-5040
103H6704-5010



Constant current circuit
Source voltage : DC24V · Operating current : 2A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

 Allowable Load · Internal Wiring · Rotation Direction ▶ P.56 General Specifications ▶ P.57 Motor Dimensions ▶ P.70 The data are measured under the trial conditions of SANYO DENKI.
Driving torque may vary according to actual machine precision.

50 mm sq. (1.97 inch sq.)

1.8˚ /step **Slim form**

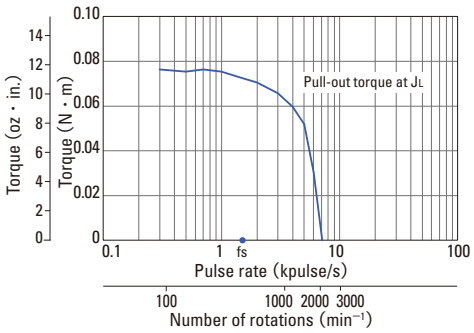
Bipolar winding · Lead wire type

Bipolar winding • Lead wire type

Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
SS2501-8040	**SS2501-8010**	0.1 (14.16)	1	4.5	2	0.026 (0.142)	0.09 (0.20)
SS2502-8040	**SS2502-8010**	0.215 (30.44)	1	5.9	3.2	0.049 (0.268)	0.15 (0.33)

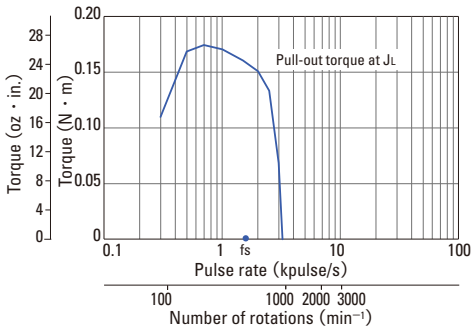
Characteristics diagram

SS2501-8040
SS2501-8010



Constant current circuit
Source voltage : DC24V · operating current : 1A/phase, 2-phase energization (full-step)
J_L=[0.01 × 10⁻⁴kg · m² (1.80 oz · in²) pulley balancer method]
fs: Maximum self-start frequency when not loaded

SS2502-8040
SS2502-8010



Constant current circuit
Source voltage : DC24V · operating current : 1A/phase, 2-phase energization (full-step)
J_L=[0.01 × 10⁻⁴kg · m² (1.80 oz · in²) pulley balancer method]
fs: Maximum self-start frequency when not loaded

56 mm sq. (2.20 inch sq.)

1.8˚ /step

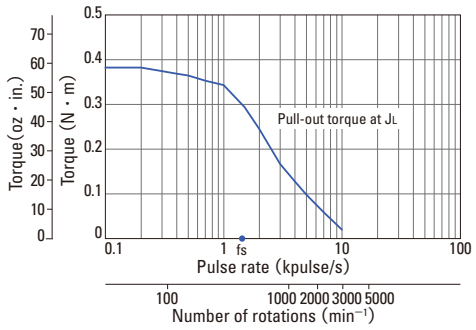
Unipolar winding · Lead wire type
Bipolar winding · Lead wire type ▶ P.40

Unipolar winding • Lead wire type

Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
103H7121-0140	**103H7121-0110**	0.39 (55.2)	1	4.8	8	0.1 (0.55)	0.47 (1.04)
103H7121-0440	**103H7121-0410**	0.39 (55.2)	2	1.25	1.9	0.1 (0.55)	0.47 (1.04)
103H7121-0740	**103H7121-0710**	0.39 (55.2)	3	0.6	0.8	0.1 (0.55)	0.47 (1.04)
103H7123-0140	**103H7123-0110**	0.83 (117.5)	1	6.7	15	0.21 (1.15)	0.65 (1.43)
103H7123-0440	**103H7123-0410**	0.83 (117.5)	2	1.6	3.8	0.21 (1.15)	0.65 (1.43)
103H7123-0740	**103H7123-0710**	0.78 (110.5)	3	0.77	1.58	0.21 (1.15)	0.65 (1.43)
103H7124-0140	**103H7124-0110**	0.98 (138.8)	1	7	14.5	0.245 (1.34)	0.8 (1.76)
103H7124-0440	**103H7124-0410**	0.98 (138.8)	2	1.7	3.1	0.245 (1.34)	0.8 (1.76)
103H7124-0740	**103H7124-0710**	0.98 (138.8)	3	0.74	1.4	0.245 (1.34)	0.8 (1.76)
103H7126-0140	**103H7126-0110**	1.27 (179.8)	1	8.6	19	0.36 (1.97)	0.98 (2.16)
103H7126-0440	**103H7126-0410**	1.27 (179.8)	2	2	4.5	0.36 (1.97)	0.98 (2.16)
103H7126-0740	**103H7126-0710**	1.27 (179.8)	3	0.9	2.2	0.36 (1.97)	0.98 (2.16)

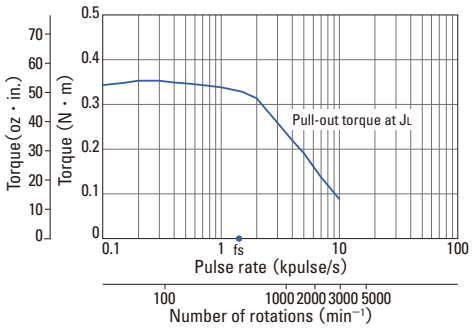
Characteristics diagram

103H7121-0140
103H7121-0110



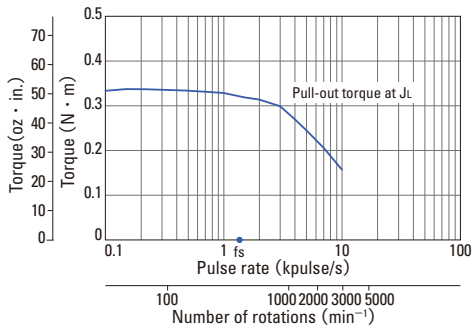
Constant current circuit
Source voltage : DC24V · Operating current : 1A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7121-0440
103H7121-0410



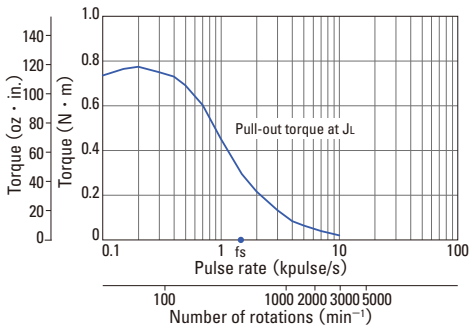
Constant current circuit
Source voltage : DC24V · Operating current : 2A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7121-0740
103H7121-0710



Constant current circuit
Source voltage : DC24V · Operating current : 3A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7123-0140
103H7123-0110

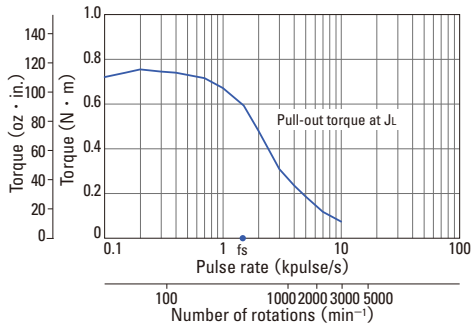


Constant current circuit
Source voltage : DC24V · Operating current : 1A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

Allowable Load · Internal Wiring · Rotation Direction ▶ P.56 General Specifications ▶ P.57 Motor Dimensions ▶ P.71 The data are measured under the trial conditions of SANYO DENKI.
Driving torque may vary according to actual machine precision.

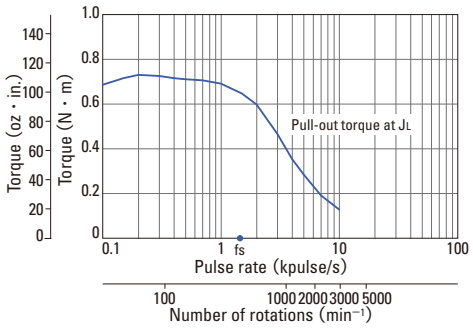
Characteristics diagram

103H7123-0440 / 103H7123-0410



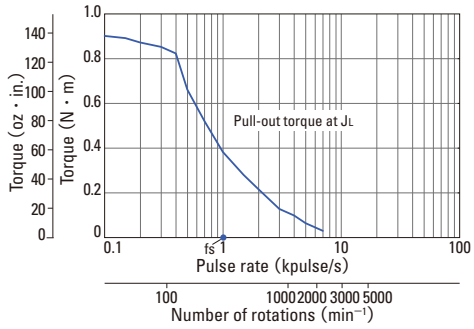
Constant current circuit
Source voltage : DC24V · Operating current : 2A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7123-0740 / 103H7123-0710



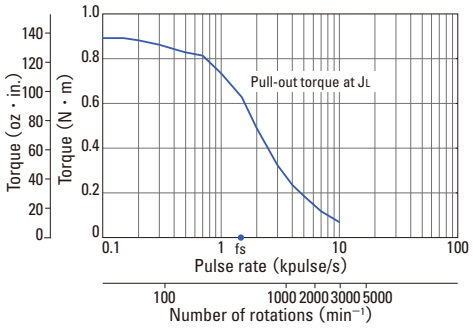
Constant current circuit
Source voltage : DC24V · Operating current : 3A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7124-0140 / 103H7124-0110



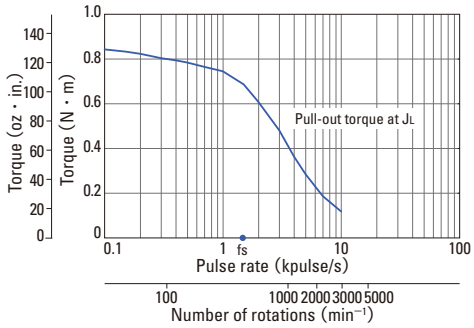
Constant current circuit
Source voltage : DC24V · Operating current : 1A/phase, 2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg · m² (14.22 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7124-0440 / 103H7124-0410



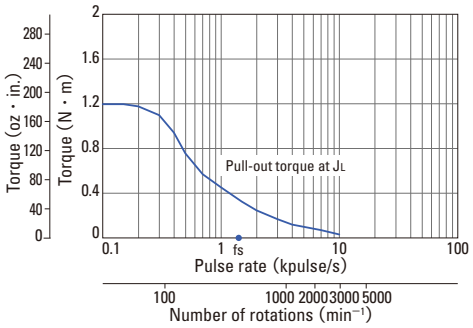
Constant current circuit
Source voltage : DC24V · Operating current : 2A/phase, 2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg · m² (14.22 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7124-0740 / 103H7124-0710



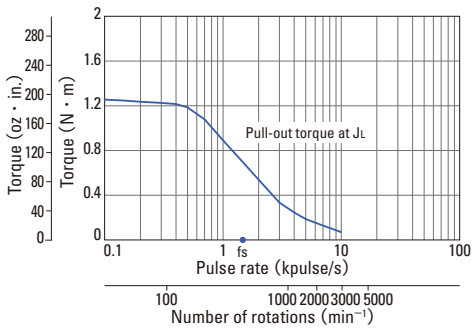
Constant current circuit
Source voltage : DC24V · Operating current : 3A/phase, 2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg · m² (14.22 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7126-0140 / 103H7126-0110



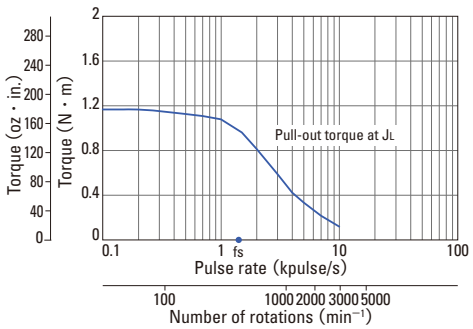
Constant current circuit
Source voltage : DC24V · Operating current : 1A/phase, 2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg · m² (14.22 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7126-0440 / 103H7126-0410



Constant current circuit
Source voltage : DC24V · Operating current : 2A/phase, 2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg · m² (14.22 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7126-0740 / 103H7126-0710



Constant current circuit
Source voltage : DC24V · Operating current : 3A/phase, 2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg · m² (14.22 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

56 mm sq. (2.20 inch sq.)

1.8˚ /step

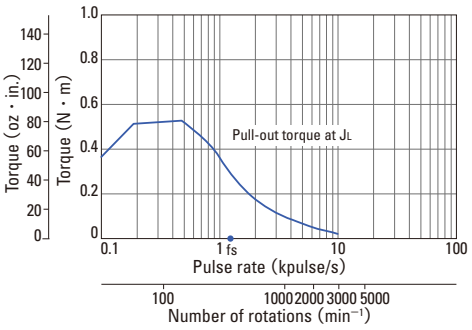
Unipolar winding · Lead wire type ▶ P.38
Bipolar winding · Lead wire type

Bipolar winding • Lead wire type

Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
103H7121-5640	**103H7121-5610**	0.55 (77.9)	1	4.3	14.5	0.1 (0.55)	0.47 (1.04)
103H7121-5740	**103H7121-5710**	0.55 (77.9)	2	1.1	3.7	0.1 (0.55)	0.47 (1.04)
103H7121-5840	**103H7121-5810**	0.55 (77.9)	3	0.54	1.74	0.1 (0.55)	0.47 (1.04)
103H7123-5640	**103H7123-5610**	1.0 (141.6)	1	5.7	29.4	0.21 (1.15)	0.65 (1.43)
103H7123-5740	**103H7123-5710**	1.0 (141.6)	2	1.5	7.5	0.21 (1.15)	0.65 (1.43)
103H7123-5840	**103H7123-5810**	1.0 (141.6)	3	0.7	3.5	0.21 (1.15)	0.65 (1.43)
103H7126-5640	**103H7126-5610**	1.6 (226.6)	1	7.7	34.6	0.36 (1.97)	0.98 (2.16)
103H7126-5740	**103H7126-5710**	1.6 (226.6)	2	2	9.1	0.36 (1.97)	0.98 (2.16)
103H7126-5840	**103H7126-5810**	1.6 (226.6)	3	0.94	4	0.36 (1.97)	0.98 (2.16)
103H7128-5640	**103H7128-5610**	2.0 (283.2)	1	8.9	40.1	0.49 (2.68)	1.3 (2.87)
103H7128-5740	**103H7128-5710**	2.0 (283.2)	2	2.3	10.4	0.49 (2.68)	1.3 (2.87)
103H7128-5840	**103H7128-5810**	2.0 (283.2)	3	1.03	4.3	0.49 (2.68)	1.3 (2.87)

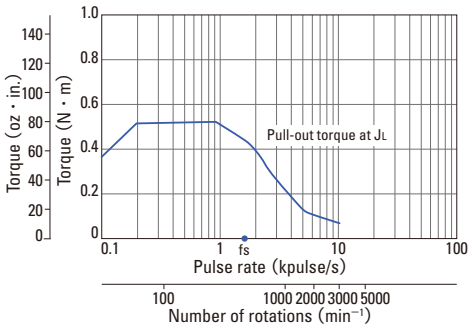
Characteristics diagram

103H7121-5640
103H7121-5610



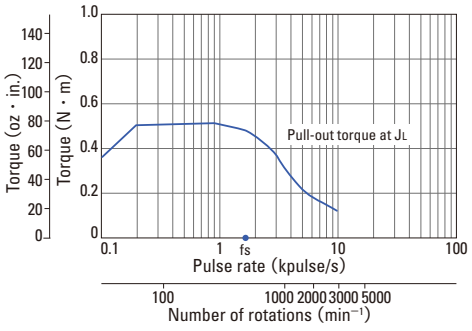
Constant current circuit
Source voltage : DC24V · Operating current : 1A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7121-5740
103H7121-5710



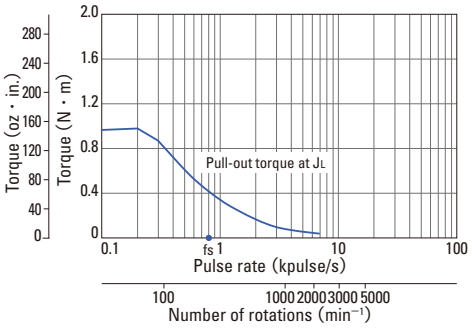
Constant current circuit
Source voltage : DC24V · Operating current : 2A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7121-5840
103H7121-5810



Constant current circuit
Source voltage : DC24V · Operating current : 3A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7123-5640
103H7123-5610

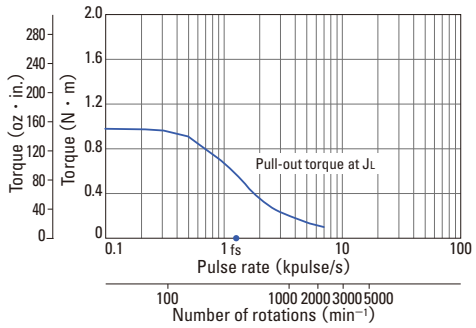


Constant current circuit
Source voltage : DC24V · Operating current : 1A/phase, 2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg · m² (14.22 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

Allowable Load · Internal Wiring · Rotation Direction ▶ P.56 General Specifications ▶ P.57 Motor Dimensions ▶ P.71 The data are measured under the trial conditions of SANYO DENKI.
Driving torque may vary according to actual machine precision.

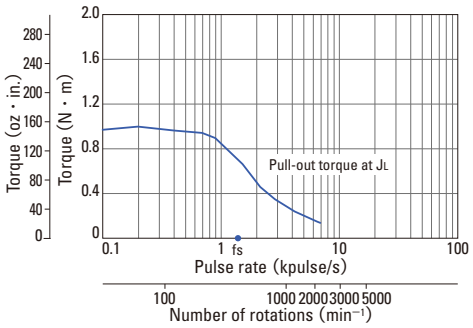
Characteristics diagram

103H7123-5740 / 103H7123-5710



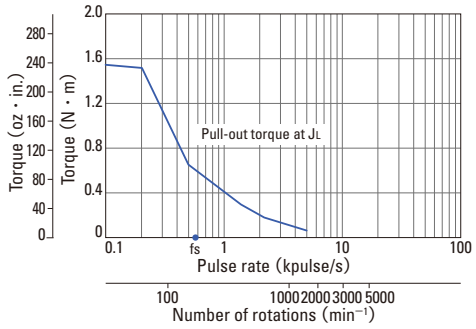
Constant current circuit
Source voltage : DC24V・operating current : 2A/phase,
2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg・m² (14.22 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7123-5840 / 103H7123-5810



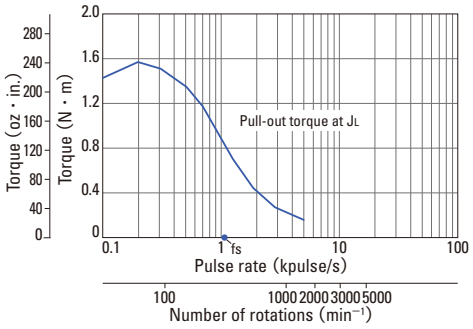
Constant current circuit
Source voltage : DC24V・Operating current : 3A/phase,
2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg・m² (14.22 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7126-5640 / 103H7126-5610



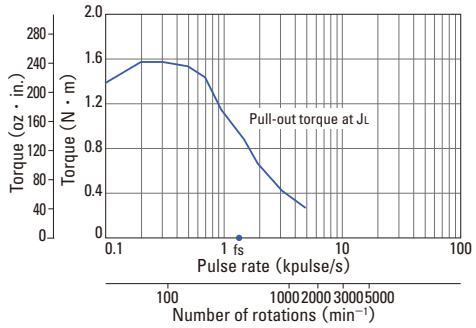
Constant current circuit
Source voltage : DC24V・Operating current : 1A/phase,
2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg・m² (14.22 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7126-5740 / 103H7126-5710



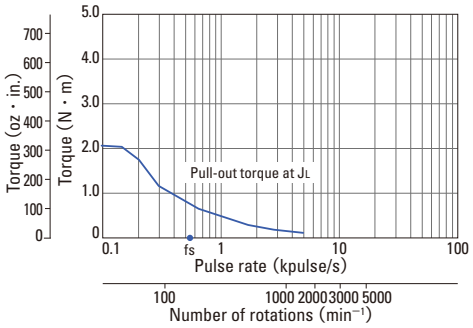
Constant current circuit
Source voltage : DC24V・Operating current : 2A/phase,
2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg・m² (14.22 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7126-5840 / 103H7126-5810



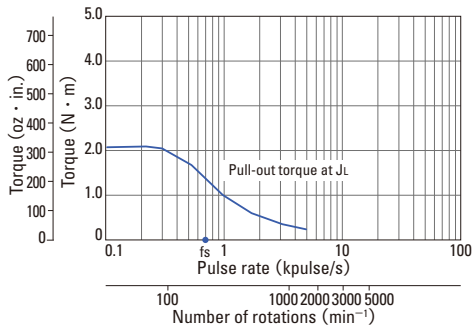
Constant current circuit
Source voltage : DC24V・Operating current : 3A/phase,
2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg・m² (14.22 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7128-5640 / 103H7128-5610



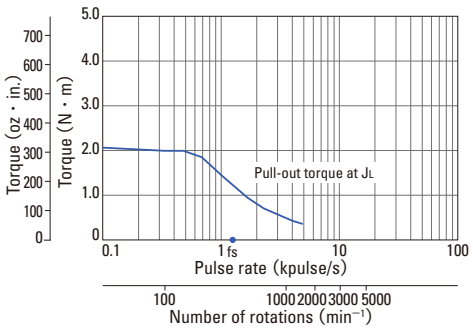
Constant current circuit
Source voltage : DC24V・Operating current : 1A/phase,
2-phase energization (full-step)
[J_L=7.4 × 10⁻⁴kg・m² (40.46 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7128-5740 / 103H7128-5710



Constant current circuit
Source voltage : DC24V・Operating current : 2A/phase,
2-phase energization (full-step)
[J_L=7.4 × 10⁻⁴kg・m² (40.46 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7128-5840 / 103H7128-5810



Constant current circuit
Source voltage : DC24V・Operating current : 3A/phase,
2-phase energization (full-step)
[J_L=7.4 × 10-⁴kg・m2 (40.46 oz・in2) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

60 mm sq. (2.36 inch sq.)

0.9˚ /step

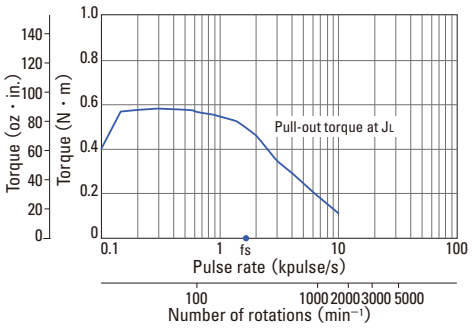
Unipolar winding · Lead wire type
Bipolar winding · Lead wire type

Unipolar winding • Lead wire type

Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
SH1601-0440	**SH1601-0410**	0.57 (80.71)	2	1.35	2	0.24 (1.312)	0.55 (1.21)
SH1602-0440	**SH1602-0410**	1.1 (155.77)	2	1.8	3.5	0.4 (2.187)	0.8 (1.76)
SH1603-0440	**SH1603-0410**	1.7 (240.74)	2	2.3	4.5	0.75 (4.101)	1.2 (2.64)

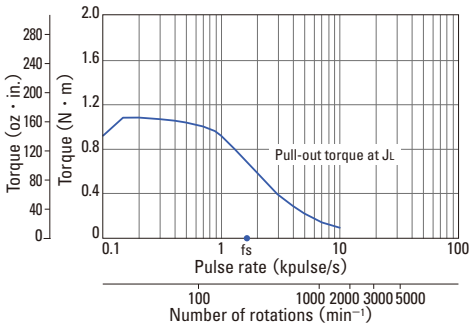
Characteristics diagram

SH1601-0440
SH1601-0410



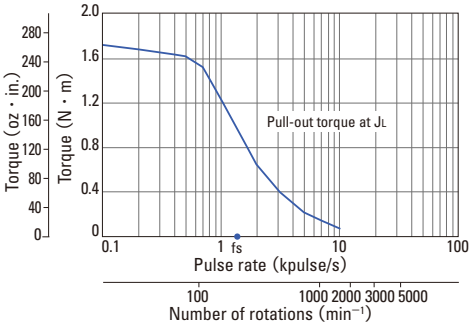
Constant current circuit
Source voltage : DC24V · Operating current : 2A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SH1602-0440
SH1602-0410



Constant current circuit
Source voltage : DC24V · Operating current : 2A/phase, 2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg · m² (14.22 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SH1603-0440
SH1603-0410



Constant current circuit
Source voltage : DC24V · Operating current : 2A/phase, 2-phase energization (full-step)
[J_L=7.4 × 10⁻⁴kg · m² (40.46 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

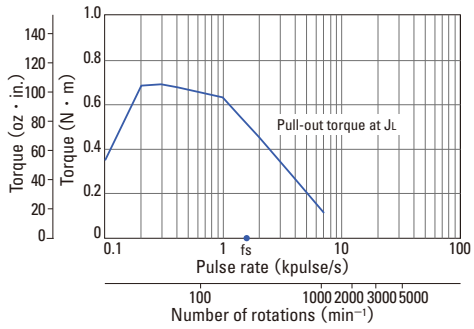
Allowable Load · Internal Wiring · Rotation Direction ▶ P.56 General Specifications ▶ P.57 Motor Dimensions ▶ P.71 The data are measured under the trial conditions of SANYO DENKI.
Driving torque may vary according to actual machine precision.

Bipolar winding • Lead wire type

Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N・m (oz・in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg・m² (oz・in²)]	[kg (lbs)]
SH1601-5240	**SH1601-5210**	0.69 (97.7)	2	1.2	3.5	0.24 (1.31)	0.55 (1.21)
SH1602-5240	**SH1602-5210**	1.28 (181.2)	2	1.65	6.1	0.4 (2.19)	0.8 (1.76)
SH1603-5240	**SH1603-5210**	2.15 (304.4)	2	2.3	8.8	0.75 (4.10)	1.2 (2.65)

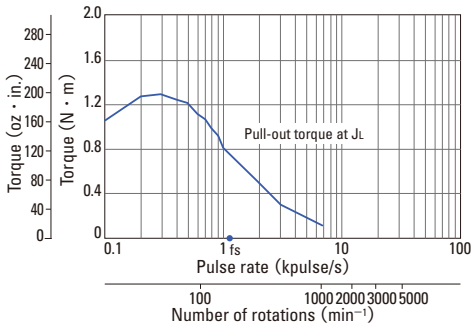
Characteristics diagram

SH1601-5240
SH1601-5210



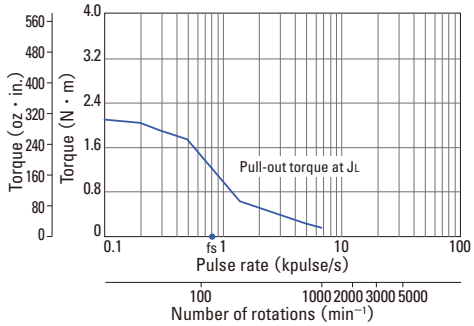
Constant current circuit
Source voltage : DC24V・Operating current : 2A/phase,
2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg・m² (5.14 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SH1602-5240
SH1602-5210



Constant current circuit
Source voltage : DC24V・Operating current : 2A/phase,
2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg・m² (14.22 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SH1603-5240
SH1603-5210



Constant current circuit
Source voltage : DC24V・Operating current : 2A/phase,
2-phase energization (full-step)
[J_L=7.4 × 10⁻⁴kg・m² (40.46 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

60 mm sq. (2.36 inch sq.)

1.8˚ /step

Unipolar winding · Connector type
Unipolar winding · Lead wire type Dimensions for attaching NEMA23 are interchangeable (47.14 mm-pitch)
Bipolar winding · Connector type ▶ P.46
Bipolar winding · Lead wire type Dimensions for attaching NEMA23 are interchangeable (47.14 mm-pitch) ▶ P.46

Unipolar winding • Connector type

Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
103H7821-0140	**103H7821-0110**	0.78 (110.5)	1	5.7	8.3	0.275 (1.50)	0.6 (1.32)
103H7821-0440	**103H7821-0410**	0.78 (110.5)	2	1.5	2	0.275 (1.50)	0.6 (1.32)
103H7821-0740	**103H7821-0710**	0.78 (110.5)	3	0.68	0.8	0.275 (1.50)	0.6 (1.32)
103H7822-0140	**103H7822-0110**	1.17 (165.7)	1	6.9	14	0.4 (2.19)	0.77 (1.70)
103H7822-0440	**103H7822-0410**	1.17 (165.7)	2	1.8	3.6	0.4 (2.19)	0.77 (1.70)
103H7822-0740	**103H7822-0710**	1.17 (165.7)	3	0.8	1.38	0.4 (2.19)	0.77 (1.70)
103H7823-0140	**103H7823-0110**	2.1 (297.4)	1	10	21.7	0.84 (4.59)	1.34 (2.95)
103H7823-0440	**103H7823-0410**	2.1 (297.4)	2	2.7	5.6	0.84 (4.59)	1.34 (2.95)
103H7823-0740	**103H7823-0710**	2.1 (297.4)	3	1.25	2.4	0.84 (4.59)	1.34 (2.95)

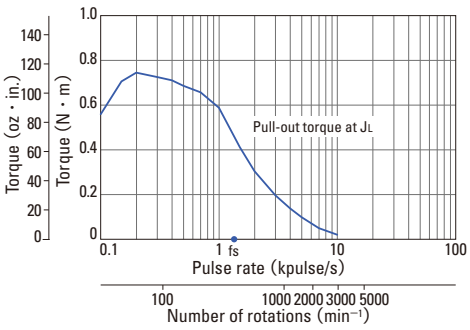
Motor cable : Model No. 4837798-1

Unipolar winding • Lead wire type Dimensions for attaching NEMA23 are interchangeable (47.14 mm-pitch)

Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
103H7821-0160	**103H7821-0130**	0.78 (110.5)	1	5.7	8.3	0.275 (1.50)	0.6 (1.32)
103H7821-0460	**103H7821-0430**	0.78 (110.5)	2	1.5	2	0.275 (1.50)	0.6 (1.32)
103H7821-0760	**103H7821-0730**	0.78 (110.5)	3	0.68	0.8	0.275 (1.50)	0.6 (1.32)
103H7822-0160	**103H7822-0130**	1.17 (165.7)	1	6.9	14	0.4 (2.19)	0.77 (1.70)
103H7822-0460	**103H7822-0430**	1.17 (165.7)	2	1.8	3.6	0.4 (2.19)	0.77 (1.70)
103H7822-0760	**103H7822-0730**	1.17 (165.7)	3	0.8	1.38	0.4 (2.19)	0.77 (1.70)
103H7823-0160	**103H7823-0130**	2.1 (297.4)	1	10	21.7	0.84 (4.59)	1.34 (2.95)
103H7823-0460	**103H7823-0430**	2.1 (297.4)	2	2.7	5.6	0.84 (4.59)	1.34 (2.95)
103H7823-0760	**103H7823-0730**	2.1 (297.4)	3	1.25	2.4	0.84 (4.59)	1.34 (2.95)

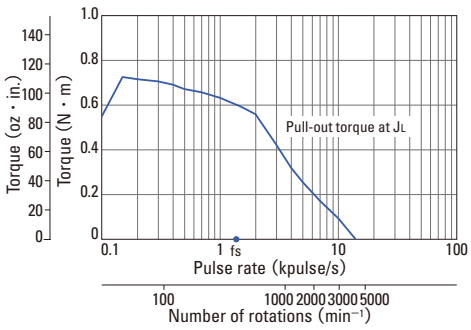
Characteristics diagram

103H7821-0140
103H7821-0110
103H7821-0160
103H7821-0130



Constant current circuit
Source voltage : DC24V · Operating current : 1A/phase,
2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7821-0440
103H7821-0410
103H7821-0460
103H7821-0430

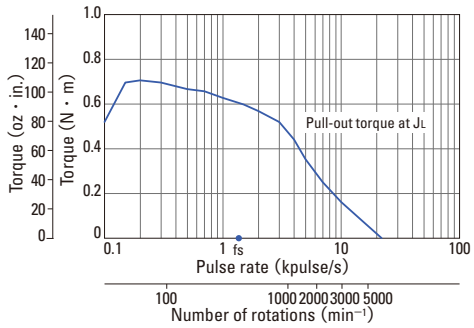


Constant current circuit
Source voltage : DC24V · Operating current : 2A/phase,
2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

Allowable Load · Internal Wiring · Rotation Direction ▶ P.56 General Specifications ▶ P.57 Motor Dimensions ▶ P.72 The data are measured under the trial conditions of SANYO DENKI.
Driving torque may vary according to actual machine precision.

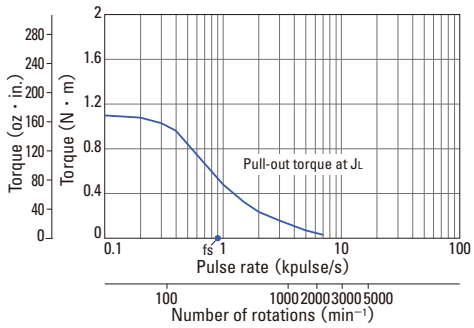
Characteristics diagram

103H7821-0740
103H7821-0710
103H7821-0760
103H7821-0730



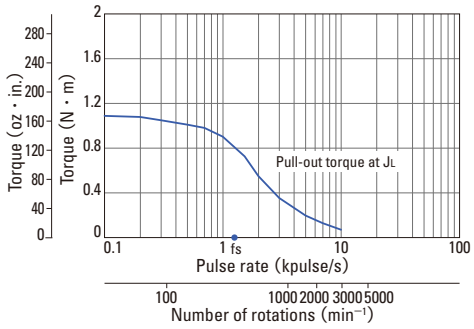
Constant current circuit
Source voltage : DC24V・Operating current : 3A/phase,
2-phase energization (full-step)
[J_L=[0.94 × 10^{-4}kg・m^2 (5.14 oz・in^2) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7822-0140
103H7822-0110
103H7822-0160
103H7822-0130



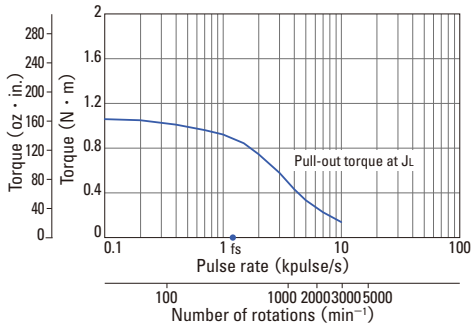
Constant current circuit
Source voltage : DC24V・Operating current : 1A/phase,
2-phase energization (full-step)
[J_L=7.4 × 10^{-4}kg・m^2 (40.46 oz・in^2) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7822-0440
103H7822-0410
103H7822-0460
103H7822-0430



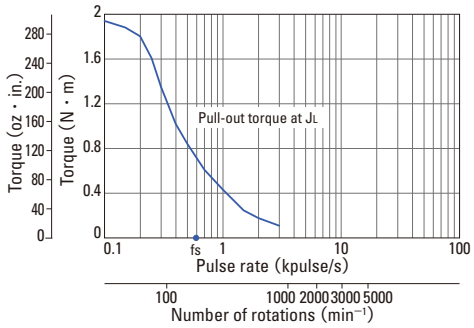
Constant current circuit
Source voltage : DC24V・Operating current : 2A/phase,
2-phase energization (full-step)
[J_L=7.4 × 10^{-4}kg・m^2 (40.46 oz・in^2) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7822-0740
103H7822-0710
103H7822-0760
103H7822-0730



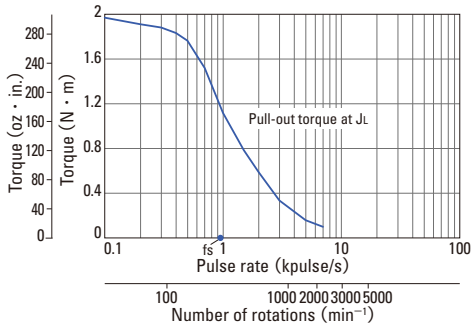
Constant current circuit
Source voltage : DC24V・Operating current : 3A/phase,
2-phase energization (full-step)
[J_L=7.4 × 10^{-4}kg・m^2 (40.46 oz・in^2) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7823-0140
103H7823-0110
103H7823-0160
103H7823-0130



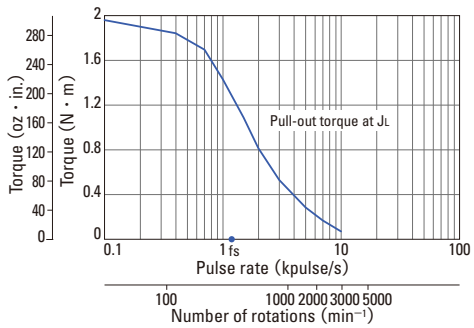
Constant current circuit
Source voltage : DC24V・Operating current : 1A/phase,
2-phase energization (full-step)
[J_L=7.4 × 10^{-4}kg・m^2 (40.46 oz・in^2) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7823-0440
103H7823-0410
103H7823-0460
103H7823-0430



Constant current circuit
Source voltage : DC24V・Operating current : 2A/phase,
2-phase energization (full-step)
[J_L=7.4 × 10^{-4}kg・m^2 (40.46 oz・in^2) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7823-0740
103H7823-0710
103H7823-0760
103H7823-0730



Constant current circuit
Source voltage : DC24V・Operating current : 3A/phase,
2-phase energization (full-step)
[J_L=7.4 × 10^{-4}kg・m^2 (40.46 oz・in^2) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

60 mm sq. (2.36 inch sq.)

1.8˚ /step

Unipolar winding · Connector type ▶ P.44
Unipolar winding · Lead wire type Dimensions for attaching NEMA23 are interchangeable (47.14 mm-pitch) ▶ P.44
Bipolar winding · Connector type
Bipolar winding · Lead wire type Dimensions for attaching NEMA23 are interchangeable (47.14 mm-pitch)

Bipolar winding • Connector type

Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
103H7821-5740	**103H7821-5710**	0.88 (124.6)	2	1.27	3.3	0.275 (1.50)	0.6 (1.32)
103H7821-1740	**103H7821-1710**	0.88 (124.6)	4	0.35	0.8	0.275 (1.50)	0.6 (1.32)
103H7822-5740	**103H7822-5710**	1.37 (194.0)	2	1.55	5.5	0.4 (2.19)	0.77 (1.70)
103H7822-1740	**103H7822-1710**	1.37 (194.0)	4	0.43	1.38	0.4 (2.19)	0.77 (1.70)
103H7823-5740	**103H7823-5710**	2.7 (382.3)	2	2.4	9.5	0.84 (4.59)	1.34 (2.95)
103H7823-1740	**103H7823-1710**	2.7 (382.3)	4	0.65	2.4	0.84 (4.59)	1.34 (2.95)

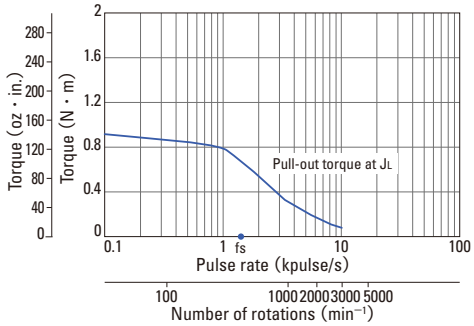
Motor cable : Model No. 4837961-1

Bipolar winding • Lead wire type Dimensions for attaching NEMA23 are interchangeable (47.14 mm-pitch)

Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
103H7821-5760	**103H7821-5730**	0.88 (124.6)	2	1.27	3.3	0.275 (1.50)	0.6 (1.32)
103H7821-1760	**103H7821-1730**	0.88 (124.6)	4	0.35	0.8	0.275 (1.50)	0.6 (1.32)
103H7822-5760	**103H7822-5730**	1.37 (194.0)	2	1.55	5.5	0.4 (2.19)	0.77 (1.70)
103H7822-1760	**103H7822-1730**	1.37 (194.0)	4	0.43	1.38	0.4 (2.19)	0.77 (1.70)
103H7823-5760	**103H7823-5730**	2.7 (382.3)	2	2.4	9.5	0.84 (4.59)	1.34 (2.95)
103H7823-1760	**103H7823-1730**	2.7 (382.3)	4	0.65	2.4	0.84 (4.59)	1.34 (2.95)

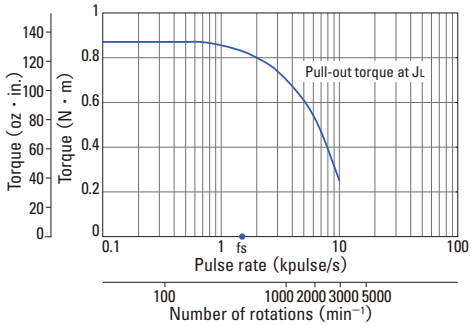
Characteristics diagram

103H7821-5740
103H7821-5710
103H7821-5760
103H7821-5730



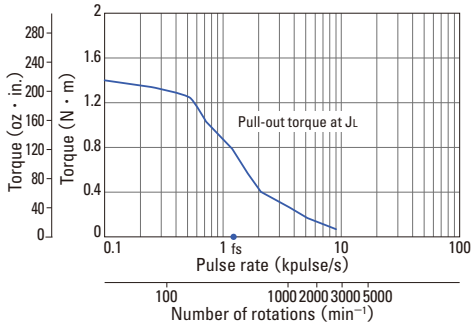
Constant current circuit
Source voltage : DC24V · Operating current : 2A/phase, 2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg · m² (14.22 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7821-1740
103H7821-1710
103H7821-1760
103H7821-1730



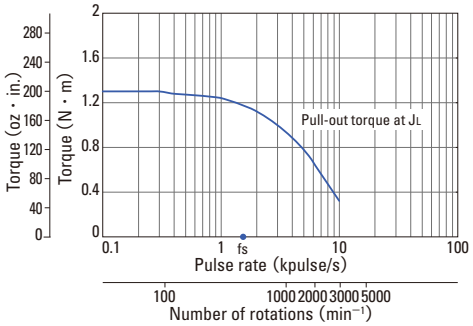
Constant current circuit
Source voltage : AC100V · operating current : 4A/phase, 2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg · m² (14.22 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7822-5740
103H7822-5710
103H7822-5760
103H7822-5730



Constant current circuit
Source voltage : DC24V · Operating current : 2A/phase, 2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg · m² (14.22 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7822-1740
103H7822-1710
103H7822-1760
103H7822-1730

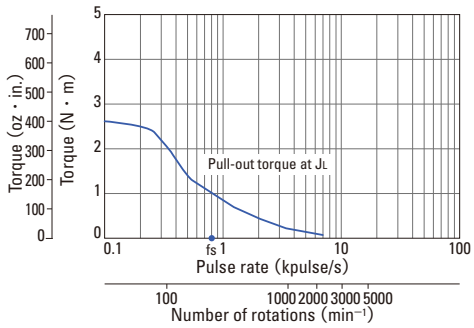


Constant current circuit
Source voltage : AC100V · operating current : 4A/phase, 2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg · m² (14.22 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

Allowable Load · Internal Wiring · Rotation Direction ▶ P.56 General Specifications ▶ P.57 Motor Dimensions ▶ P.72 The data are measured under the trial conditions of SANYO DENKI.
Driving torque may vary according to actual machine precision.

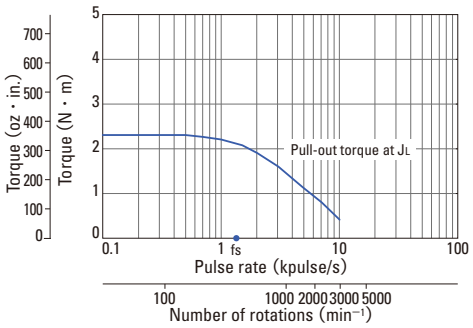
Characteristics diagram

103H7823-5740
103H7823-5710
103H7823-5760
103H7823-5730



Constant current circuit
Source voltage : DC24V · Operating current : 2A/phase,
2-phase energization (full-step)
[J_L=7.4 × 10^{-4}kg · m^2 (40.46 oz · in^2) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7823-1740
103H7823-1710
103H7823-1760
103H7823-1730



Constant current circuit
Source voltage : AC100V · operating current : 4A/phase,
2-phase energization (full-step)
[J_L=7.4 × 10^{-4}kg · m^2 (40.46 oz · in^2) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

86 mm sq. (3.39 inch sq.)

1.8˚ /step

Unipolar winding · Lead wire type
Unipolar winding · Lead wire type CE · UL model
Bipolar winding · Lead wire type ▶ P.50
Bipolar winding · Lead wire type CE · UL model ▶ P.50
Bipolar winding · Terminal block type CE · UL model ▶ P.50

Unipolar winding • Lead wire type

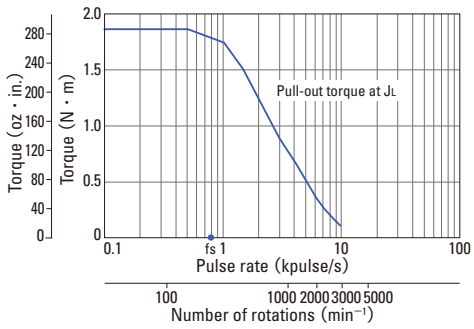
Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
SH2861-0441	**SH2861-0411**	2.5 (354)	2	2.3	8.0	1.48 (8.09)	1.75 (3.92)
SH2861-0941	**SH2861-0911**	2.5 (354)	4	0.6	2.0	1.48 (8.09)	1.75 (3.92)
SH2862-0441	**SH2862-0411**	4.7 (665.6)	2	3.2	13.0	3.0 (16.4)	2.9 (6.5)
SH2862-0941	**SH2862-0911**	4.7 (665.6)	4	0.85	3.4	3.0 (16.4)	2.9 (6.5)
SH2863-0441	**SH2863-0411**	6.7 (948.8)	2	4.0	17.0	4.5 (24.6)	4.0 (8.96)
SH2863-0941	**SH2863-0911**	6.7 (948.8)	4	0.9	4.2	4.5 (24.6)	4.0 (8.96)

Unipolar winding • Lead wire type CE • UL model

Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
SM2861-0451	**SM2861-0421**	2.5 (354)	2	2.3	8.0	1.48 (8.09)	1.75 (3.92)
SM2861-0951	**SM2861-0921**	2.5 (354)	4	0.6	2.0	1.48 (8.09)	1.75 (3.92)
SM2862-0451	**SM2862-0421**	4.7 (665.6)	2	3.2	13.0	3.0 (16.4)	2.9 (6.5)
SM2862-0951	**SM2862-0921**	4.7 (665.6)	4	0.85	3.4	3.0 (16.4)	2.9 (6.5)
SM2863-0451	**SM2863-0421**	6.7 (948.8)	2	4.0	17.0	4.5 (24.6)	4.0 (8.96)
SM2863-0951	**SM2863-0921**	6.7 (948.8)	4	0.9	4.2	4.5 (24.6)	4.0 (8.96)

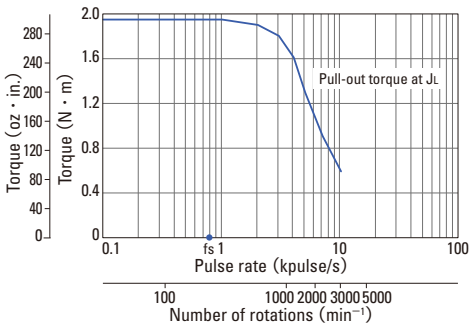
Characteristics diagram

SH2861-0441
SH2861-0411
SM2861-0451
SM2861-0421



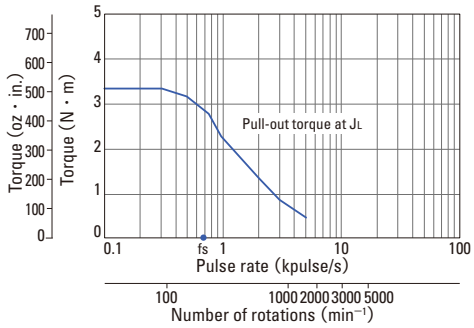
Constant current circuit
Source voltage : AC100V · operating current : 2A/phase, 2-phase energization (full-step)
[JL=7.4 × 10⁻⁴kg · m² (40.46 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SH2861-0941
SH2861-0911
SM2861-0951
SM2861-0921



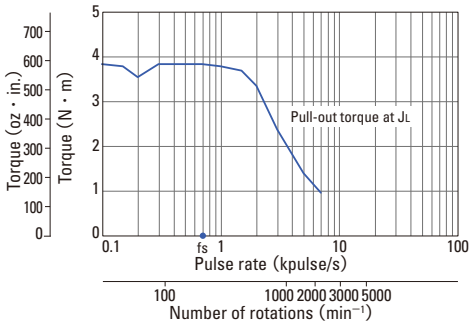
Constant current circuit
Source voltage : AC100V · operating current : 4A/phase, 2-phase energization (full-step)
[JL=7.4 × 10⁻⁴kg · m² (40.46 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SH2862-0441
SH2862-0411
SM2862-0451
SM2862-0421



Constant current circuit
Source voltage : AC100V · operating current : 2A/phase, 2-phase energization (full-step)
JL=[15.3 × 10⁻⁴kg · m² (83.65 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SH2862-0941
SH2862-0911
SM2862-0951
SM2862-0921

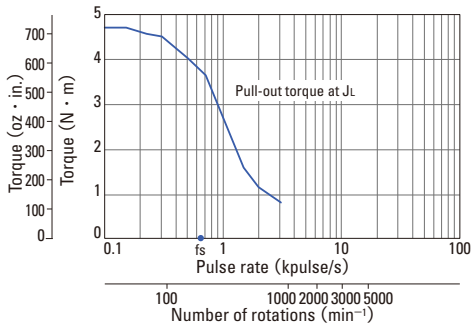


Constant current circuit
Source voltage : AC100V · operating current : 4A/phase, 2-phase energization (full-step)
JL=[15.3 × 10⁻⁴kg · m² (83.65 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

Allowable Load · Internal Wiring · Rotation Direction ▶ P.56 General Specifications ▶ P.57 Motor Dimensions ▶ P.73 The data are measured under the trial conditions of SANYO DENKI.
Driving torque may vary according to actual machine precision.

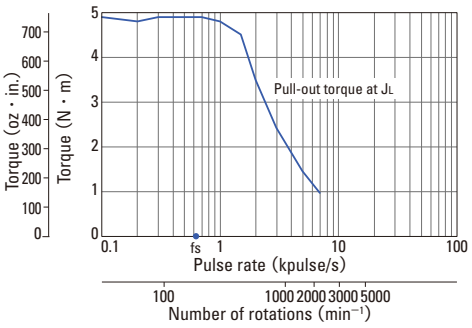
Characteristics diagram

SH2863-0441
SH2863-0411
SM2863-0451
SM2863-0421



Constant current circuit
Source voltage : AC100V · operating current : 2A/phase,
2-phase energization (full-step)
J_L=[15.3 × 10^{-4}kg · m^2 (83.65 oz · in^2) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SH2863-0941
SH2863-0911
SM2863-0951
SM2863-0921



Constant current circuit
Source voltage : AC100V · operating current : 4A/phase,
2-phase energization (full-step)
J_L=[15.3 × 10^{-4}kg · m^2 (83.65 oz · in^2) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

86 mm sq. (3.39 inch sq.)

1.8˚ /step

Unipolar winding · Lead wire type ▶ P.48
Unipolar winding · Lead wire type CE · UL model ▶ P.48
Bipolar winding · Lead wire type
Bipolar winding · Lead wire type CE · UL model
Bipolar winding · Terminal block type CE · UL model

Bipolar winding • Lead wire type

Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
SH2861-5041	**SH2861-5011**	3.3 (467.3)	2	2.2	15	1.48 (8.09)	1.75 (3.92)
SH2861-5141	**SH2861-5111**	3.3 (467.3)	4	0.56	3.7	1.48 (8.09)	1.75 (3.92)
SH2861-5241	**SH2861-5211**	3.3 (467.3)	6	0.29	1.7	1.48 (8.09)	1.75 (3.92)
SH2862-5041	**SH2862-5011**	6.4 (906.3)	2	3.2	25	3.0 (16.4)	2.9 (6.5)
SH2862-5141	**SH2862-5111**	6.4 (906.3)	4	0.83	6.4	3.0 (16.4)	2.9 (6.5)
SH2862-5241	**SH2862-5211**	6.4 (906.3)	6	0.36	2.8	3.0 (16.4)	2.9 (6.5)
SH2863-5041	**SH2863-5011**	9 (1274.4)	2	4.0	32	4.5 (24.6)	4.0 (8.96)
SH2863-5141	**SH2863-5111**	9 (1274.4)	4	1.0	7.9	4.5 (24.6)	4.0 (8.96)
SH2863-5241	**SH2863-5211**	9 (1274.4)	6	0.46	3.8	4.5 (24.6)	4.0 (8.96)

Bipolar winding • Lead wire type CE • UL model

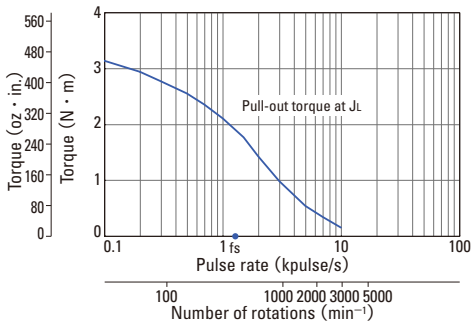
Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
SM2861-5051	**SM2861-5021**	3.3 (467.3)	2	2.2	15	1.48 (8.09)	1.75 (3.92)
SM2861-5151	**SM2861-5121**	3.3 (467.3)	4	0.56	3.7	1.48 (8.09)	1.75 (3.92)
SM2861-5251	**SM2861-5221**	3.3 (467.3)	6	0.29	1.7	1.48 (8.09)	1.75 (3.92)
SM2862-5051	**SM2862-5021**	6.4 (906.3)	2	3.2	25	3.0 (16.4)	2.9 (6.5)
SM2862-5151	**SM2862-5121**	6.4 (906.3)	4	0.83	6.4	3.0 (16.4)	2.9 (6.5)
SM2862-5251	**SM2862-5221**	6.4 (906.3)	6	0.36	2.8	3.0 (16.4)	2.9 (6.5)
SM2863-5051	**SM2863-5021**	9 (1274.4)	2	4.0	32	4.5 (24.6)	4.0 (8.96)
SM2863-5151	**SM2863-5121**	9 (1274.4)	4	1.0	7.9	4.5 (24.6)	4.0 (8.96)
SM2863-5251	**SM2863-5221**	9 (1274.4)	6	0.46	3.8	4.5 (24.6)	4.0 (8.96)

Bipolar winding • Terminal block type CE • UL model

Model number	Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
SM2861-5066	3.3 (467.3)	2	2.03	15	1.48 (8.09)	1.9 (4.19)
SM2861-5166	3.3 (467.3)	4	0.52	3.7	1.48 (8.09)	1.9 (4.19)
SM2861-5266	3.3 (467.3)	6	0.27	1.7	1.48 (8.09)	1.9 (4.19)
SM2862-5066	6.4 (906.3)	2	3.08	25	3.0 (16.4)	3.05 (6.72)
SM2862-5166	6.4 (906.3)	4	0.79	6.4	3.0 (16.4)	3.05 (6.72)
SM2862-5266	6.4 (906.3)	6	0.33	2.8	3.0 (16.4)	3.05 (6.72)
SM2863-5066	9 (1274.4)	2	3.83	32	4.5 (24.6)	4.15 (9.15)
SM2863-5166	9 (1274.4)	4	0.96	7.9	4.5 (24.6)	4.15 (9.15)
SM2863-5266	9 (1274.4)	6	0.48	3.8	4.5 (24.6)	4.15 (9.15)

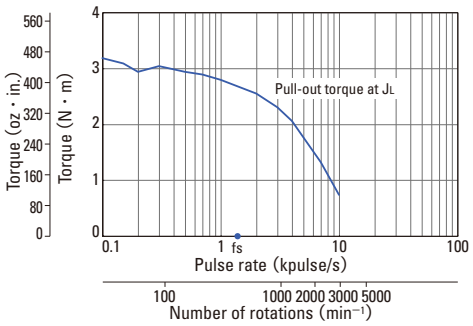
Characteristics diagram

SH2861-5041
SH2861-5011
SM2861-5051
SM2861-5021
SM2861-5066



Constant current circuit
Source voltage : AC100V · operating current : 2A/phase,
2-phase energization (full-step)
[JL=15.3 × 10⁻⁴kg · m² (83.65 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SH2861-5141
SH2861-5111
SM2861-5151
SM2861-5121
SM2861-5166

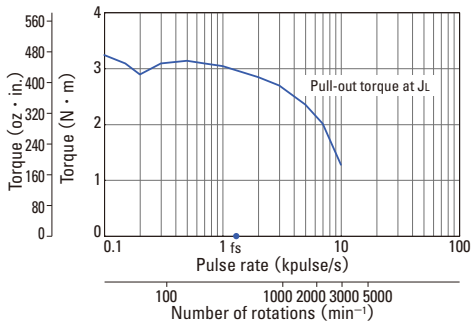


Constant current circuit
Source voltage : AC100V · operating current : 4A/phase,
2-phase energization (full-step)
[JL=15.3 × 10⁻⁴kg · m² (83.65 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

Allowable Load · Internal Wiring · Rotation Direction ▶ P.56 General Specifications ▶ P.57 Motor Dimensions ▶ P.73 The data are measured under the trial conditions of SANYO DENKI.
Driving torque may vary according to actual machine precision.

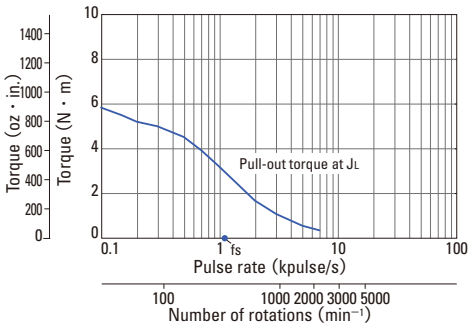
Characteristics diagram

SH2861-5241
SH2861-5211
SM2861-5251
SM2861-5221
SM2861-5266



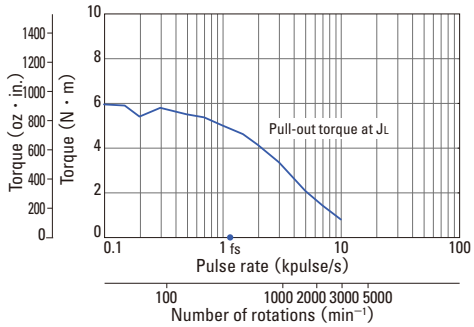
Constant current circuit
Source voltage : AC100V · operating current : 6A/phase, 2-phase energization (full-step)
J_L=[15.3 × 10⁻⁴kg · m² (83.65 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SH2862-5041
SH2862-5011
SM2862-5051
SM2862-5021
SM2862-5066



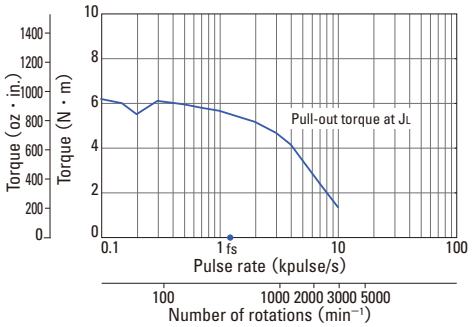
Constant current circuit
Source voltage : AC100V · operating current : 2A/phase, 2-phase energization (full-step)
J_L=[15.3 × 10⁻⁴kg · m² (83.65 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SH2862-5141
SH2862-5111
SM2862-5151
SM2862-5121
SM2862-5166



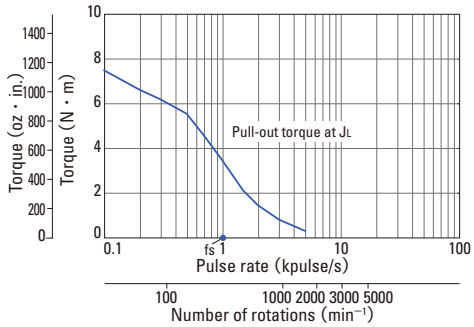
Constant current circuit
Source voltage : AC100V · operating current : 4A/phase, 2-phase energization (full-step)
J_L=[15.3 × 10⁻⁴kg · m² (83.65 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SH2862-5241
SH2862-5211
SM2862-5251
SM2862-5221
SM2862-5266



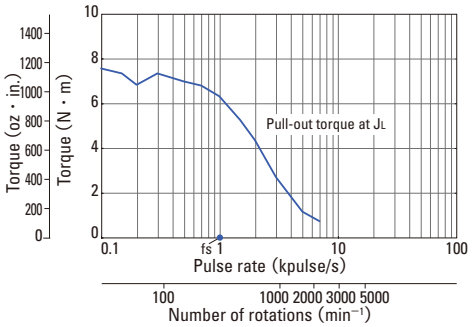
Constant current circuit
Source voltage : AC100V · operating current : 6A/phase, 2-phase energization (full-step)
J_L=[15.3 × 10⁻⁴kg · m² (83.65 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SH2863-5041
SH2863-5011
SM2863-5051
SM2863-5021
SM2863-5066



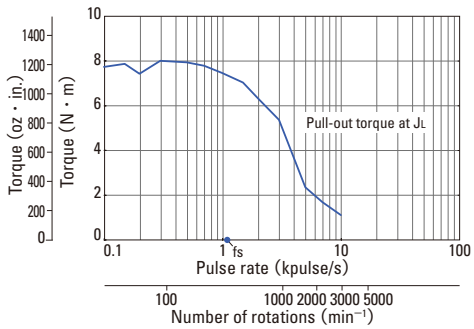
Constant current circuit
Source voltage : AC100V · operating current : 2A/phase, 2-phase energization (full-step)
J_L=[44 × 10⁻⁴kg · m² (240.56 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SH2863-5141
SH2863-5111
SM2863-5151
SM2863-5121
SM2863-5166



Constant current circuit
Source voltage : AC100V · operating current : 4A/phase, 2-phase energization (full-step)
J_L=[44 × 10⁻⁴kg · m² (240.56 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SH2863-5241
SH2863-5211
SM2863-5251
SM2863-5221
SM2863-5266



Constant current circuit
Source voltage : AC100V · operating current : 6A/phase, 2-phase energization (full-step)
J_L=[44 × 10⁻⁴kg · m² (240.56 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

ϕ106 mm (ϕ4.17 inch)

1.8˚ /step

Unipolar winding · Lead wire type
Bipolar winding · Lead wire type

Unipolar winding • Lead wire type

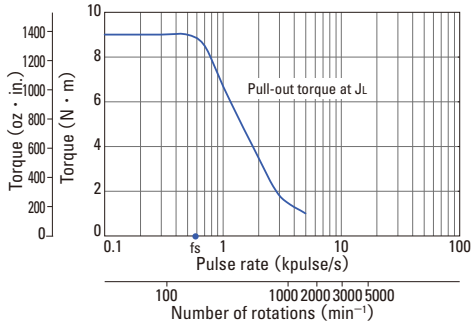
Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
103H89222-0941	**103H89222-0911**	10.8 (1529.4)	4	0.98	6.3	14.6 (79.83)	7.5 (16.53)
103H89223-0941	**103H89223-0911**	15.5 (2194.9)	4	1.4	9.7	22 (120.28)	10.5 (23.15)

Bipolar winding • Lead wire type

Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
103H89222-5241	**103H89222-5211**	13.2 (1869.2)	6	0.45	5.4	14.6 (79.83)	7.5 (16.53)
103H89223-5241	**103H89223-5211**	19 (2690.5)	6	0.63	8	22 (120.28)	10.5 (23.15)

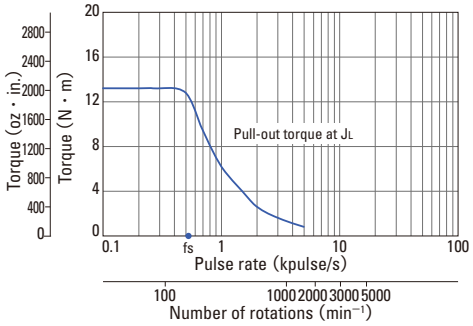
Characteristics diagram

103H89222-0941
103H89222-0911



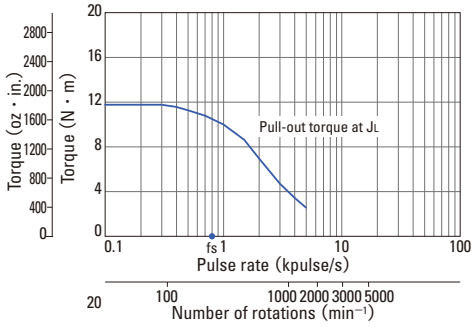
Constant current circuit
Source voltage : AC100V · operating current : 4A/phase, 2-phase energization (full-step)
J_L=[44 × 10⁻⁴kg · m² (240.56 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H89223-0941
103H89223-0911



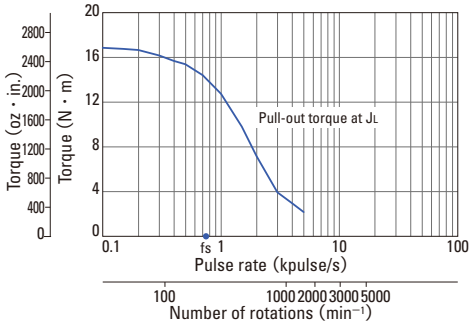
Constant current circuit
Source voltage : AC100V · operating current : 4A/phase, 2-phase energization (full-step)
J_L=[44 × 10⁻⁴kg · m² (240.56 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H89222-5241
103H89222-5211



Constant current circuit
Source voltage : AC100V · operating current : 6A/phase, 2-phase energization (full-step)
J_L=[44 × 10⁻⁴kg · m² (240.56 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H89223-5241
103H89223-5211



Constant current circuit
Source voltage : AC100V · operating current : 6A/phase, 2-phase energization (full-step)
J_L=[44 × 10⁻⁴kg · m² (240.56 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

Allowable Load · Internal Wiring · Rotation Direction ▶ P.56 General Specifications ▶ P.57 Motor Dimensions ▶ P.74 The data are measured under the trial conditions of SANYO DENKI.
Driving torque may vary according to actual machine precision.

56 mm sq. (2.20 inch sq.)

1.8˚ /step

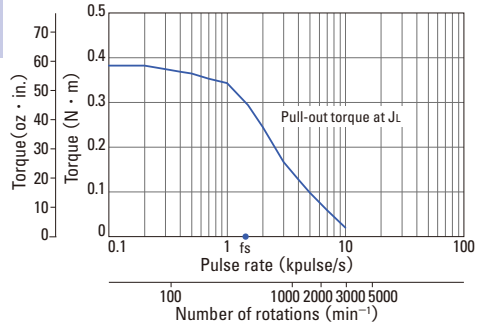
Unipolar winding · CE Model

Unipolar winding • CE Model

Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
103H7121-6140	**103H7121-6110**	0.39 (55.2)	1	4.8	8	0.1 (0.55)	0.47 (1.04)
103H7121-6740	**103H7121-6710**	0.39 (55.2)	3	0.6	0.8	0.1 (0.55)	0.47 (1.04)
103H7123-6140	**103H7123-6110**	0.83 (117.5)	1	6.7	15	0.21 (1.15)	0.65 (1.43)
103H7123-6740	**103H7123-6710**	0.78 (110.5)	3	0.77	1.58	0.21 (1.15)	0.65 (1.43)
103H7126-6140	**103H7126-6110**	1.27 (179.8)	1	8.6	19	0.36 (1.97)	0.98 (2.16)
103H7126-6740	**103H7126-6710**	1.27 (179.8)	3	0.9	2.2	0.36 (1.97)	0.98 (2.16)

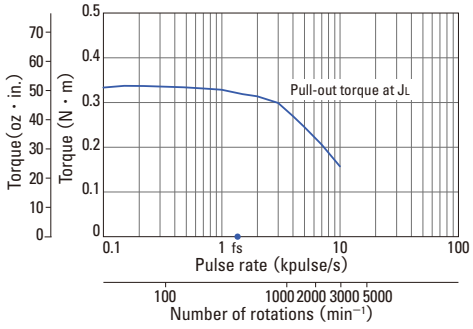
Characteristics diagram

103H7121-6140
103H7121-6110



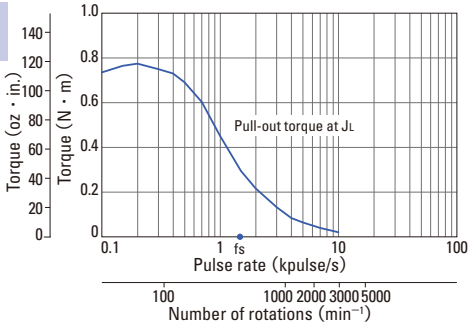
Constant current circuit
Source voltage : DC24V · Operating current : 1A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7121-6740
103H7121-6710



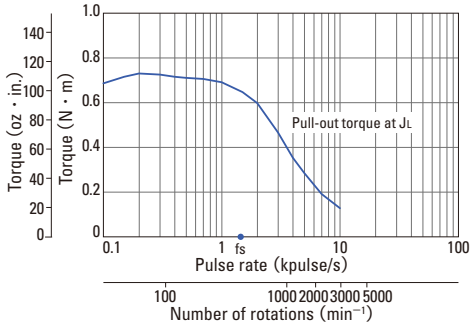
Constant current circuit
Source voltage : DC24V · Operating current : 3A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7123-6140
103H7123-6110



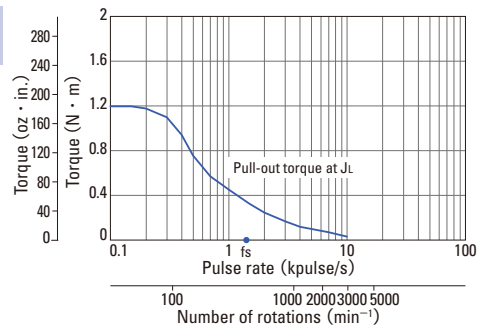
Constant current circuit
Source voltage : DC24V · Operating current : 1A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7123-6740
103H7123-6710



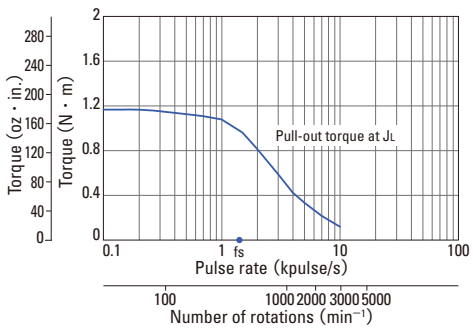
Constant current circuit
Source voltage : DC24V · Operating current : 3A/phase, 2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg · m² (5.14 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7126-6140
103H7126-6110



Constant current circuit
Source voltage : DC24V · Operating current : 1A/phase, 2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg · m² (14.22 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H7126-6740
103H7126-6710



Constant current circuit
Source voltage : DC24V · Operating current : 3A/phase, 2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg · m² (14.22 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

ϕ86 mm (ϕ3.39 inch)

1.8˚ /step

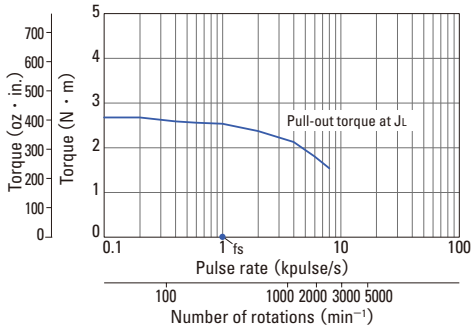
Bipolar winding · CE Model

Bipolar winding • CE Model

Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
103H8221-6240	**103H8221-6210**	2.74 (388)	6	0.3	1.65	1.45 (7.93)	1.5 (3.31)
103H8222-6340	**103H8222-6310**	5.09 (720.8)	6	0.35	2.7	2.9 (15.86)	2.5 (5.51)
103H8223-6340	**103H8223-6310**	7.44 (1053.6)	6	0.45	3.4	4.4 (24.06)	3.5 (7.72)

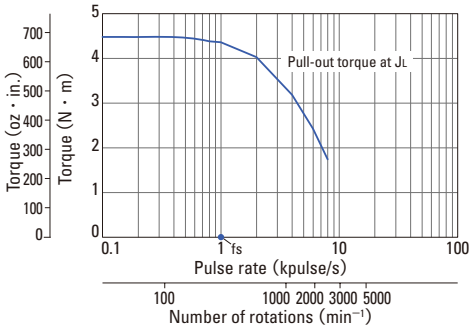
Characteristics diagram

103H8221-6240
103H8221-6210



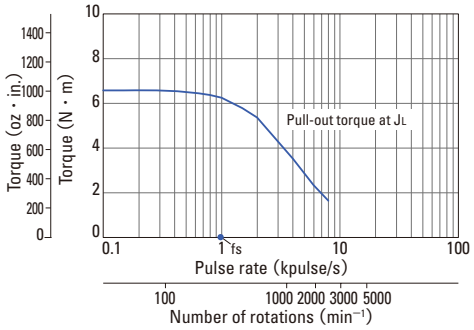
Constant current circuit
Source voltage : AC100V · operating current : 6A/phase, 2-phase energization (full-step)
[J_L=7.4 × 10⁻⁴kg · m² (40.46 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H8222-6340
103H8222-6310



Constant current circuit
Source voltage : AC100V · operating current : 6A/phase, 2-phase energization (full-step)
J_L=[15.3 × 10⁻⁴kg · m² (83.65 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H8223-6340
103H8223-6310



Constant current circuit
Source voltage : AC100V · operating current : 6A/phase, 2-phase energization (full-step)
J_L=[44 × 10⁻⁴kg · m² (240.56 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

ϕ106 mm (ϕ4.17 inch)

1.8˚ /step

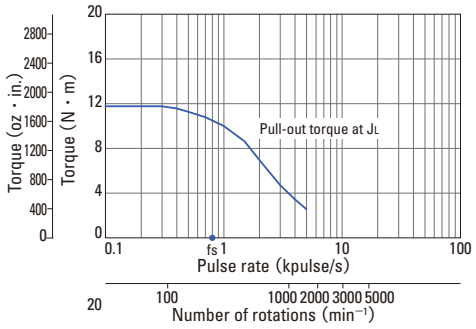
Bipolar winding · CE Model

Bipolar winding • CE Model

Model number		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Dual shaft	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴kg · m² (oz · in²)]	[kg (lbs)]
103H89222-6341	**103H89222-6311**	13.2 (1869.2)	6	0.45	5.4	14.6 (79.83)	7.5 (16.53)
103H89223-6341	**103H89223-6311**	19 (2690.5)	6	0.63	8	22 (120.28)	10.5 (23.15)

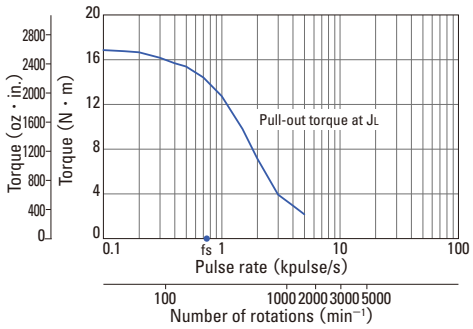
Characteristics diagram

103H89222-6341
103H89222-6311



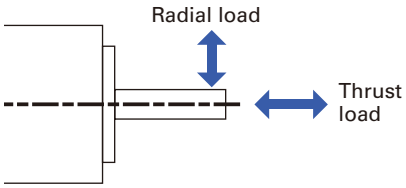
Constant current circuit
Source voltage : AC100V · operating current : 6A/phase,
2-phase energization (full-step)
J_L=[44 × 10⁻⁴kg · m² (240.56 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

103H89223-6341
103H89223-6311



Constant current circuit
Source voltage : AC100V · operating current : 6A/phase,
2-phase energization (full-step)
J_L=[44 × 10⁻⁴kg · m² (240.56 oz · in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

Allowable Radial / Thrust Load



Flange size	Model number	Distance from end of shaft : mm (in)				Thrust load N (lbs)
		0	5	10	15	
		Radial load : N (lbs)				
14 mm sq. (0.55 in sq.)	SH2141	10 (2.25)	11 (2.47)	13 (2.92)	-	0.7 (0.16)
28 mm sq.(1.10 in sq.)	SH228 □	42 (9)	48 (10)	56 (12)	66 (14)	3 (0.67)
35 mm sq.(1.38 in sq.)	SH353 □	40 (8)	50 (11)	67 (15)	98 (22)	10 (2.25)
42 mm sq.(1.65 in sq.)	103H52 □□ SH142 □	22 (4)	26 (5)	33 (7)	46 (10)	10 (2.25)
50 mm sq.(1.97 in sq.)	103H670 □	71 (15)	87 (19)	115 (25)	167 (37)	15 (3.37)
56 mm sq.(2.20 in sq.)	103H712 □	52 (11)	65 (14)	85 (19)	123 (27)	15 (3.37)
	103H7128	85 (19)	105 (23)	138 (31)	200 (44)	15 (3.37)
60 mm sq.(2.36 in sq.)	103H782 □	70 (15)	87 (19)	114 (25)	165 (37)	20 (4.50)
	SH160 □					15 (3.37)
86 mm sq.(3.39 in sq.)	SM286 □ SH286 □	167 (37)	193 (43)	229 (51)	280 (62)	60 (13.488)
86 mm sq.(3.39 in sq.)	103H822 □	191 (43)	234 (53)	301 (68)	421 (95)	60 (13.488)
ϕ106 mm (ϕ4.17 in)	103H8922 □	321 (72)	356 (79)	401 (90)	457 (101)	100 (22.48)

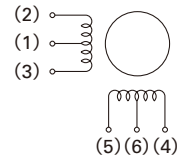
Internal Wiring and Rotation Direction

Unipolar winding

103H52 □□ Connector type

Internal wire connection

( ) connector pin number



Direction of motor rotation

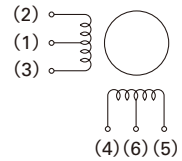
The output shaft shall rotate clockwise as seen from the shaft side, when excited by DC in the following order.

		Connector pin number				
		(1.6)	(5)	(3)	(4)	(2)
Exciting order	1	+	–	–		
	2	+		–	–	
	3	+			–	–
	4	+	–			–

103H782 □□ Connector type

Internal wire connection

( ) connector pin number



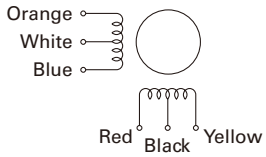
Direction of motor rotation

The output shaft shall rotate clockwise as seen from the shaft side, when excited by DC in the following order.

		Connector pin number				
		(1.6)	(4)	(3)	(5)	(2)
Exciting order	1	+	–	–		
	2	+		–	–	
	3	+			–	–
	4	+	–			–

Lead wire type

Internal wire connection



Direction of motor rotation

The output shaft shall rotate clockwise as seen from the shaft side, when excited by DC in the following order.

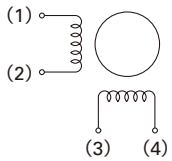
		Lead wire color				
		White & black	Red	Blue	Yellow	Orange
Exciting order	1	+	–	–		
	2	+		–	–	
	3	+			–	–
	4	+	–			–

Bipolar winding

Connector type

Internal wire connection

( ) connector pin number, terminal block number



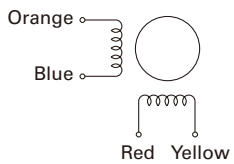
Direction of motor rotation

The output shaft shall rotate clockwise as seen from the shaft side, when excited by DC in the following order.

		Connector pin number, terminal block number			
		(3)	(2)	(4)	(1)
Exciting order	1	–	–	+	+
	2	+	–	–	+
	3	+	+	–	–
	4	–	+	+	–

Lead wire type

Internal wire connection



Direction of motor rotation

The output shaft shall rotate clockwise as seen from the shaft side, when excited by DC in the following order.

		Lead wire color			
		Red	Blue	Yellow	Orange
Exciting order	1	–	–	+	+
	2	+	–	–	+
	3	+	+	–	–
	4	–	+	+	–

General Specifications

Motor model number	SH2141	SH228 □	SH353 □	SS242 □	SH142 □	103H52 □□	SS250 □	103H67 □□	103H712 □
Type	—								
Operating ambient temperature	− 10℃ to + 50℃								
Conversation temperature	− 20℃ to + 65℃								
Operating ambient humidity	20 to 90% RH (no condensation)								
Conversation humidity	5 to 95% RH (no condensation)								
Operation altitude	1000m (3280 feet) MAX above sea level								
Vibration resistance	Vibration frequency 10 to 500 Hz, total amplitude 1.52 mm (10 to 70 Hz), vibration acceleration 147m/s² (70 to 500 Hz), sweep time 15 min/cycle, 12 sweeps in each X, Y and Z direction.								
Impact resistance	490m/s² of acceleration for 11 ms with half-sine wave applying three times for X, Y, and Z axes each, 18 times in total.								
Insulation class	Class B (+130℃)								
Withstand voltage	At normal temperature and humidity, no failure with 500 V AC @50/60 Hz applied for one minute between motor winding and frame.								At normal temperature and humidity, no failure with 1000 V AC @50/60 Hz applied for one minute between motor winding and frame.
Insulation resistance	At normal temperature and humidity, not less then 100MΩ between winding and frame by DC500V megger.								
Protection grade	IP40								
Winding temperature rise	80K MAX. (Based on Sanyo Denki standard)								
Static angle error	± 0.09°				± 0.054°	± 0.09°			
Axial play *1	0.075 mm (0.003 in) MAX. (load: 0.35N (0.08 lbs))	0.075 mm (0.003 in) MAX. (load: 1.5N (0.34 lbs))	0.075 mm (0.003 in) MAX. (load: 5N (1.12 lbs))	0.075 mm (0.003 in) MAX. (load: 4N (0.9 lbs))	0.075 mm (0.003 in) MAX. (load: 5N (1.12 lbs))	0.075 mm (0.003 in) (load: 5N (1.12 lbs))	0.075 mm (0.003 in) MAX. (load: 4N (0.9 lbs))	0.075 mm (0.003 in) (load: 10N (2.25 lbs))	0.075 mm (0.003 in) (load: 10N (2.25 lbs))
Radial play *2	0.025 mm (0.001 in) MAX. (load: 5N (1.12 lbs))								
Shaft runout	0.025 mm (0.001 in)								
Concentricity of mounting pilot relative to shaft	ϕ 0.05 mm (ϕ 0.002 in)	ϕ 0.05 mm (ϕ 0.002 in)	ϕ 0.075 mm (ϕ 0.003 in)	ϕ 0.075 mm (ϕ 0.003 in)	ϕ 0.05 mm (ϕ 0.002 in)	ϕ 0.05 mm (ϕ 0.002 in)	ϕ 0.075 mm (ϕ 0.003 in)	ϕ 0.075 mm (ϕ 0.003 in)	ϕ 0.075 mm (ϕ 0.003 in)
Squareness of mounting surface relative to shaft	0.1 mm (0.004 in)	0.1 mm (0.004 in)	0.1 mm (0.004 in)	0.1 mm (0.004 in)	0.1 mm (0.004 in)	0.1 mm (0.004 in)	0.1 mm (0.004 in)	0.075 mm (0.003 in)	0.075 mm (0.003 in)

Motor model number	SH160 □	103H78 □□	SH286 □	103H8922 □	SM286 □	103H712 □ -6 □□ 0 CE Model	103H822 □ -6 □□ 0 CE Model	103H8922 □ -63 □ 1 CE Model
Type	—				S1 (continuous operation)			
Operating ambient temperature	− 10℃ to + 50℃				− 10℃ to + 40℃			
Conversation temperature	− 20℃ to + 65℃				− 20℃ to + 60℃			
Operating ambient humidity	20 to 90% RH (no condensation)				95%MAX. : 40℃ MAX., 57%MAX. : 50℃ MAX., 35%MAX. : 60℃ MAX. (no condensation)			
Conversation humidity	5 to 95% RH (no condensation)							
Operation altitude	1000m (3280 feet) MAX above sea level							
Vibration resistance	Vibration frequency 10 to 500 Hz, total amplitude 1.52 mm (10 to 70 Hz), vibration acceleration 147m/s² (70 to 500 Hz), sweep time 15 min/cycle, 12 sweeps in each X, Y and Z direction.							
Impact resistance	490m/s² of acceleration for 11 ms with half-sine wave applying three times for X, Y and Z axes each, 18 times in total.							
Insulation class	Class B (+130℃)				Class F (+155℃)	Class B (+130℃)		
Withstand voltage	At normal temperature and humidity, no failure with 1000 V AC @50/60 Hz applied for one minute between motor winding and frame.			At normal temperature and humidity, no failure with 1500 V AC @50/60 Hz applied for one minute between motor winding and frame.				
Insulation resistance	At normal temperature and humidity, not less then 100MΩ between winding and frame by DC500V megger.							
Protection grade	IP40				IP43			
Winding temperature rise	80K MAX. (Based on Sanyo Denki standard)							
Static angle error	± 0.054°	± 0.09°						
Axial play *1	0.075 mm (0.003 in) MAX. (load: 10N (2.25 lbs))							
Radial play *2	0.025 mm (0.001 in) (load: 5N (1.12 lbs))	0.025 mm (0.001 in) (load: 5N (1.12 lbs))	0.025 mm (0.001 in) (load: 5N (1.12 lbs))	0.025 mm (0.001 in) (load: 10N (2.25 lbs))	0.025 mm (0.001 in) (load: 5N (1.12 lbs))	0.025 mm (0.001 in) (load: 5N (1.12 lbs))	0.025 mm (0.001 in) (load: 5N (1.12 lbs))	0.025 mm (0.001 in) (load: 10N (2.25 lbs))
Shaft runout	0.025 mm (0.001 in)							
Concentricity of mounting pilot relative to shaft	ϕ 0.075 mm (ϕ 0.003 in)							
Squareness of mounting surface relative to shaft	0.1 mm (0.004 in)	0.075 mm (0.003 in)	0.15 mm (0.006 in)	0.1 mm (0.004 in)	0.15 mm (0.006 in)	0.075 mm (0.003 in)	0.1 mm (0.004 in)	0.1 mm (0.004 in)

*1 Axial play: Shaft displacement under axial load.
*2 Radial play: Shaft displacement under radial load applied 1/3rd of the length from the end of the shaft.

Safety standards

Model Number: SM286 □ CE • UL marked models

CE (TÜV)	Standard category		Standard part
	Low-voltage directives		EN60034-1, EN60034-5
UL	Acquired standards	Standard part	File No.
	UL	UL1004-1	E179832
	UL for Canada		

Model Number: 103H712 □ -6 □□ 0, 103H822 □ -6 □□ 0, 103H8922 □ -63 □ 1 CE marked model

CE (TÜV)	Standard category	Standard part
	Low-voltage directives	EN60034-1, EN60034-5

Stepping Motors with Integrated Drivers

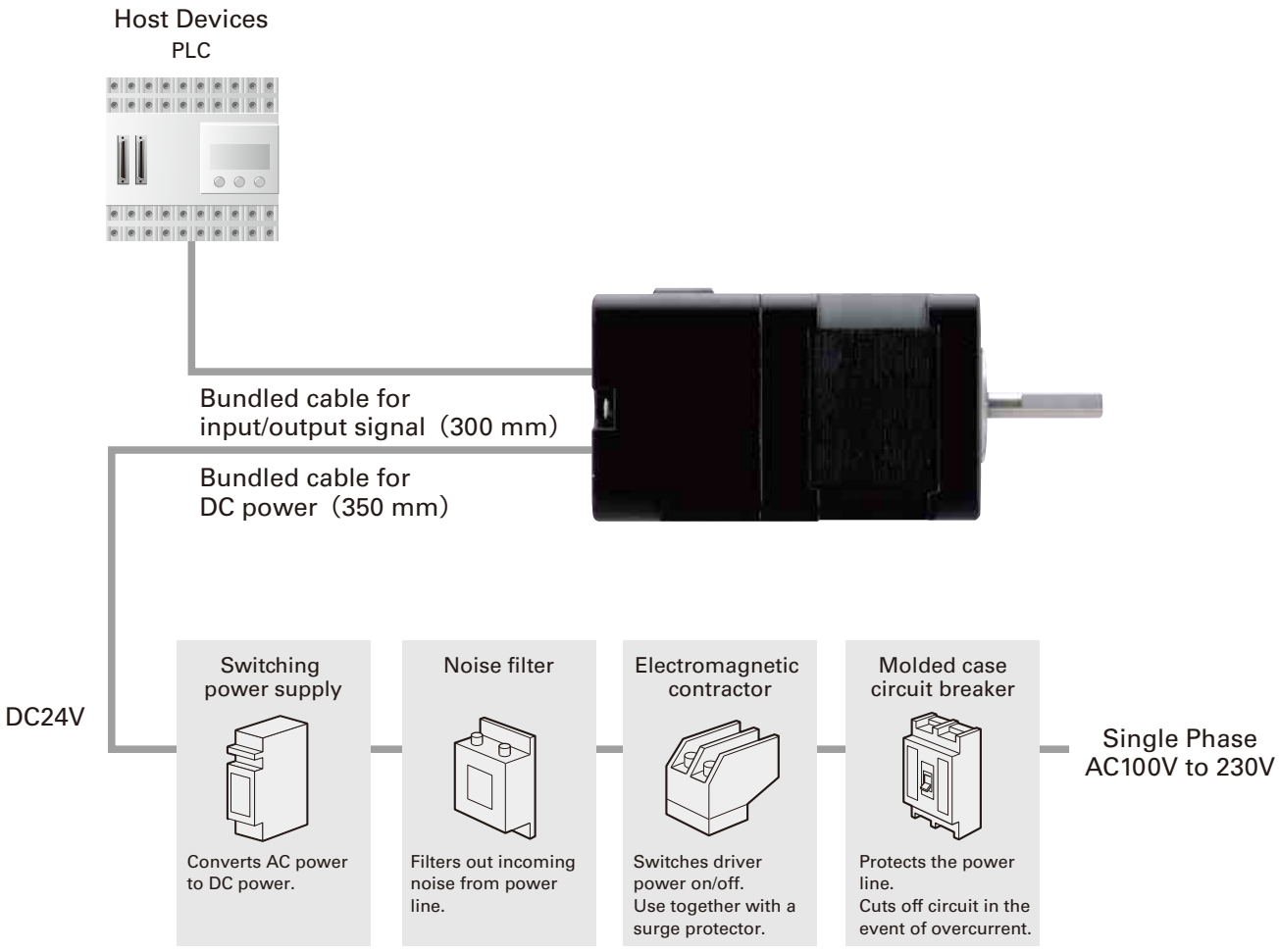
Dimensions ▶ P.75

Features

1. Driver and motor are now integrated into a single unit.
   A driver incorporating a motion control function needed for driving a motor and a 2-phase stepping motor were integrated into a single unit, enabling a more compact installation space and less wiring.

2. Three types of operation modes can be selected to match the specific application.
   (1) Pulse train interface mode:
   Control by command pulses
   (2) Parallel interface mode:
   Program control by general-purpose I/O(Parallel)
   (3) Serial interface mode:
   Compliant with RS-485, half-duplex asynchronous communication

System Configuration Diagram



Specifications

Model number			DB21M142S-01	DB22M162S-01
Basic specifications	Motor size		42 mm sq. (1.65 in sq.)	60 mm sq. (2.36 in sq.)
	Input source *1		DC24V ±10%	
	Source current (A)		2 MAX.	3 MAX.
	Environment	Protection class	Class Ⅰ	
		Operation environment	Installation category (over-voltage category) : Ⅰ, pollution degree : 2	
		Operating ambient temperature *2	0 to + 40℃	
		Conservation temperature	− 20 to + 60℃	
		Operating ambient humidity	35 to 85%RH (no condensation)	
		Conservation humidity	10 to 90%RH (no condensation)	
		Operation altitude	1000 m (3280 feet) MAX. above sea level	
		Vibration resistance	Tested under the following conditions ; 100m/s², frequency range 10 to 2000Hz, direction along X, Y and Z axes, for 2 hours each	
		Impact resistance	Not influenced at NDS-C-0110 standard section 3.2.2 division "C".	
		Withstand voltage	Not influenced when 500V AC is applied between power input terminal and cabinet for one minute.	
		Insulation resistance	10 MΩ MIN. when measured with 500V DC megohmmeter between input terminal and cabinet.	
	Mass (Weight)		0.5kg (1.10 lbs)	0.87kg (1.92 lbs)
Function	Protection function		Against driver overheat	
	LED indicator		Alarm monitor	
I/O signals	Command pulse input signal *3		Photocoupler input method, input resistance 220 Ω	Input signal voltage : "H" = 4.0 to 5.5V, "L" = 0 to 0.5V
	Power down input signal (PD)		Photocoupler input method, input resistance 470 Ω	Input signal voltage : "H" = 4.0 to 5.5V, "L" = 0 to 0.5V
	Step angle setting selection input (EXT)		Photocoupler input method, input resistance 470 Ω	Input signal voltage : "H" = 4.0 to 5.5V, "L" = 0 to 0.5V
	FULL/HALF setting selection input (F/H)		Photocoupler input method, input resistance 470 Ω	Input signal voltage : "H" = 4.0 to 5.5V, "L" = 0 to 0.5V
	EMG input signal		Photocoupler input method, input resistance 470 Ω	Input signal voltage : "H" = 4.0 to 5.5V, "L" = 0 to 0.5V
	BUSY output signal		Open collector output by photocoupler	Output signal standard : Vceo = 30V MAX., Ic = 20mA MAX.
	Phase origin monitor output signal (MON)		Open collector output by photocoupler	Output signal standard : Vceo = 30V MAX., Ic = 20mA MAX.
	Alarm output signal (AL)		Open collector output by photocoupler	Output signal standard : Vceo = 30V MAX., Ic = 20mA MAX.

*1 Note that the power voltage must not exceed 24VDC + 10% (26.4VDC).
*2 If the driver is placed in a box, the temperature inside the box must not exceed this specified range.
*3 The maximum input frequency is 250k pulse/s.

Safety standards

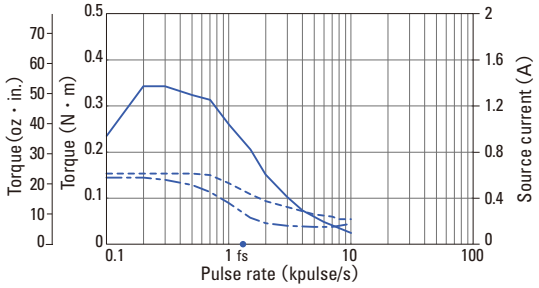
	Directives	Category	Name	Standard part	
				DB21M142S-01	DB22M162S-01
CE (TÜV)	Low-voltage directives	—	—	EN60034-1	EN60034-1
				EN60034-5	EN60034-5
				EN61010-1	EN61010-1
	EMC directives	Emission	Terminal disturbance voltage	EN55011-A	EN61000-6-4
			Electromagnetic radiation disturbance	EN55011-A	EN61000-6-4
		Immunity	ESD (Electrostatic discharge)	EN61000-4-2	EN61000-4-2
			RS (Radio-frequency amplitude modulated electromagnetic field)	EN61000-4-3	EN61000-4-3
			Fast transients / burst	EN61000-4-4	EN61000-4-4
			Conducted disturbances	EN61000-4-6	EN61000-4-6
UL	Acquired standards		Standard part	File No.	
	UL		UL508C	E179775	
	UL for Canada				

・EMC characteristics may vary depending on the configuration of the users' control panel, which contains the driver or stepping motor, or the arrangement and wiring of other electrical devices.
Parts for EMC noise suppression like noise filters and toroidal type ferrite cores may be required depending on circumstances.
・Validation test of driver has been performed for low-voltage EMC directives at TÜV (TÜV product service) for self-declaration of CE marking.

Characteristics diagram

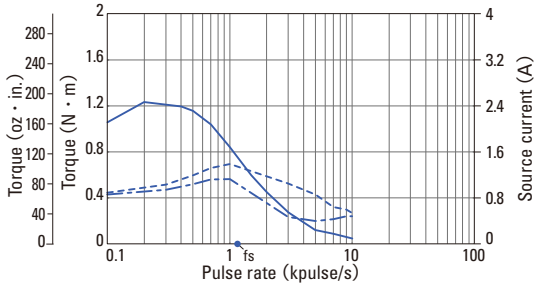
Pull-out torque ——— Source current (no load) —·—·— Source current (load applied) - - - - -

DB21M142S-01



Constant current circuit
Source voltage : DC24V・Operating current : 2A/phase,
2-phase energization (full-step)
J_L=[0.94 × 10⁻⁴kg・m² (5.14 oz・in²) use the rubber coupling]

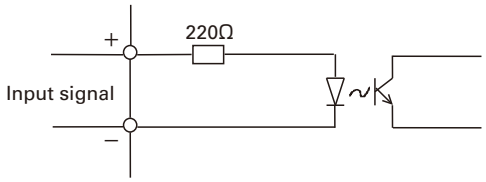
DB22M162S-01



Constant current circuit
Source voltage : DC24V・Operating current : 3A/phase,
2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg・m² (14.22 oz・in²) use the rubber coupling]

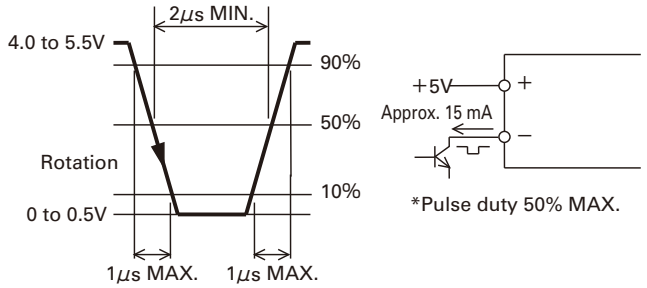
The data are measured under the trial conditions of SANYO DENKI. Driving torque may vary according to actual machine precision.

Input Circuit Configuration (CW, CCW)

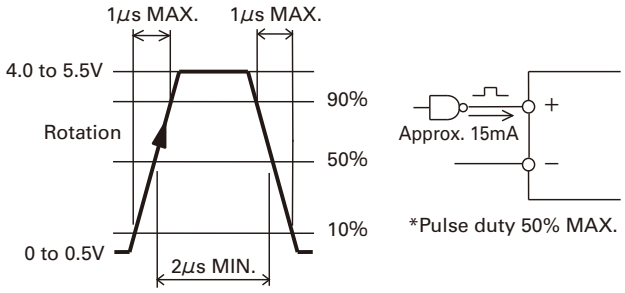


Input signal specifications

Negative logic

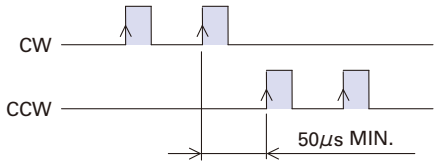


Positive logic



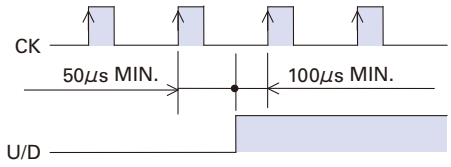
Timing of the command pulse

2-input mode (CW, CCW)



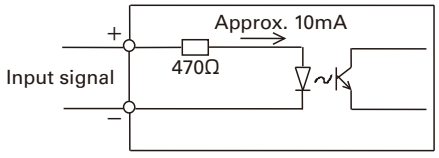
- Shaded area ▒ indicates internal photocoupler "ON". Internal circuit (motor) starts operating at leading edge of the photocoupler "ON".
- To apply pulse to CW, set CCW side internal photocoupler to "OFF".
- To apply pulse to CCW, set CW side internal photocoupler to "OFF".

Pulse and direction mode (CK, U/D)

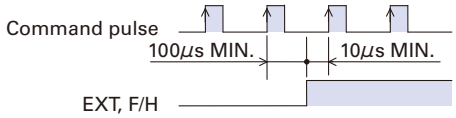


- Shaded area ▒ indicates internal photocoupler "ON". Internal circuit (motor) starts operating at leading edge of CK side photocoupler "ON".
- Switching of U/D input signal must be done while CK side internal photocoupler is "OFF".

Input Circuit Configuration (PD, EXT, F/H, EMG)

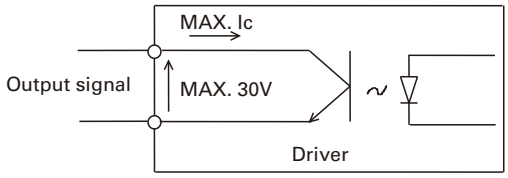


Timing of command pulse, step angle selection, and FULL/HALF selection input signal



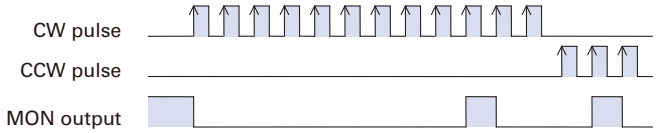
- ▒ Shaded area indicates internal photocoupler "ON".
- EXT input signal
  EXT photocoupler "ON" enables a function by external F/H input signal.
  EXT photocoupler "OFF" enables the setting of a number of micro steps by main unit's rotary switch S.S.
- F/H input signal
  F/H photocoupler "ON" sets HALF step (2-division) operation.
  F/H photocoupler "OFF" sets FULL step (1-division) operation.
- Refer to switching EXT and F/H input signal in the [FULL/HALF input signal, command pulse, and step angle select].
- When switching the step angle by EXT and F/H input signal, the phase origin LCD may not turn ON and the phase origin monitor output may not output when stop.
  Refer to the MON output in the [Output Interface].

Output Interface (BUSY, MON, AL)



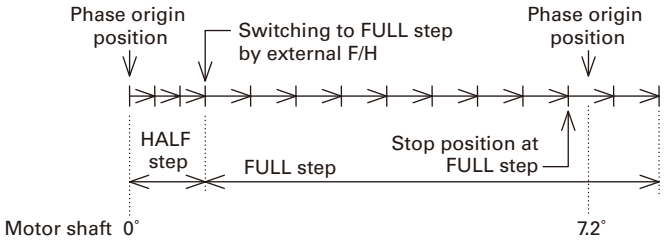
- MAX. Ic current: 20mA

MON output



- When the motor excitation phase is at the phase origin (power ON status), the photocoupler is turned "ON", and the upper D.P of status LED turns on synchronously.
- MON output is taken at every 3.6 degrees of motor output shaft from phase origin.

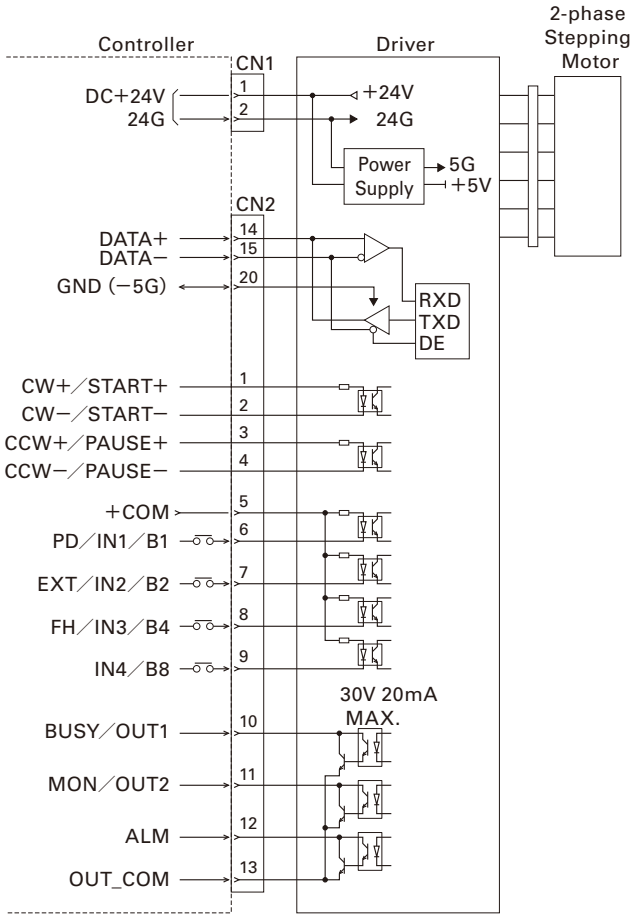
When changing the division setting by F/H input signal.



- When changing the motor division setting by the external input signal and the rotary switch as shown in the example below, the motor cannot stop where MON output signal can be output. Take this into consideration when using the MON output signal.

Connections and Signals

External wiring diagram



Wiring

Specification summary of input/output signals (Parallel I/F mode)

Signal	Reference Designation	Pin Number	Function Summary
Program drive Start/Stop	START + START −	1 2	Commands the start and stop of program driving. Internal photocoupler on ···Program driving start Internal photocoupler off ···Program driving stop
Program pause	PAUSE + PAUSE −	3 4	When START signal on, a pause in program driving is commanded. Internal photocoupler on ···Program driving pause Internal photocoupler off ···Program driving pause release
General-purpose input common	+ COM	5	Input signal common of the 6 to 9 pins DC5V is input.
Alarm clear signal (standard)	ALMC	6	Recoverable alarms are cleared. Internal photocoupler off → on···Alarm clear
General-purpose input 1	IN1	6	This is a general-purpose input signal that can be used by program driving. Internal photocoupler on ···General purpose input 1 on Internal photocoupler off ···General purpose input 1 off
Program number selection bit 1	B1	6	The program number is selected along with other bits. (Subordinate bit) Internal photocoupler on···Corresponding bit 1 Internal photocoupler off···Corresponding bit 0
Emergency stop input	EMG	6	The emergency stop signal is input. Internal photocoupler on···No emergency stop Internal photocoupler off···Emergency stop
Origin signal	ORG	6	The origin signal used for the return to origin operation is input. Internal photocoupler on···Origin signal on Internal photocoupler off···Origin signal off
+ direction overtravel signal	+ OT	7	An overtravel signal in the + direction is input. Internal photocoupler on ····+ direction overtravel not arrived Internal photocoupler off ····+ direction overtravel arrived
General-purpose input 2	IN2	7	This is a general-purpose input signal that can be used by program driving. Internal photocoupler on ···General purpose input 2 on Internal photocoupler off ···General purpose input 2 off
Program number selection bit 2	B2	7	The program number is selected along with other bits. (The second bit from the subordinate) Internal photocoupler on···Corresponding bit 1 Internal photocoupler off···Corresponding bit 0
Emergency stop input	EMG	7	The emergency stop signal is input. Internal photocoupler on···No emergency stop Internal photocoupler off···Emergency stop
Origin signal	ORG	7	The origin signal used for the return to origin operation is input. Internal photocoupler on···Origin signal on Internal photocoupler off···Origin signal off
Alarm clear signal	ALMC	7	Recoverable alarms are cleared. Internal photocoupler off → on···Alarm clear
− direction overtravel signal	− OT	8	An overtravel signal in the − direction is input. Internal photocoupler on ····− direction overtravel not arrived Internal photocoupler off ····− direction overtravel arrived
General-purpose input 3	IN3	8	This is a general-purpose input signal that can be used by program driving. Internal photocoupler on ···General purpose input 3 on Internal photocoupler off ···General purpose input 3 off
Program number selection bit 4	B4	8	The program number is selected along with other bits. (The third bit from the subordinate) Internal photocoupler on···Corresponding bit 1 Internal photocoupler off···Corresponding bit 0
Emergency stop input	EMG	8	The emergency stop signal is input. Internal photocoupler on···No emergency stop Internal photocoupler off···Emergency stop

Signal	Reference Designation	Pin Number	Function Summary
Origin signal	ORG	8	The origin signal used for the return to origin operation is input. Internal photocoupler on···Origin signal on Internal photocoupler off···Origin signal off
Alarm clear signal	ALMC	8	Recoverable alarms are cleared. Internal photocoupler off → on···Alarm clear
Emergency stop signal	EMG	9	The emergency stop signal is input. Internal photocoupler on ···No emergency stop Internal photocoupler off ···Emergency stop
General-purpose input 4	IN4	9	This is a general-purpose input signal that can be used by program driving. Internal photocoupler on ···General purpose input 4 on Internal photocoupler off ···General purpose input 4 off
Program number selection bit 8	B8	9	The program number is selected along with other bits. (The fourth bit from the subordinate) Internal photocoupler on···Corresponding bit 1 Internal photocoupler off···Corresponding bit 0
Origin signal	ORG	9	The origin signal used for the return to origin operation is input. Internal photocoupler on···Origin signal on Internal photocoupler off···Origin signal off
Alarm clear signal	ALMC	9	Recoverable alarms are cleared. Internal photocoupler off → on···Alarm clear
During motor operation	BUSY	10	The operation status of the motor is output. Internal photocoupler on ···During motor operation Internal photocoupler off ···During motor stop
During program execution	PEND	10	The execution status of the program is output. Internal photocoupler on ···During program execution Internal photocoupler off ···Program execution complete
Zone signal	ZONE	10	Turns on when the current position is inside the coordinates that were set beforehand.
During program execution	PEND	11	The execution status of the program is output. Internal photocoupler on ···During program execution Internal photocoupler off ···Program execution complete
During motor operation	BUSY	11	The operation status of the motor is output. Internal photocoupler on ···During motor operation Internal photocoupler off ···During motor stop
Zone signal	ZONE	11	Turns on when the current position is inside the coordinates that were set beforehand.
Alarm output	ALM	12	When various alarm circuits operate in the driver, an external signal is output. At this time, the stepping motor becomes non excited status.
Output signal common	OUT_ COM	13	It is for the output signal common.
DATA +	DATA +	14	It is for the serial signal.
DATA −	DATA −	15	It is for the serial signal.

Specification summary of input/output signals (Serial I/F mode)

Signal	Reference Designation	Pin Number	Function Summary
General-purpose input common	+ COM	5	Input signal common of the 6 to 9 pins DC 5V is input.
Alarm clear signal (standard)	ALMC	6	Recoverable alarms are cleared. Internal photocoupler off → on···Alarm clear
General-purpose input 1	IN1	6	This is a general-purpose input signal that can be used by program driving. Internal photocoupler on ···General purpose input 1 on Internal photocoupler off ···General purpose input 1 off
Emergency stop input	EMG	6	The emergency stop signal is input. Internal photocoupler on···No emergency stop Internal photocoupler of···Emergency stop
Origin signal	ORG	6	The origin signal used for the return to origin operation is input. Internal photocoupler on···Origin signal on Internal photocoupler off···Origin signal off
+ direction overtravel signal	+ OT	7	An overtravel signal in the + direction is input. Internal photocoupler on ····+ direction overtravel not arrived Internal photocoupler off ····+ direction overtravel arrived
General-purpose input 2	IN2	7	This is a general-purpose input signal that can be used by program driving. Internal photocoupler on ···General purpose input 2 on Internal photocoupler off ···General purpose input 2 off
Emergency stop input	EMG	7	The emergency stop signal is input. Internal photocoupler on···No emergency stop Internal photocoupler off···Emergency stop
Origin signal	ORG	7	The origin signal used for the return to origin operation is input. Internal photocoupler on···Origin signal on Internal photocoupler off···Origin signal off
Alarm clear signal	ALMC	7	Recoverable alarms are cleared. Internal photocoupler off → on···Alarm clear
− direction overtravel signal	− OT	8	An overtravel signal in the − direction is input. Internal photocoupler on ····− direction overtravel not arrived Internal photocoupler off ····− direction overtravel arrived
General-purpose input 3	IN3	8	This is a general-purpose input signal that can be used by program driving. Internal photocoupler on ···General purpose input 3 on Internal photocoupler off ···General purpose input 3 off
Emergency stop input	EMG	8	emergency stop signal is input. Internal photocoupler on···No emergency stop Internal photocoupler off···Emergency stop
Origin signal	ORG	8	The origin signal used for the return to origin operation is input. Internal photocoupler on···Origin signal on Internal photocoupler off···Origin signal off
Alarm clear signal	ALMC	8	Recoverable alarms are cleared. Internal photocoupler off → on···Alarm clear
Emergency stop signal	EMG	9	The emergency stop signal is input. Internal photocoupler on···No emergency stop Internal photocoupler off···Emergency stop
General-purpose input 4c	IN4	9	This is a general-purpose input signal that can be used by program driving. Internal photocoupler on ···General purpose input 4 on Internal photocoupler off ···General purpose input 4 off
Origin signal	ORG	9	The origin signal used for the return to origin operation is input. Internal photocoupler on···Origin signal on Internal photocoupler off···Origin signal off
Alarm clear signal	ALMC	9	alarms are cleared. Internal photocoupler off → on···Alarm clear
During motor operation	BUSY	10	The operation status of the motor is output. Internal photocoupler on···During motor operation Internal photocoupler off···During motor stop
During program execution	PEND	10	The execution status of the program is output. Internal photocoupler on ···During program execution Internal photocoupler off ···Program execution complete
Zone signal	ZONE	10	on when the current position is inside the coordinates that were set beforehand.
During program execution	PEND	11	The execution status of the program is output. Internal photocoupler on ···During program execution Internal photocoupler off ···Program execution complete
During motor operation	BUSY	11	The operation status of the motor is output. Internal photocoupler on···During motor operation Internal photocoupler off···During motor stop
Zone signal	ZONE	11	Turns on when the current position is inside the coordinates that were set beforehand.
Alarm output	ALM	12	When various alarm circuits operate in the driver, an external signal is output. At this time, the stepping motor becomes non excited status.
Output signal common	OUT_ COM	13	It is for the output signal common.
DATA +	DATA +	14	It is for the serial signal.
DATA −	DATA −	15	It is for the serial signal.

Specification summary of input/output signals (Pulse train I/F mode)

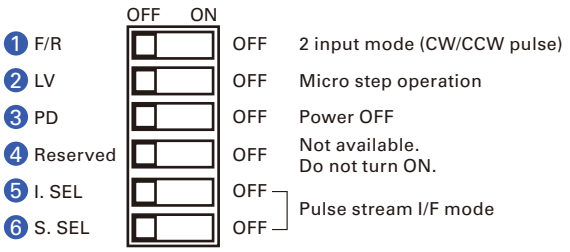
Signal	Reference Designation	Pin Number	Function Summary
CW pulse input (Standard)	CW + CW −	1 2	When "2 input mode", Input drive pulse rotating CW direction.
Pulse train input	CK + CK −	1 2	When "1 input mode", Input drive pulse train for motor rotation.
CCW pulse input (Standard)	CCW + CCW −	3 4	When "2 input mode", Input drive pulse rotating CCW direction.
Rotational direction input	U／D + U／D −	3 4	When "1 input mode", Input motor rotational direction signal. Internal photocoupler ON···CW direction Internal photocoupler OFF···CCW direction
General-purpose input common	+ COM	5	Input signal common of the 6 to 9 pins DC5V is input.
Power down input	PD	6	Inputting PD signal will cut off (power off) the current flowing to the Motor (With dip switch select, change to the Power low function is possible). PD input signal on (internal photocoupler on) ···PD function is valid. PD input signal off (internal photocoupler off) ···PD function is invalid.
Step angle select input	EXT	7	FULL/HALF select input will become valid by inputting EXT signal. EXT input signal on (internal photocoupler on) ···External input signal F/H is valid EXT input signal off (internal photocoupler off) ···Main body rotary switch S.S is valid
FULL/HALF select input	F／H	8	When EXT input signal on (internal photocoupler on), F/H input signal on (internal photocoupler on) ···HALF step F/H input signal off (internal photocoupler off) ···FULL step
—	—	9	Reserved
During motor operation	BUSY	10	The operation status of the motor is output. Internal photocoupler on ···During motor operation Internal photocoupler off ···During motor stop
Phase origin monitor output	MON	11	When the excitation phase is at the origin (in power on) it turns on. When FULL step, ON once for 4 pulses, when HALF step, ON once for 8 pulses.
Alarm output	ALM	12	When alarm circuits actuated inside the Driver, outputs signals to outside. Then the Stepping motor becomes unexcited status.
Output signal common	OUT_ COM	13	It is for the output signal common.

* As for the Motor rotational direction, CW direction is regard as the clockwise revolution, and CCW direction is regard as the counterclockwise revolution when viewing the Motor from output shaft side.

Set Up

Function select dip switch

The functions according to the specification can be selected with this Dip switch.
Confirm the ex-factory setting as follows.



◎ **For parallel I/F mode or serial I/F mode**

The communication speed of serial communication is set.

Switch	Set value	Communication speed (bps)		
		9,600	19,200	38,400
F/R	OFF	✓	✓	✓
	ON			
LV	OFF	✓	✓	
	ON			✓
PD	OFF	✓		✓
	ON		✓	

* The setting change after the power supply is turned on is invalid. It does not function as a F/R, LV, and PD.
* The communication speed of pulse stream I/F mode is fixed at 9600bps.

◎ **For pulse stream I/F mode**

1 Input mode select (F/R)
Input pulse mode selection
This switch setting is only effective in pulse stream I/F mode.

F/R	Input pulse mode
ON	1 input mode (CK,U/D)
OFF	2 input mode (CW,CCW)

2 Low vibration mode select (LV)
Low vibration and smooth operation are enabled even during coarse resolution settings (e.g. 1 division, 2 division).
This switch setting is only effective in pulse stream I/F mode.
For parallel I/F mode and serial I/F mode, this is usually a low vibration operation.

LV	Operation
ON	Low vibration operation
OFF	Micro step operation

* When LV select is ON (low vibration mode), operational process of driving pulse will be carried out inside the Driver. Therefore, the Motor movement delays for the time of 3.2ms pulse per input pulse. Note that depending upon the combined Motor, load, driving profile etc., it may take a while until the shaft is adjusted when the Motor stops. (In parallel I/F mode and serial I/F mode there is no delay)

3 Power down select (PD)
Select the Motor winding current value when inputting the power down signal. This switch setting is only effective in pulse stream I/F mode.

PD	Motor winding current
ON	Current value by rotary switch STP (Power Low)
OFF	0A (Power OFF)

* PD function (the setting selected by PD of the function select dip switch) is enabled by PD input signal ON (built-in photocoupler ON) of Input/Output signal connector (CN2). Power down signal input is prior to all the other current settings except for alarms. The operational status may not be maintained such as power swing due to output torque drop or lower operation due to Motor current OFF (unexcited Motor).
Pay extra attention to the input timing of the power down signal and also install security devices to the machine.

4 Reserved
* Do not turn ON this switch.

5 , 6 Operation mode selection (I.SEL, S.SEL)
The operation mode is selected.

I.SEL	S.SEL	Operation mode
OFF	–	Pulse stream I/F mode
ON	OFF	Parallel I/F mode
	ON	Serial I/F mode

* Change the operation mode selection switch after cutting off the driver's power supply.

Rotary switch (RSW) and the mode change switch (PSW)

◎ **For pulse stream I/F mode**

The combination of rotary switch (RSW) and mode change switch (PSW) select the step angle, driving current and stop the current.

1. Step angle select (S.S)

The divisions of the basic step angle (0.9° /step) during micro step driving can be set.

Gradation	0	1	2	3	4	5	6	7
Partition	1	2	2.5	4	5	8	10	20
Gradation	8	9	A	B	C	D	E	F
Partition	25	40	50	80	100	125	200	250

Initial setting is at gradation 1 (division 2)

* The step angle select switch (S.S) and the number of partitions become invalid by EXT input signal ON (built-in photocoupler ON) of Input/Output signal connector (CN2).

2. Driving current select (RUN)

The Motor operation current value can be selected.

Gradation	0	1	2	3	4	5	6	7
Motor current (%)	100 (rated)	95	90	85	80	75	70	65
Gradation	8	9	A	B	C	D	E	F
Motor current (%)	60	55	50	45	40	35	30	25

Initial setting is at gradation 0 (motor current 100%, rated).

* When there is a sufficient extra motor torque, lowering the operation current value will be effective in the lower vibration. The Motor output torque is almost proportional to the current value. When adjusting the operational torque, confirm the sufficient operation margin and determine the Motor current value.

3. Current Select when Stop (STP)

The motor current value when, stopped and when power down input signal ON (power low function is selected by dip switch) can be selected.

Gradation	0	1	2	3	4	5	6	7
Motor current (%)	100 (rated)	95	90	85	80	75	70	65
Gradation	8	9	A	B	C	D	E	F
Motor current (%)	60	55	50	45	40	35	30	25

Initial setting is set at gradation A (motor current 50%).

* The current setting when stop by STP becomes valid when the Motor stops (approximately 200ms after the last pulse input) and when power down input signal Output torque is approximately proportional to motor current.
Pay attention to output torque when stopping motor (especially when dropping Z-axis workload).
* If motor output torque is unconstrained, motor/driver heating can be suppressed by selecting appropriate drive current and stopping current settings.

◎ **For parallel I/F mode and serial I/F mode**

The slave bureau address of serial communications can be set.

RSW	Slave station address (HEX)
0	0
1	1
:	:
E	E
F	F

Initial setting is set at 0

* The slave station address of the pulse stream I/F mode is fixed at 0.

IP65 Splash and Dust Proof Stepping Motors

Cable type CE Model
CE/UL Model

Connector type CE Model

Features

- These IP65 rated motors* have superior water and dust resistance, and can be safely utilized in harsh or wet environments such as in food processing machines.
  ※ Except for the shaft and the cable end.
- The input voltage range of the motors is up to AC 250 V.
- Brake, encoder, and oil seal can be combined.

Safety standards

The CE model (Cable or Connector type) and the CE/UL model (Cable type) are available.

Specifications

	56 mm sq. (2.20 in sq.)		86 mm sq. (3.39 in sq.)	
	CE Model	CE/UL Model	CE Model	CE/UL Model
Motor model number	SP256 □ T-5 □□ 0	SP256 □ -5 □ 60	SP286 □ T-5 □□ 0	SP286 □ -5 □ 60
Type	S1 (continuous operation)			
Operating ambient temperature	− 10℃ to + 40℃			
Conversation temperature	− 20℃ to + 60℃			
Operating ambient humidity	95%MAX. : 40℃ MAX., 57%MAX. : 50℃ MAX.			
Conversation humidity	35%MAX. : 60℃ MAX. (no condensation)			
Operation altitude	1000m (3280 feet) MAX above sea level			
Vibration resistance	Vibration frequency 10 to 500 Hz, total amplitude 1.52 mm (10 to 70 Hz), vibration acceleration 147m/s² (70 to 500 Hz), sweep time 15 min/cycle, 12 sweeps in each X, Y and Z direction.			
Impact resistance	500m/s² of acceleration for 11 ms with half-sine wave applying three times for X, Y and Z axes each, 18 times in total.			
Insulation class	Class F (+155℃)			
Withstand voltage	At normal temperature and humidity, no failure with 1500 V AC @50/60 Hz applied for one minute between motor winding and frame.			
Insulation resistance	At normal temperature and humidity, not less then 100MΩ between winding and frame by DC500V megger.			
Protection grade	IP65 (Except for the shaft and the cable end)			
Winding temperature rise	100K MAX. (Based on Sanyo Denki standard)			
Static angle error	± 0.054°		± 0.09°	
Axial play	0.075 mm (0.003 in) MAX. (load: 10N (2.25 lbs))			
Radial play	0.025 mm (0.001 in) MAX. (load: 5N (1.12 lbs))			
Shaft runout	0.025 mm (0.001 in)			
Concentricity of mounting pilot relative to shaft	ϕ 0.075 mm (ϕ 0.003 in)			
Squareness of mounting surface relative to shaft	0.1 mm (0.004 in)	0.1 mm (0.004 in)	0.15 mm (0.006 in)	0.15 mm (0.006 in)

Safety standards

CE	Standard category	Standard code	
	Low-voltage directives	EN60034-1, EN60034-5	
UL	Acquired standards	Standard code	File No.
	UL	UL1004-1, UL1004-6	E179832
	UL for Canada (c-UL)		

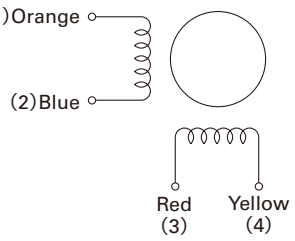
Model No. differs when the motor is equipped with a brake or oil seal.
Model No. and vibration resistence levels differ when the motor is equipped with a brake or oil seal.

Internal wiring and rotation direction

Bipolar winding

Internal wire connection

( ) : connector pin number



Direction of motor rotation

The output shaft shall rotate clockwise as seen from the shaft side, when excited by DC in the following order.

Lead wire color		Red	Blue	Yellow	Orange
Connector pin number		3	2	4	1
Exciting order	1	−	−	+	+
	2	+	−	−	+
	3	+	+	−	−
	4	−	+	+	−

56 mm sq. (2.20 inch sq.)

1.8° /step

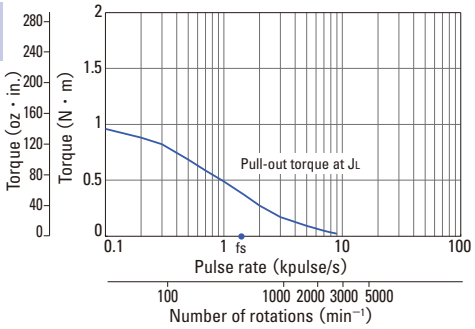
Bipolar winding

Safety standards	Model number		Holding torque at 2-phase energization	Rated current	Winding resistance	Winding inductance	Rotor inertia	Mass (Weight)
	Cable type	Connector type	[N·m (oz・in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴ kg·m² (oz・in²)]	[kg (lbs)]
CE Model	**SP2563T-5060**	**SP2563T-5000**	1 (141.6)	1	5.7	29	0.21 (1.15)	0.9 (2)
	SP2563T-5160	**SP2563T-5100**	1 (141.6)	2	1.5	7.3	0.21 (1.15)	0.9 (2)
	SP2563T-5260	**SP2563T-5200**	1 (141.6)	3	0.7	3.4	0.21 (1.15)	0.9 (2)
	SP2566T-5060	**SP2566T-5000**	1.7 (240.7)	1	7.7	35.4	0.36 (1.97)	1.2 (2.65)
	SP2566T-5160	**SP2566T-5100**	1.7 (240.7)	2	2	9.2	0.36 (1.97)	1.2 (2.65)
	SP2566T-5260	**SP2566T-5200**	1.7 (240.7)	3	0.94	4.4	0.36 (1.97)	1.2 (2.65)
CE/UL Model	**SP2563-5060**	—	1 (141.6)	1	5.8	29	0.21 (1.15)	0.9 (2)
	SP2563-5160	—	1 (141.6)	2	1.5	7.3	0.21 (1.15)	0.9 (2)
	SP2563-5260	—	1 (141.6)	3	0.75	3.4	0.21 (1.15)	0.9 (2)
	SP2566-5060	—	1.7 (240.7)	1	7.8	35.4	0.36 (1.97)	1.2 (2.65)
	SP2566-5160	—	1.7 (240.7)	2	2	9.2	0.36 (1.97)	1.2 (2.65)
	SP2566-5260	—	1.7 (240.7)	3	1	4.4	0.36 (1.97)	1.2 (2.65)

・The Model No., rotor inertia and mass differ when the motor is equipped with brake, encoder or oil seal.

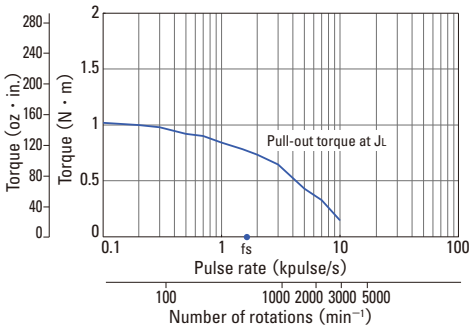
Characteristics diagram

SP2563T-50 □□
SP2563-5060



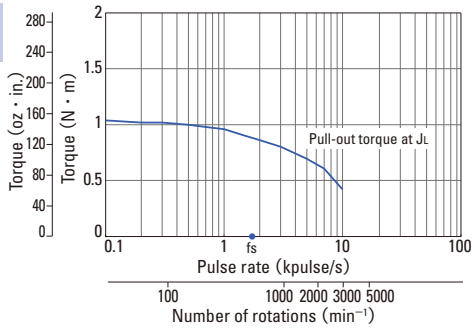
Constant current circuit
Source voltage : AC100V・operating current : 1A/phase, 2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg・m² (14.22 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SP2563T-51 □□
SP2563-5160



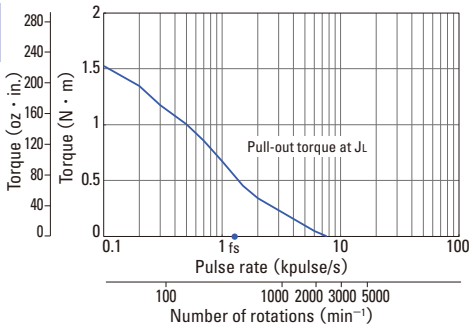
Constant current circuit
Source voltage : AC100V・operating current : 2A/phase, 2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg・m² (14.22 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SP2563T-52 □□
SP2563-5260



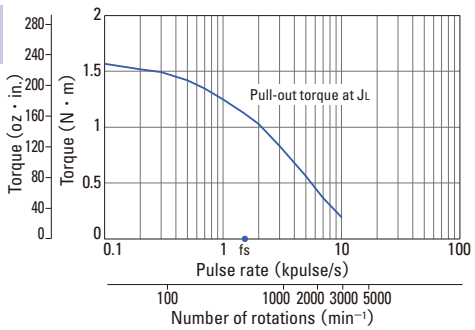
Constant current circuit
Source voltage : AC100V・operating current : 3A/phase, 2-phase energization (full-step)
J_L=[2.6 × 10⁻⁴kg・m² (14.22 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SP2566T-50 □□
SP2566-5060



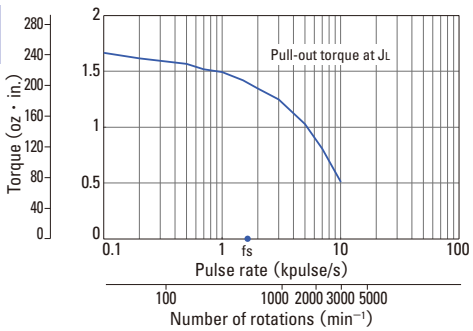
Constant current circuit
Source voltage : AC100V・operating current : 1A/phase, 2-phase energization (full-step)
J_L=[7.4 × 10⁻⁴kg・m² (40.46 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SP2566T-51 □□
SP2566-5160



Constant current circuit
Source voltage : AC100V・operating current : 2A/phase, 2-phase energization (full-step)
J_L=[7.4 × 10⁻⁴kg・m² (40.46 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SP2566T-52 □□
SP2566-5260



Constant current circuit
Source voltage : AC100V・operating current : 3A/phase, 2-phase energization (full-step)
J_L=[7.4 × 10⁻⁴kg・m² (40.46 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

86 mm sq. (3.39 inch sq.)

1.8° /step

Bipolar winding

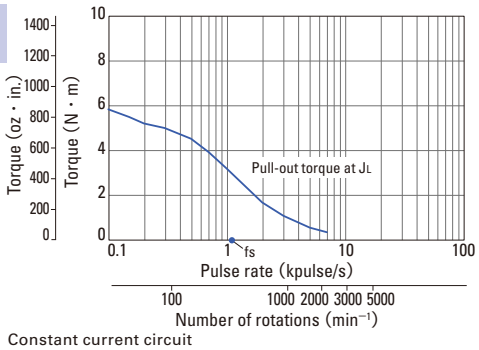
Safety standards	Model number		Holding torque at 2-phase energization	Rated current	Winding resistance	Winding inductance	Rotor inertia	Mass (Weight)
	Cable type	Connector type	[N·m (oz・in) MIN.]	A/phase	Ω /phase	mH/phase	[×10⁻⁴ kg·m² (oz・in²)]	[kg (lbs)]
CE Model	**SP2862T-5060**	**SP2862T-5000**	6.4 (906.3)	2	3.2	25	3 (16.4)	3.1 (6.8)
	SP2862T-5160	**SP2862T-5100**	6.4 (906.3)	4	0.83	6.4	3 (16.4)	3.1 (6.8)
	SP2862T-5260	—	6.4 (906.3)	6	0.36	2.8	3 (16.4)	3.1 (6.8)
	SP2863T-5060	**SP2863T-5000**	9 (1274.5)	2	4	32	4.5 (24.6)	4.2 (9.3)
	SP2863T-5160	**SP2863T-5100**	9 (1274.5)	4	1	7.9	4.5 (24.6)	4.2 (9.3)
	SP2863T-5260	—	9 (1274.5)	6	0.46	3.8	4.5 (24.6)	4.2 (9.3)
CE/UL Model	**SP2862-5060**	—	6.4 (906.3)	2	3.2	25	3 (16.4)	3.1 (6.8)
	SP2862-5160	—	6.4 (906.3)	4	0.85	6.4	3 (16.4)	3.1 (6.8)
	SP2862-5260	—	6.4 (906.3)	6	0.41	2.8	3 (16.4)	3.1 (6.8)
	SP2863-5060	—	9 (1274.5)	2	4	32	4.5 (24.6)	4.2 (9.3)
	SP2863-5160	—	9 (1274.5)	4	1.05	7.9	4.5 (24.6)	4.2 (9.3)
	SP2863-5260	—	9 (1274.5)	6	0.53	3.8	4.5 (24.6)	4.2 (9.3)

・The Model No., rotor inertia and mass differ when the motor is equipped with brake, encoder or oil seal.

・The rated current of the motor with the connector is 4A or less.

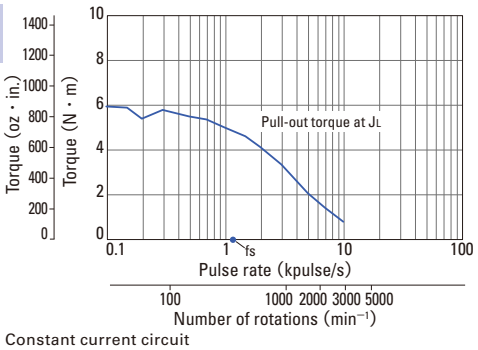
Characteristics diagram

SP2862T-50 □□
SP2862-5060



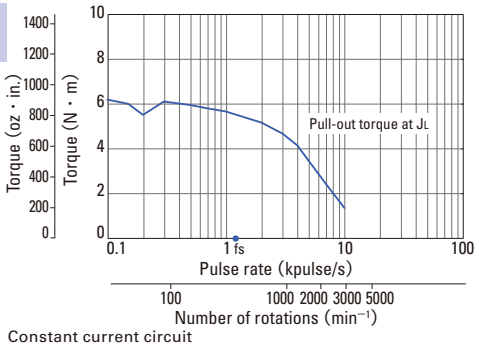
Constant current circuit
Source voltage : AC100V・operating current : 2A/phase, 2-phase energization (full-step)
J_L=[15.3 × 10⁻⁴kg・m² (83.65 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SP2862T-51 □□
SP2862-5160



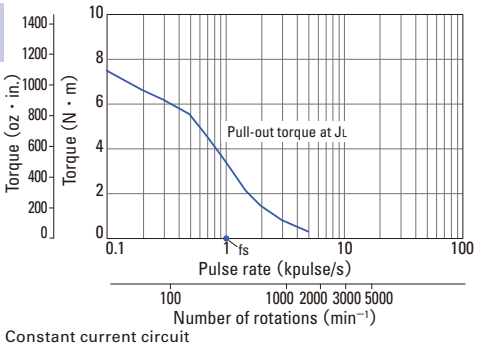
Constant current circuit
Source voltage : AC100V・operating current : 4A/phase, 2-phase energization (full-step)
J_L=[15.3 × 10⁻⁴kg・m² (83.65 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SP2862T-5260
SP2862-5260



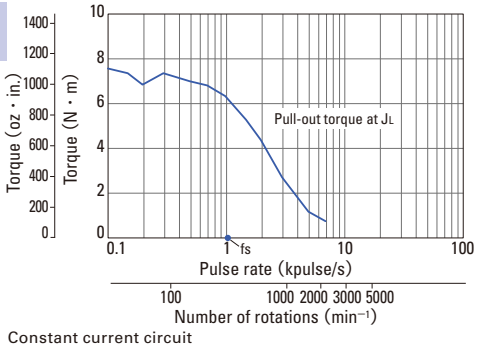
Constant current circuit
Source voltage : AC100V・operating current : 6A/phase, 2-phase energization (full-step)
J_L=[15.3 × 10⁻⁴kg・m² (83.65 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SP2863T-50 □□
SP2863-5060



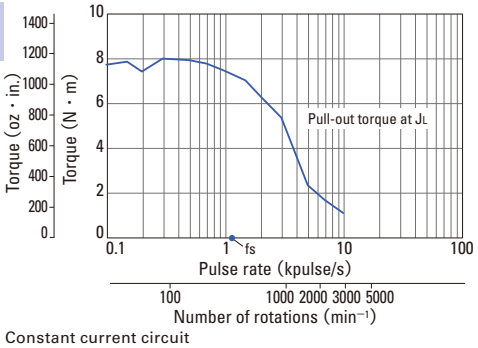
Constant current circuit
Source voltage : AC100V・operating current : 2A/phase, 2-phase energization (full-step)
J_L=[44 × 10⁻⁴kg・m² (240.56 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SP2863T-51 □□
SP2863-5160



Constant current circuit
Source voltage : AC100V・operating current : 4A/phase, 2-phase energization (full-step)
J_L=[44 × 10⁻⁴kg・m² (240.56 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

SP2863T-5260
SP2863-5260



Constant current circuit
Source voltage : AC100V・operating current : 6A/phase, 2-phase energization (full-step)
J_L=[44 × 10⁻⁴kg・m² (240.56 oz・in²) use the rubber coupling]
fs: Maximum self-start frequency when not loaded

Stepping Motors for Vacuum Environments Customized Products

Features

- These stepping motors can be driven in a vacuum environment without requiring a vacuum feedthrough. Use as vacuum-compatible actuators while retaining the stepping motor benefits of easy high-precision open-loop control.
- We can customize for a wide range of environment pressures, from low to ultra-high vacuums.
- Available baked at 200℃ .
- Size is similar to that of typical stepping motors.

Intended Operating Pressure

Low vacuum				Medium vacuum		High vacuum				Ultra-High vacuum				
10^{5}	10^{4}	10^{3}	10^{2}	10^{1}	1	10^{-1}	10^{-2}	10^{-3}	10^{-4}	10^{-5}	10^{-6}	10^{-7}	10^{-8}	[Pa]

Applications

Ideal for the following applications. Contact us to discuss your particular application environment needs.

- Semiconductor manufacturing equipment
- Satellite robotics
- Electron microscopes
- Large-scale research facilities such as accelerators, synchrotron radiation analysis equipment, etc.

Motor size

42 mm sq. (1.65 inch sq.) to ϕ 106 mm (ϕ 4.17 inch)

Synchronous Motors Customized Products

Features

- These motors always maintain a constant speed under variable load and voltage conditions, rotating in step with the frequency of the power supply. This eliminates motor slip.
- Provides high torque at ultraslow speeds with gearless construction.
- Allows for simplification by connecting directly to the commercial (AC) power supply, eliminating the need for a driver circuit.

Applications

Ideal for the following applications. Contact us to discuss your particular application environment needs.

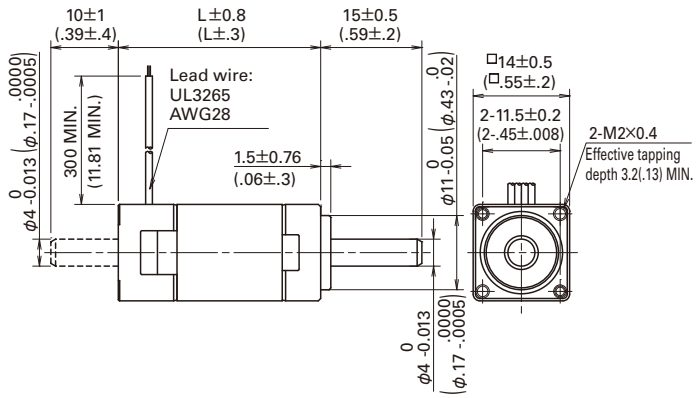
- Conveyor drives
- Printers
- Cryopumps
- Cryocoolers
- Switchgears

Motor size

56 mm sq. (2.20 inch sq.) to ϕ 106 mm (ϕ 4.17 inch)

Stepping motors [Unit: mm (inch)]

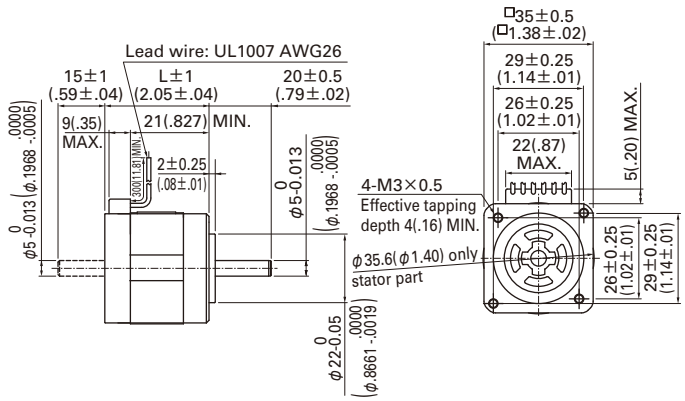
14 mm sq. (0.55 inch sq.)



Bipolar

Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
–	–	SH2141-5541	SH2141-5511	30 (1.18)

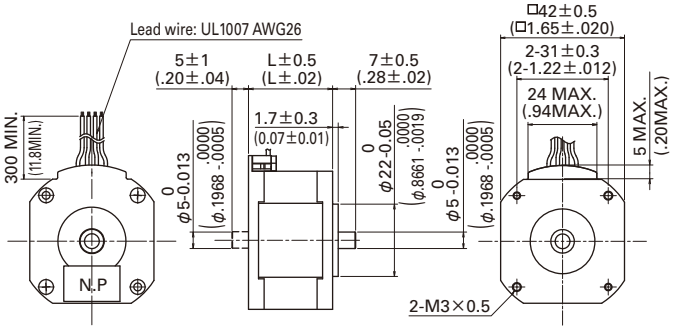
35 mm sq. (1.65 inch sq.)



Unipolar

Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
–	–	SH3533-12U40	SH3533-12U10	33 (1.25)
–	–	SH3537-12U40	SH3537-12U10	37 (1.54)
–	–	SH3552-12U40	SH3552-12U10	52 (1.89)

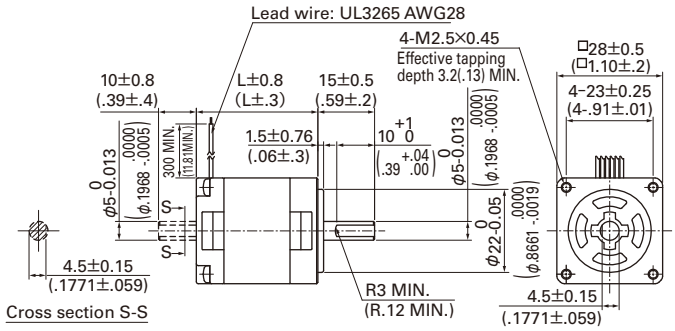
42 mm sq. (1.65 inch sq.)



Bipolar

Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
–	–	SS2421-5041	SS2421-5011	11.6 (.457)
–	–	SS2422-5041	SS2422-5011	18.6 (.732)

28 mm sq. (1.10 inch sq.)



Note: A unipolar motor is illustrated; bipolar motors have four lead wires.

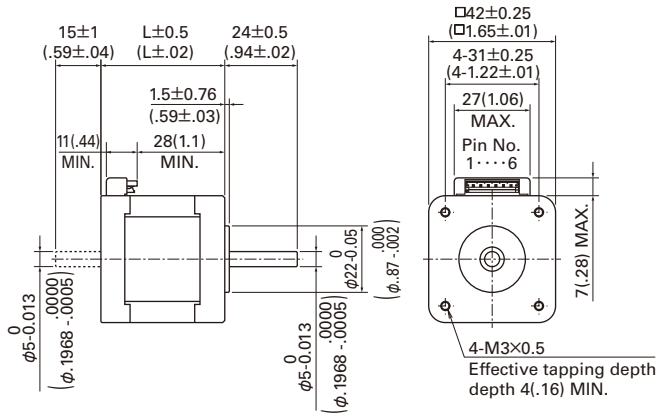
Unipolar

Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
–	–	SH2281-5171	SH2281-5131	32 (1.26)
DU14S281S	DU14S281D	SH2281-5271	SH2281-5231	32 (1.26)
–	–	SH2285-5171	SH2285-5131	51.5 (2.03)
DU14S285S	DU14S285D	SH2285-5271	SH2285-5231	51.5 (2.03)

Bipolar

Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
–	–	SH2281-5671	SH2281-5631	32 (1.26)
DB14S281S	DB14S281D	SH2281-5771	SH2281-5731	32 (1.26)
–	–	SH2285-5671	SH2285-5631	51.5 (2.03)
DB14S285S	DB14S285D	SH2285-5771	SH2285-5731	51.5 (2.03)

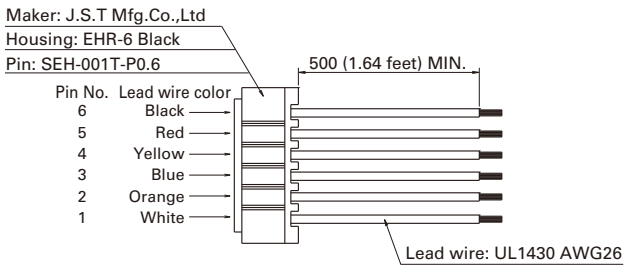
42 mm sq. (1.65 inch sq.)



Unipolar

Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
DU15H521S	DU15H521D	103H5205-0440	103H5205-0410	33 (1.25)
DU15H522S	DU15H522D	103H5208-0440	103H5208-0410	39 (1.54)
–	–	103H5209-0440	103H5209-0410	41 (1.61)
DU15H524S	DU15H524D	103H5210-0440	103H5210-0410	48 (1.89)

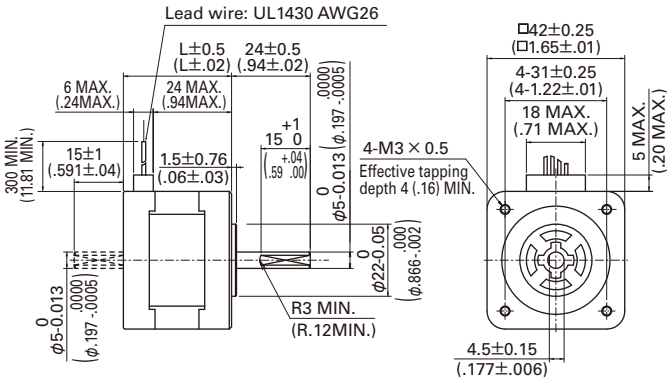
Motor cable Model number: 4835710-1



This driver-motor cable is for motor model numbers 103H52□□-04□□.

Stepping motors [Unit: mm (inch)]

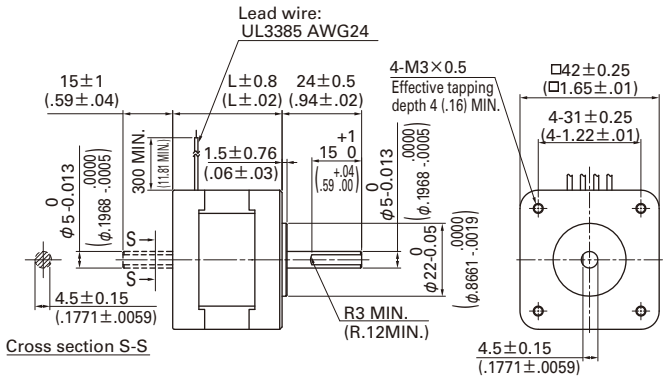
42 mm sq. (1.65 inch sq.)



Bipolar

Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
–	–	103H5205-5040	103H5205-5010	33 (1.25)
–	–	103H5205-5140	103H5205-5110	33 (1.25)
DB14H521S	DB14H521D	103H5205-5240	103H5205-5210	33 (1.25)
–	–	103H5208-5040	103H5208-5010	39 (1.54)
–	–	103H5208-5140	103H5208-5110	39 (1.54)
DB14H522S	DB14H522D	103H5208-5240	103H5208-5210	39 (1.54)
–	–	103H5209-5040	103H5209-5010	41 (1.61)
–	–	103H5209-5140	103H5209-5110	41 (1.61)
–	–	103H5209-5240	103H5209-5210	41 (1.61)
–	–	103H5210-5040	103H5210-5010	48 (1.89)
–	–	103H5210-5140	103H5210-5110	48 (1.89)
DB14H524S	DB14H524D	103H5210-5240	103H5210-5210	48 (1.89)

42 mm sq. (1.65 inch sq.)



Note: A bipolar motor is illustrated; unipolar motors have six lead wires.

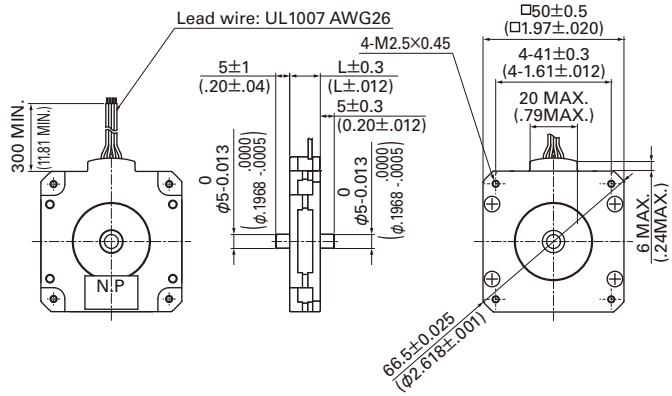
Unipolar

Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
DU15S141S	DU15S141D	SH1421-0441	SH1421-0411	33 (1.25)
DU15S142S	DU15S142D	SH1422-0441	SH1422-0411	39 (1.54)
DU15S144S	DU15S144D	SH1424-0441	SH1424-0411	48 (1.89)

Bipolar

Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
–	–	SH1421-5041	SH1421-5011	33 (1.25)
DB16S141S	DB16S141D	SH1421-5241	SH1421-5211	33 (1.25)
–	–	SH1422-5041	SH1422-5011	39 (1.54)
DB16S142S	DB16S142D	SH1422-5241	SH1422-5211	39 (1.54)
–	–	SH1424-5041	SH1424-5011	48 (1.89)
DB16S144S	DB16S144D	SH1424-5241	SH1424-5211	48 (1.89)

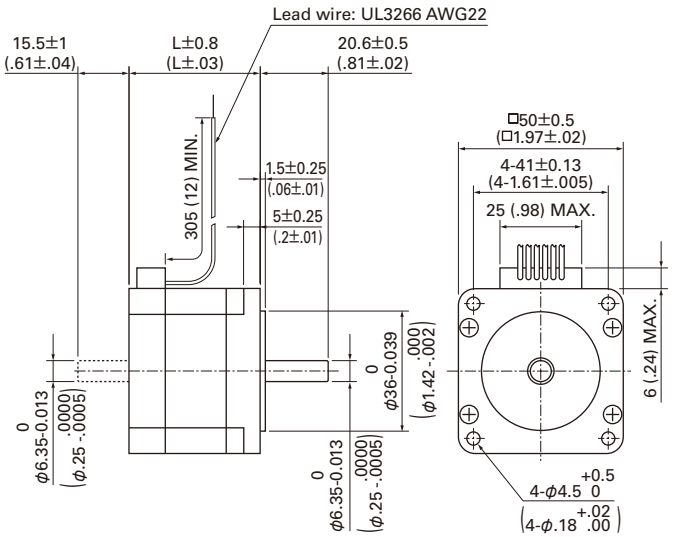
50 mm sq. (1.97 inch sq.)



Bipolar

Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
–	–	SS2501-8040	SS2501-8010	11.4 (.43)
–	–	SS2502-8040	SS2502-8010	16.4 (.63)

50 mm sq. (1.97 inch sq.)



Note: A unipolar motor is illustrated; bipolar motors have four lead wires.

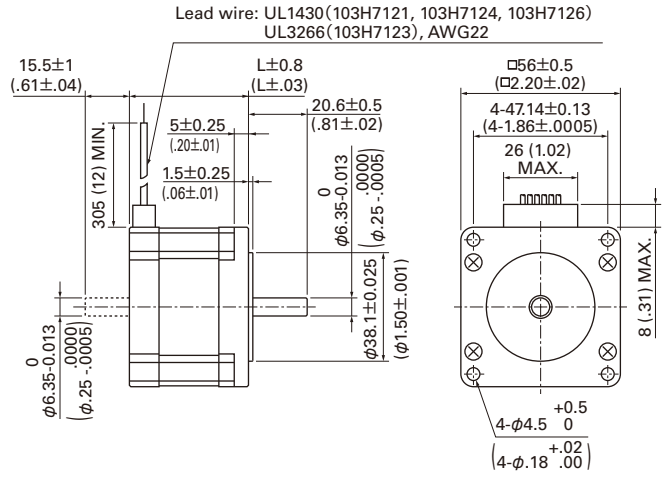
Unipolar

Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
–	–	103H6701-0140	103H6701-0110	39.8 (1.57)
–	–	103H6701-0440	103H6701-0410	39.8 (1.57)
–	–	103H6701-0740	103H6701-0710	39.8 (1.57)
–	–	103H6703-0140	103H6703-0110	51.3 (2.02)
–	–	103H6703-0440	103H6703-0410	51.3 (2.02)
–	–	103H6703-0740	103H6703-0710	51.3 (2.02)
–	–	103H6704-0140	103H6704-0110	55.8 (2.20)
–	–	103H6704-0440	103H6704-0410	55.8 (2.20)
–	–	103H6704-0740	103H6704-0710	55.8 (2.20)

Bipolar

Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
DB16H671S	DB16H671D	103H6701-5040	103H6701-5010	39.8 (1.57)
DB16H673S	DB16H673D	103H6703-5040	103H6703-5010	51.3 (2.02)
–	–	103H6704-5040	103H6704-5010	55.8 (2.20)

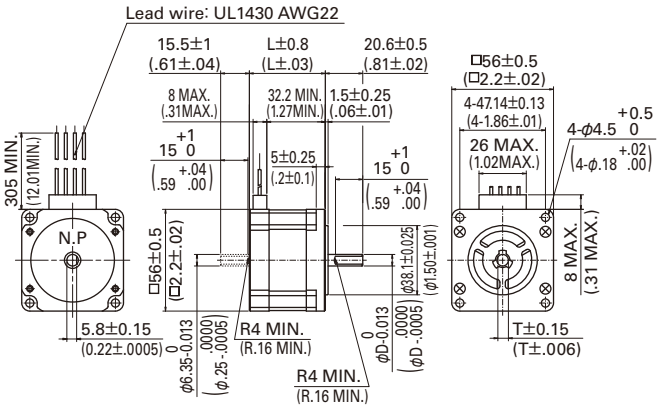
56 mm sq. (2.20 inch sq.)



Unipolar

Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
–	–	103H7121-0140	103H7121-0110	41.8 (1.65)
DU16H711S	DU16H711D	103H7121-0440	103H7121-0410	41.8 (1.65)
–	–	103H7121-0740	103H7121-0710	41.8 (1.65)
–	–	103H7123-0140	103H7123-0110	53.8 (2.12)
DU16H713S	DU16H713D	103H7123-0440	103H7123-0410	53.8 (2.12)
–	–	103H7123-0740	103H7123-0710	53.8 (2.12)
–	–	103H7124-0140	103H7124-0110	63.8 (2.51)
–	–	103H7124-0440	103H7124-0410	63.8 (2.51)
–	–	103H7124-0740	103H7124-0710	63.8 (2.51)
–	–	103H7126-0140	103H7126-0110	75.8 (2.98)
DU16H716S	DU16H716D	103H7126-0440	103H7126-0410	75.8 (2.98)
–	–	103H7126-0740	103H7126-0710	75.8 (2.98)

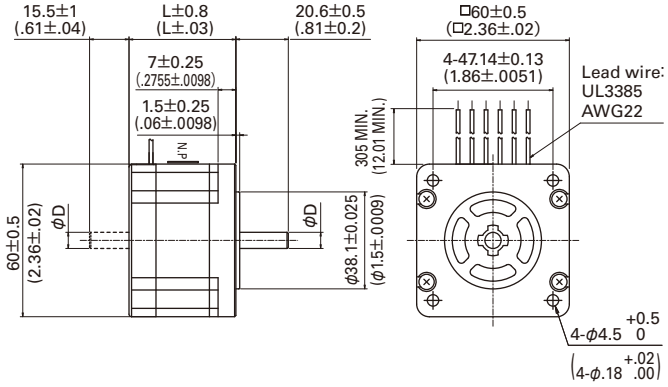
56 mm sq. (2.20 inch sq.)



Bipolar

Set model number		Motor model number		Motor length (L)	Shaft diameter (D)	Dcut thickness (T)
Single shaft	Dual shaft	Single shaft	Dual shaft			
–	–	103H7121-5640	103H7121-5610	41.8 (1.65)	φ 6.35 (φ 0.25)	5.8 (0.23)
DB16H711S	DB16H711D	103H7121-5740	103H7121-5710	41.8 (1.65)	φ 6.35 (φ 0.25)	5.8 (0.23)
–	–	103H7121-5840	103H7121-5810	41.8 (1.65)	φ 6.35 (φ 0.25)	5.8 (0.23)
–	–	103H7123-5640	103H7123-5610	53.8 (2.12)	φ 6.35 (φ 0.25)	5.8 (0.23)
DB16H713S	DB16H713D	103H7123-5740	103H7123-5710	53.8 (2.12)	φ 6.35 (φ 0.25)	5.8 (0.23)
–	–	103H7123-5840	103H7123-5810	53.8 (2.12)	φ 6.35 (φ 0.25)	5.8 (0.23)
–	–	103H7126-5640	103H7126-5610	75.8 (2.98)	φ 6.35 (φ 0.25)	5.8 (0.23)
DB16H716S	DB16H716D	103H7126-5740	103H7126-5710	75.8 (2.98)	φ 6.35 (φ 0.25)	5.8 (0.23)
–	–	103H7126-5840	103H7126-5810	75.8 (2.98)	φ 6.35 (φ 0.25)	5.8 (0.23)
–	–	103H7128-5640	103H7128-5610	94.8 (3.73)	φ 8 (φ 0.31)	7.5 (0.30)
–	–	103H7128-5740	103H7128-5710	94.8 (3.73)	φ 8 (φ 0.31)	7.5 (0.30)
–	–	103H7128-5840	103H7128-5810	94.8 (3.73)	φ 8 (φ 0.31)	7.5 (0.30)

60 mm sq. (2.36 inch sq.)



Note: A unipolar motor is illustrated; bipolar motors have four lead wires.

Unipolar

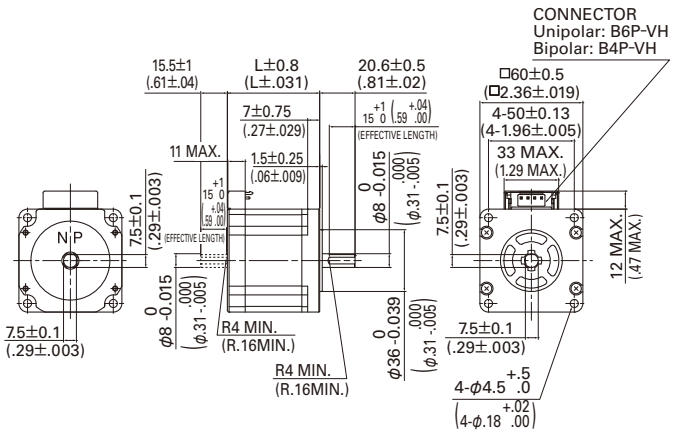
Set model number		Motor model number		Motor length (L)	Shaft diameter (D)
Single shaft	Dual shaft	Single shaft	Dual shaft		
–	–	SH1601-0440	SH1601-0410	42 (1.65)	φ 6.35 0 -0.013 (φ .25 .0000 -.0005)
–	–	SH1602-0440	SH1602-0410	54 (2.13)	φ 6.35 0 -0.013 (φ .25 .0000 -.0005)
–	–	SH1603-0440	SH1603-0410	76 (2.99)	φ 8 0 -0.015 (φ .31 .0000 -.0006)

Bipolar

Set model number		Motor model number		Motor length (L)	Shaft diameter (D)
Single shaft	Dual shaft	Single shaft	Dual shaft		
DB16S161S	DB16S161D	SH1601-5240	SH1601-5210	42 (1.65)	φ 6.35 0 -0.013 (φ .25 .0000 -.0005)
DB16S162S	DB16S162D	SH1602-5240	SH1602-5210	54 (2.13)	φ 6.35 0 -0.013 (φ .25 .0000 -.0005)
–	–	SH1603-5240	SH1603-5210	76 (2.99)	φ 8 0 -0.015 (φ .31 .0000 -.0006)

Stepping motors [Unit: mm (inch)]

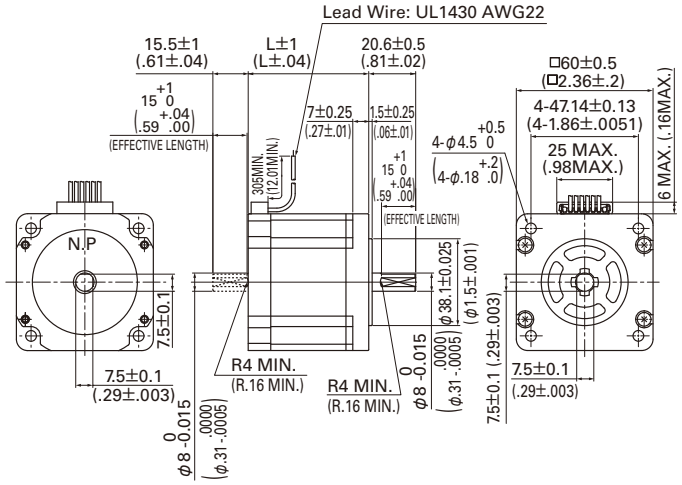
60 mm sq. (2.36 inch sq.)



Note: A bipolar motor is illustrated.

60 mm sq. (2.36 inch sq.)

(Dimensions for attaching NEMA23 are interchangeable)



Note: A unipolar motor is illustrated; bipolar motors have four lead wires.

Unipolar

Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
–	–	103H7821-0140	103H7821-0110	44.8 (1.76)
–	–	103H7821-0440	103H7821-0410	44.8 (1.76)
–	–	103H7821-0740	103H7821-0710	44.8 (1.76)
–	–	103H7822-0140	103H7822-0110	53.8 (2.12)
–	–	103H7822-0440	103H7822-0410	53.8 (2.12)
–	–	103H7822-0740	103H7822-0710	53.8 (2.12)
–	–	103H7823-0140	103H7823-0110	85.8 (3.38)
–	–	103H7823-0440	103H7823-0410	85.8 (3.38)
–	–	103H7823-0740	103H7823-0710	85.8 (3.38)

Bipolar

Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
DB16H781S	DB16H781D	103H7821-5740	103H7821-5710	44.8 (1.76)
DB16H782S	DB16H782D	103H7822-5740	103H7822-5710	53.8 (2.12)
DB16H783S	DB16H783D	103H7823-5740	103H7823-5710	85.8 (3.38)
–	–	103H7821-1740	103H7821-1710	44.8 (1.76)
–	–	103H7822-1740	103H7822-1710	53.8 (2.12)
–	–	103H7823-1740	103H7823-1710	85.8 (3.38)

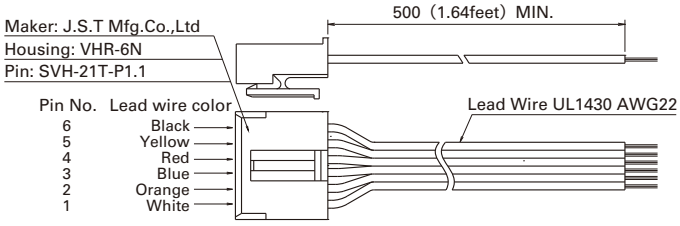
Unipolar

Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
–	–	103H7821-0160	103H7821-0130	43.5 (1.71)
–	–	103H7821-0460	103H7821-0430	43.5 (1.71)
–	–	103H7821-0760	103H7821-0730	43.5 (1.71)
–	–	103H7822-0160	103H7822-0130	52.5 (2.07)
–	–	103H7822-0460	103H7822-0430	52.5 (2.07)
–	–	103H7822-0760	103H7822-0730	52.5 (2.07)
–	–	103H7823-0160	103H7823-0130	84.5 (3.33)
–	–	103H7823-0460	103H7823-0430	84.5 (3.33)
–	–	103H7823-0760	103H7823-0730	84.5 (3.33)

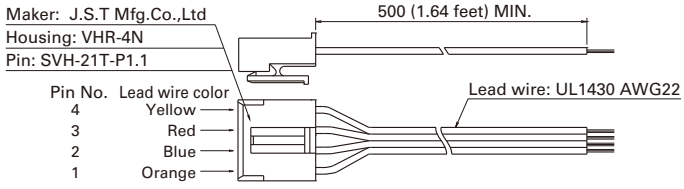
Bipolar

Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
–	–	103H7821-5760	103H7821-5730	43.5 (1.71)
–	–	103H7821-1760	103H7821-1730	43.5 (1.71)
–	–	103H7822-5760	103H7822-5730	52.5 (2.07)
–	–	103H7822-1760	103H7822-1730	52.5 (2.07)
–	–	103H7823-5760	103H7823-5730	84.5 (3.33)
–	–	103H7823-1760	103H7823-1730	84.5 (3.33)

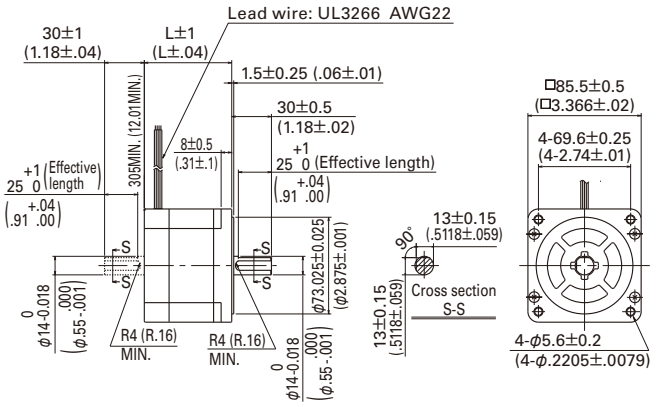
Motor cable Unipolar Model number: 4837798-1



Motor cable Bipolar Model number: 4837961-1



86 mm sq. (3.39 inch sq.)



Note: A bipolar motor is illustrated; unipolar motors have six lead wires.

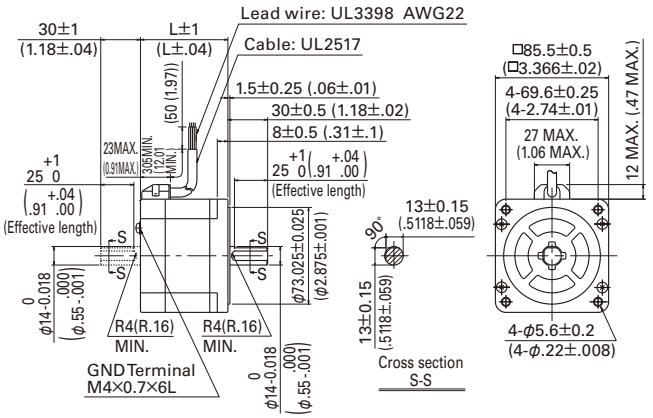
Unipolar

Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
–	–	SH2861-0441	SH2861-0411	66 (2.6)
–	–	SH2861-0941	SH2861-0911	66 (2.6)
–	–	SH2862-0441	SH2862-0411	96.5 (3.8)
–	–	SH2862-0941	SH2862-0911	96.5 (3.8)
–	–	SH2863-0441	SH2863-0411	127 (5)
–	–	SH2863-0941	SH2863-0911	127 (5)

Bipolar

Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
–	–	SH2861-5041	SH2861-5011	66 (2.6)
–	–	SH2861-5141	SH2861-5111	66 (2.6)
–	–	SH2861-5241	SH2861-5211	66 (2.6)
–	–	SH2862-5041	SH2862-5011	96.5 (3.8)
–	–	SH2862-5141	SH2862-5111	96.5 (3.8)
–	–	SH2862-5241	SH2862-5211	96.5 (3.8)
–	–	SH2863-5041	SH2863-5011	127 (5)
–	–	SH2863-5141	SH2863-5111	127 (5)
–	–	SH2863-5241	SH2863-5211	127 (5)

86 mm sq. (3.39 inch sq.) CE · UL Model



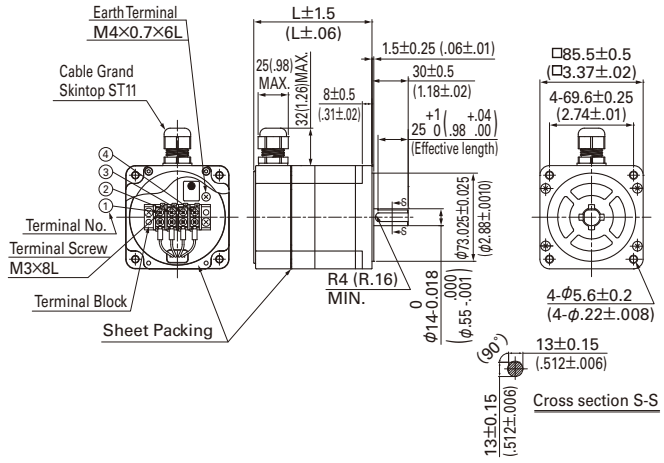
Unipolar CE · UL Model

Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
–	–	SM2861-0451	SM2861-0421	66 (2.6)
–	–	SM2861-0951	SM2861-0921	66 (2.6)
–	–	SM2862-0451	SM2862-0421	96.5 (3.8)
–	–	SM2862-0951	SM2862-0921	96.5 (3.8)
–	–	SM2863-0451	SM2863-0421	127 (5)
–	–	SM2863-0951	SM2863-0921	127 (5)

Bipolar CE · UL Model

Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
–	–	SM2861-5051	SM2861-5021	66 (2.6)
–	–	SM2861-5151	SM2861-5121	66 (2.6)
–	–	SM2861-5251	SM2861-5221	66 (2.6)
–	–	SM2862-5051	SM2862-5021	96.5 (3.8)
–	–	SM2862-5151	SM2862-5121	96.5 (3.8)
–	–	SM2862-5251	SM2862-5221	96.5 (3.8)
–	–	SM2863-5051	SM2863-5021	127 (5)
–	–	SM2863-5151	SM2863-5121	127 (5)
–	–	SM2863-5251	SM2863-5221	127 (5)

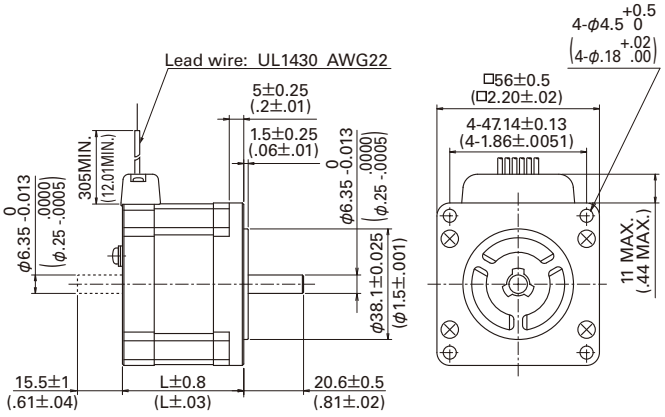
86 mm sq. (3.39 inch sq.) CE · UL Model



Bipolar terminal block type CE · UL Model

Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
–	–	SM2861-5066	–	97.9 (3.9)
–	–	SM2861-5166	–	97.9 (3.9)
–	–	SM2861-5266	–	97.9 (3.9)
–	–	SM2862-5066	–	128.4 (5.1)
–	–	SM2862-5166	–	128.4 (5.1)
–	–	SM2862-5266	–	128.4 (5.1)
–	–	SM2863-5066	–	158.8 (6.3)
–	–	SM2863-5166	–	158.8 (6.3)
–	–	SM2863-5266	–	158.8 (6.3)

56 mm sq. (2.20 inch sq.) CE Model

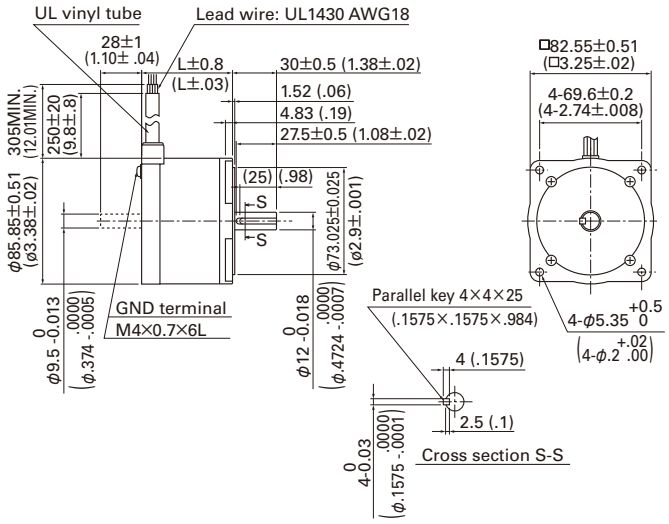


Unipolar CE Model

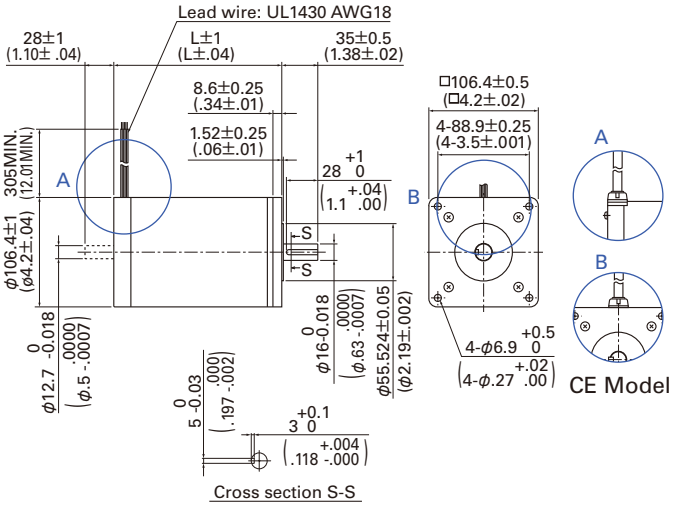
Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
–	–	103H7121-6140	103H7121-6110	41.8 (1.65)
–	–	103H7121-6740	103H7121-6710	41.8 (1.65)
–	–	103H7123-6140	103H7123-6110	53.8 (2.12)
–	–	103H7123-6740	103H7123-6710	53.8 (2.12)
–	–	103H7126-6140	103H7126-6110	75.8 (2.98)
–	–	103H7126-6740	103H7126-6710	75.8 (2.98)

Stepping motors [Unit: mm (inch)]

φ86 mm (φ3.39 inch) CE Model



φ106 mm (φ4.17 inch)



Bipolar CE Model

Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
–	–	103H8221-6240	103H8221-6210	62 (3.31)
–	–	103H8222-6340	103H8222-6310	92.2 (5.51)
–	–	103H8223-6340	103H8223-6310	125.9 (7.72)

Unipolar

Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
–	–	103H89222-0941	103H89222-0911	163.3 (6.4)
–	–	103H89223-0941	103H89223-0911	221.3 (8.7)

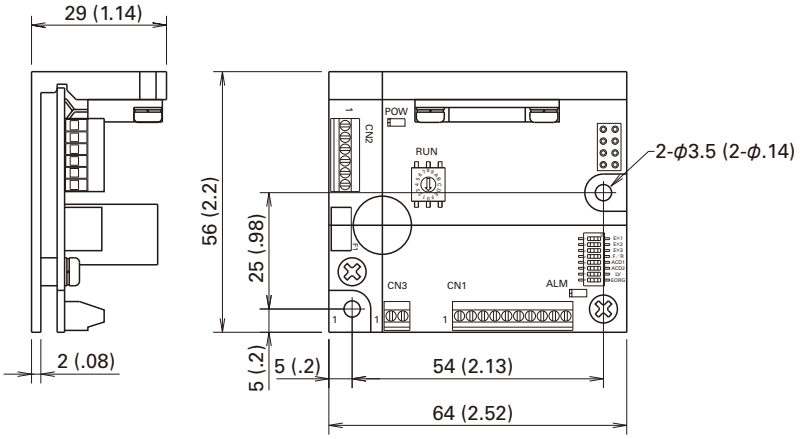
Bipolar

Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
–	–	103H89222-5241	103H89222-5211	163.3 (6.4)
–	–	103H89223-5241	103H89223-5211	221.3 (8.7)

Bipolar CE Model

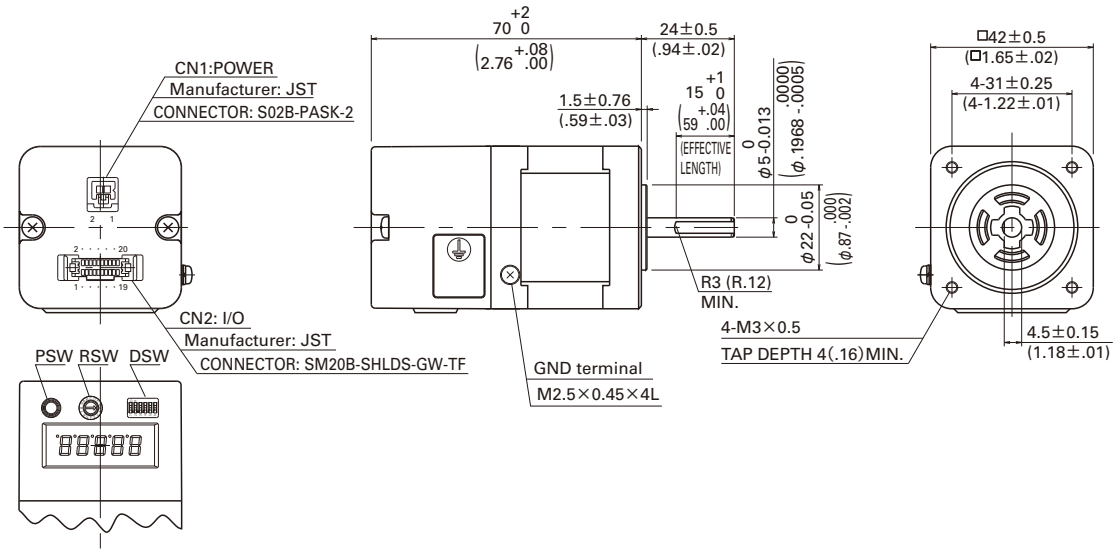
Set model number		Motor model number		Motor length (L)
Single shaft	Dual shaft	Single shaft	Dual shaft	
–	–	103H89222-6341	103H89222-6311	163.3 (6.4)
–	–	103H89223-6341	103H89223-6311	221.3 (8.7)

Stepping Drivers [Unit: mm (inch)]

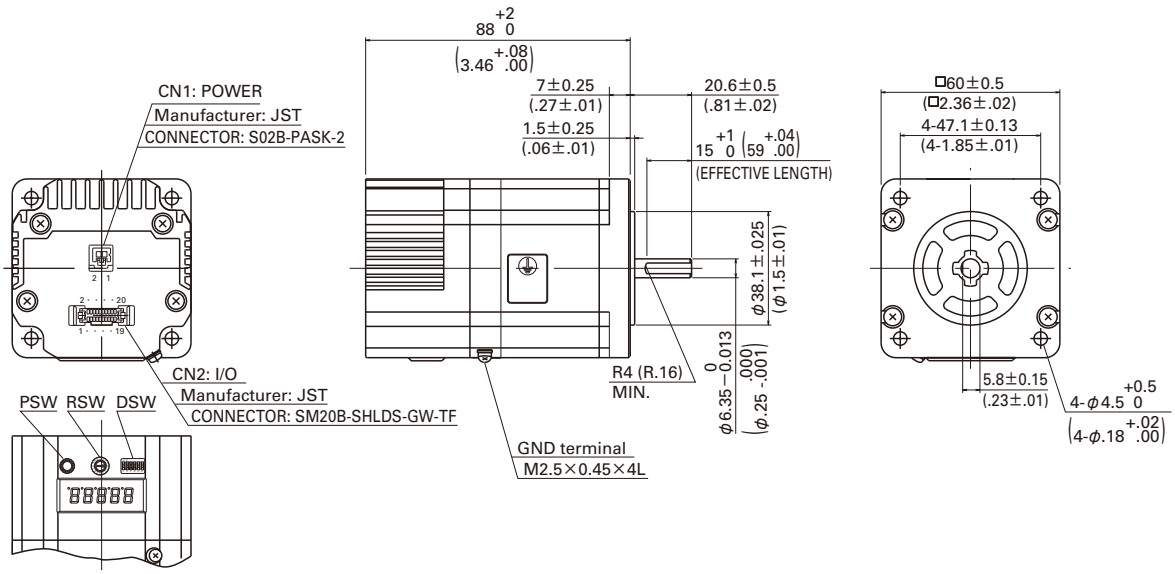


Stepping Motors with Integrated Drivers [Unit: mm (inch)]

42 mm sq. (1.65 inch sq.)



60 mm sq. (2.36 inch sq.)

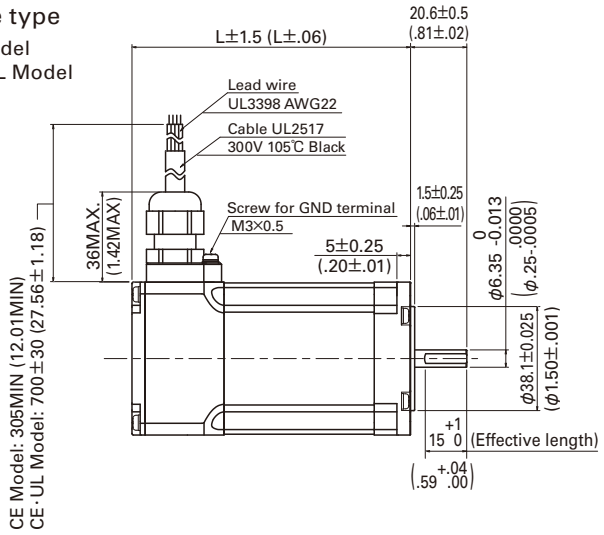


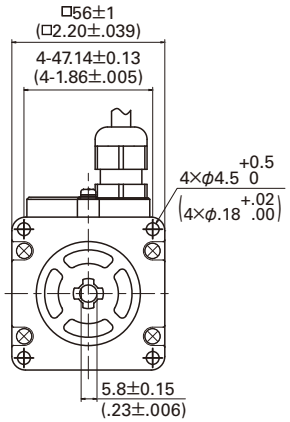
IP65 Splash and Dust Proof Stepping Motors [Unit: mm (inch)]

56 mm sq. (2.20 inch sq.)

Cable type

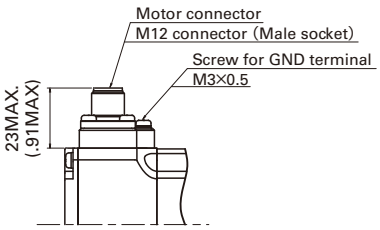
CE Model
CE・UL Model





Connector type

CE Model

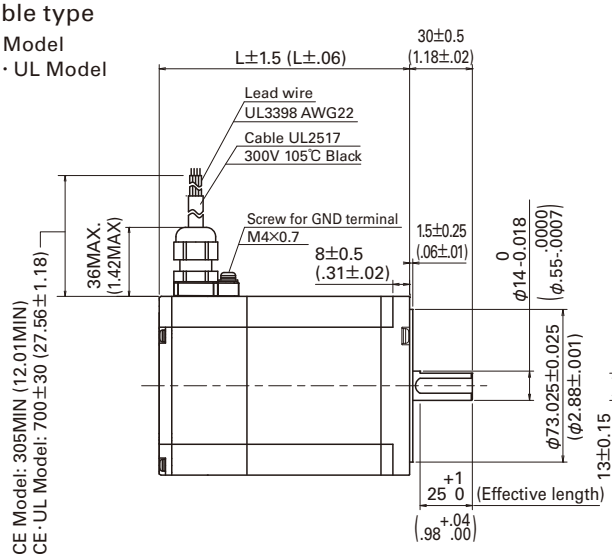


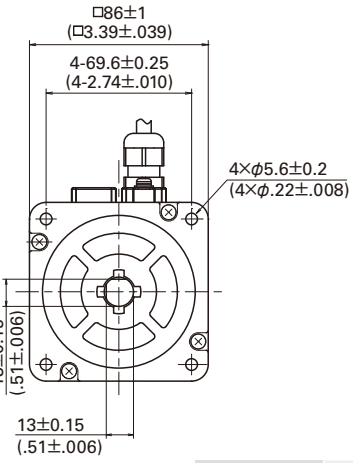
Safety standards	Model number		Motor length (L)
	Cable type	Connector type	
CE Model	SP2563T-5 □ 60	SP2563T-5 □ 00	80 (3.15)
	SP2566T-5 □ 60	SP2566T-5 □ 00	102 (4.02)
CE・UL Model	SP2563-5 □ 60	—	80 (3.15)
	SP2566-5 □ 60	—	102 (4.02)

86 mm sq. (3.39 inch sq.)

Cable type

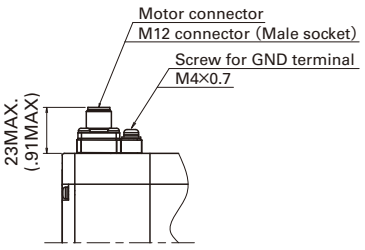
CE Model
CE・UL Model





Connector type

CE Model



Safety standards	Model number		Motor length (L)
	Cable type	Connector type	
CE Model	SP2862T-5 □ 60	SP2862T-5 □ 00	120 (4.72)
	SP2863T-5 □ 60	SP2863T-5 □ 00	150 (5.91)
CE・UL Model	SP2862-5 □ 60	—	120 (4.72)
	SP2863-5 □ 60	—	150 (5.91)

Safety Consideration

Drivers and stepping motors are products designed to be used for the general industrial devices.
When using them, pay sufficient attention to the following points.

- Read the Operation Manual throughly prior to placement, assembly and/or operation in order to use the product properly.
- Refrain from modifying or processing the product in any way.
- Consult with the distributor or professional experts for placement or maintenance services of the product.
- In case of the following uses of the product, contact us for the special care required to the operation, maintenance and management such as multiplexing the system, installing an emergency electric generator set, or so forth.
  - ❶ **Use for the medical devices concerned with a fatal accident .**
  - ❷ **Use for trains, elevators, and so forth that are likely to cause an accident resulting in injury, damage or death.**
  - ❸ **Use in computer systems that could have a great effect on society or public systems.**
  - ❹ **Use in other devices highly influential to maintaining the human safety or the public functions.**

In addition to the above, consult with us for use in such a vibration environment as automobile or transportation.
Make yourself knowledgeable and familiarize with the devices, safety issues and cautions before handling the product.

Indication by (Warning Label) on the Product

Either or all of the following indications are expressed by the Warning Labels depending on the type of driver or stepping motor.

This label is affixed near high voltage parts such as the electrically charged or cover-protected section, warning of the places where it is likely to cause an electric shock.

This label is affixed near the place where the driver or stepping motor body should be easily acknowledged, warning that it is likely to cause burns from high temperature.

This label is affixed near the GND terminals of the driver or stepping motors for which grounding is required, suggesting that the terminals should be well grounded.

This label is affixed for the driver or stepping motor to which the power source is applied in the voltage exceeding the safety standard, drawing attention to the risk of the electric shock.

Safety ranks of the cautions

Following four ranks are provided.

Improper operations or use is most likely to result in serious injury or death.

Improper operations or use is likely to result in average or minor injury, or in property damage.

> In spite of the cautions with the ⚠CAUTION CAUTION label, it may cause serious results.
> Either the contents of the labels is describing important cautions to be followed inevitably.

Indicates what must not be done.

Indicates what must be done.

DANGER

< General matters >

1. Do not use the product in an explosive, flammable or corrosive atmosphere, watery place or near a combustible material. Doing so may cause injury or fire.
2. Have a person with expert knowledge for performing the transportation, placement, wiring, operation, maintenance or inspection of the product.
   Without such knowledge, it may cause an electric shock, injury or fire.
3. Do not work for wiring, maintenance servicing or inspection with the electric power on. Perform either of those five minutes after turning the power off, or otherwise, it may cause an electric shock.
4. When the protective functions of the product is activated, turn the power off mmediately and eliminate the cause. If continuing the operation without eliminating the cause, the product may operate improperly and cause injury or a breakdown of the system devices.
5. Stepping motor may run out of order at the operating and stopping occasions, depending on the magnitude of the load. Put the product into use after confirming with the adequate trial test operation in the maximum load conditions that the product performs reliable operation. Doing otherwise may cause a breakdown of the system. (Should the product run out of order in the use to drive upward/ downward, it may cause a fall of the load.)
6. Do not touch the internal parts of the driver. Doing so may cause an electric shock.

< Wiring >

7. Do not connect the stepping motor directly with the commercial power outlet. Doing so may cause an electric shock, injury or fire. The power shall be supplied to the stepping motor through the driving circuit.
8. Use the electric power source within the rated input voltage. Using otherwise may cause fire or an electric shock.
9. Connect the driver and stepping motor to the ground. Using without grounding may cause an electric shock.
10. Do not harm, forcibly put a stress, or load a heavy article on the cable or get it caught between the articles. Doing so may cause an electric shock.
11. Perform wiring with the power cable as instructed by the wiring diagram or the Operation Manual. Doing otherwise may cause an electric shock or fire.

< Operation >

12. Be sure not to touch the rotating part of the stepping motor during its operation. Touching it may cause injury.
13. Neither reach or touch the electric terminals while electric power is on. Doing so may cause an electric shock.
14. Never disconnect any of the connectors while electric power is on. Doing so may cause an electric shock and corruption.

< General matters >

1. Prior to placement, operation, maintenance servicing or inspection, be sure to read the Operation Manual and follow the instructions to perform those. Failure to follow the instructions may cause an electric shock, injury or fire.
2. Do not use the driver or the stepping motor outside the specified conditions.
   Doing so may cause an electric shock, injury or fire.
3. Do not insert a finger or a thing into the opening of the product. Doing so may cause an electric shock, injury or fire.
4. Do not use the damaged driver or stepping motor. Doing so may cause injury, fire or the like.
5. Use the driver and stepping motor in the designated combination. Using otherwise may cause fire or a trouble.
6. Be careful that the temperature rises in the operating driver, stepping motor or peripheral devices. Failure to be careful may cause a burn.

< Unpacking >

7. Unpack while confirming the ceiling. Failure to do so may cause injury.
8. Confirm if the product is the one having been ordered. Installing an incorrect product may cause a breakdown.

< Wiring >

9. Do not perform measurement of the insulation resistance or withstand insulation voltage of the product. Doing so may cause a breakdown. Instead, contact with us for such inspection.
10. Perform wiring conforming to the technical standards of electric facility or the internal rule. Doing otherwise may cause burning or fire.
11. Ensure that wiring has been correctly done. Operating without correct wiring may cause the stepping motor to run out of control and result in injury.
12. Take insulation process for the attached condenser or the external resistance connection terminals. Failure to do so may cause an electric shock.

< Placement >

13. Do not climb or attach a heavy article on the product. Doing so may cause injury.
14. Neither block nor stuff the aspiration/exhaust vent with a foreign particle. Doing so may cause fire.
15. Follow the instructions for the direction to place. Failure to do so may cause a trouble.
16. Keep a distance as instructed by the Operation Manual for the driver from the inner surface of the control console or other devices. Failure to do so may cause a trouble.
17. Place the product with a great care so as to prevent from the danger such as a tumble or a turnover.

CAUTION

18. Mount the product on an incombustible material such as metal. Doing otherwise may cause fire.
19. Confirm the rotating direction before connecting with the mechanical device. Failure to do so may cause injury or a breakdown.
20. Do not touch the motor output spindle (including the key slot and gears) with a bare hand. Doing so may cause injury.

< Operation >

21. The stepping motor is not equipped with any protective device. Takeprotective measures using an over-current protective relay, a ground fault interrupter, a protective device from excess temperature, and an emergency stopping device. Failure to do so may cause injury or fire.
22. Do not touch the product for a period after the power is on or has been turned off, since the driver and stepping motor remain in the high temperature. Doing so may cause burns. Especially the temperature rises considerably of the stepping motor depending on the operating conditions. Use the motor on the condition so that its surface temperature becomes 100˚ C or under.
23. Stop the operation immediately when an emergency occurs. Failure to do so may cause an electric shock, injury or fire.
24. Do not change adjustment to an extreme, for such a change results in the unstable operation. Doing so may cause injury.
25. When conducting the trial operation, make the stepping motor fixed firmly, and confirm the operation by disconnecting with the mechanical system before connecting with it. Failure to do so may cause injury.
26. When the alarm has been activated, eliminate the cause and ensure the safety to resume operation. Failure to do so may cause injury.
27. When the electric power recovers after the momentary interruption, do not approach the devices because the system may re-start operation by itself. (Set the system so as to secure the safety even when it re-start on such occasion.) Failure to do so may cause injury.
28. Confirm that the electric power supply is all proper conforming to the specifications. Failure to do so may cause a trouble.
29. The brake mechanism of the motor with the electro-magnetic brake is to hold the movable section and the motor position. Do not use it as a safety measure, or doing so may cause the breakdown of the system.
30. Fix the key firmly when operating the motor with key individually. Failure to do so may cause injury.

< Maintenance services >

31. Be careful when performing maintenance services or inspection about the temperature which rises highly in the driver and stepping motor frame. Failure to do so may cause burns.
32. It is recommended to replace the electrolytic condenser of the driver with a new one for securing the preventive measure after using for 5 years, the expected life in the average 40˚C. The expected life of the fuse is 10 years in the average 40˚C. Thus, the periodical replacement is recommended.
33. Contact with us for repair. If the product is disassembled by the user, it may put it out of action.

< Transportation >

34. Handle the product with care during transportation so as to prevent from the danger such as a tumble or a turnover.
35. Do not hold with the cable or the motor spindle. Doing so may cause a trouble or injury.

< Retirement >

36. When scrapping the driver or stepping motor, treat it for the general industrial waste.

PROHIBITED

< Storage >

1. Avoid the place exposed to rain or water drops, or in an environment with hazardous gas or liquid for storing the product. Failure to do so may cause a trouble.

< Maintenance services >

2. Do not assemble or repair the product. Doing so may cause fire or an electric shock.

< General matters >

3. Do not remove the rating plate.

COMPULSORY

< Storage >

1. Store the product within the specified conservation temperature and humidity in the place not exposed to the sun beam.
2. If the driver has been stored for a long period (3 years or longer for a guide), consult with us. The capacitance may have decreased with the electrolytic condenser due to the long period storage, and it may cause a trouble.

< Operation >

3. Install an external emergency stop circuit to turn the power off for the instant halt of operation.
4. Put the product into operation in the specified ambient temperature and humidity.

< Transportation >

5. Excess loading of the product on the carrier may cause the load to fall in pieces. Follow the instructions given outside the package.

Inquiry Check Sheet

For more information regarding any products or services described herein, please contact your nearest office listed on the back of this catalog.

To SANYO DENKI Co., LTD.　　Date：

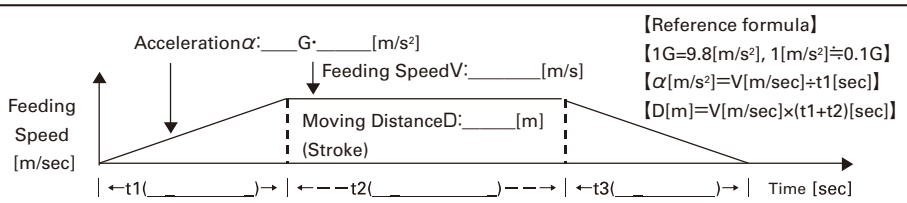
Company:

Department:

Name:

Tel:　　FAX:

E-mail:

	Item	Contents
❶	Name of target equipment	Equipment name, category (transport, processing, test, other)
❷	Name of servo axis	Axis name, axial mechanism (horizontal/vertical), brake mechanism (yes/no)
❸	Current condition of above axis	Manufacturer Name (　) Series Name (　) Motor Capacity (　) Hydraulic, Mechanical, or New System (　)
❹	Positioning accuracy	±　mm·±　μm
❺	Operation pattern	
❻	Mechanism	Ball-screw/screw-rotation type (horizontal), ball-screw/nut-rotation type (horizontal), rack and pinion (horizontal), belt/chain (horizontal), rotary table, roll feed, instability
❼	Mechanical structure	WT(table mass) kg　WL(work mass) kg　WA(mass of other drive parts) kg WR(rack mass) kg　WB(belt/chain mass) kg　WC(counterbalance mass) kg Fa(external force axial direction) N　Fb(ball-screw preload) N　T(roll pushing force) N Dr1(drive-side roll diameter) mm　Dr2(follower-side roll diameter) mm Lr1(drive-side roll length) mm　Lr2(follower-side roll length) mm　G(reduction ratio) JG(speed-reducer inertia) kg·m²　JC(coupling inertia) kg·m² JN(nut inertia) kg·m²　JO(other motor-axis conversion inertia) kg·m² Db(ball-screw diameter) mm　Lb(ball-screw axial length) mm　Pb(ball -screw lead) mm Dp(pinion/pulley diameter) mm　Lp(pinion axial length) mm　tp(pully thickness) mm Dt(table diameter) mm　Dh(table-support diameter) mm　LW(load shift from axis) mm Ds(table shaft diameter) mm　Ls(table shaft length) mm ρ(specific gravity of ball-screw/pinion/pulley/table-shaft material) kg·cm³ μ(friction coefficient between sheet and sliding surface/support-section/roll)　ρ1(specific gravity of roll-1 material) kg／cm³ ρ2(specific gravity of roll-2 material) kg／cm³　κ(internal friction coefficient of preload nut) η(mechanical efficiency)　JL(load inertia of motor-axis conversion) kg·m² TF(friction torque of motor axis conversion) N·m　Tu(imbalance torque of motor axis conversion) N·m
❽	Speed reducer	Customer-provided (　／　)·Sanyo Denki standard(planet/spur/no-backlash-planet　／　) other(　／　)
❾	Encoder type	Encoder type specified (yes / no) Yes: (Wiring saving incremental encoder, battery backup absolute encoder, absolute encoder for incremental system, batteryless absolute encoder) Resolution(　)
❿	Input format	Position, velocity, torque, other (　)
⓫	Host equipment (controller)	Sequencer, laptop, customer-developed product, Sanyo Denki-provided, other (　)
⓬	Usage environment and other requirements	Cutting, clean-room use, anti-dust measures, other (　)
⓭	Estimated production	Single product: (　) units/month (　) units/year
⓮	Development schedule	Prototype period: (　) Year (　) Month Production period: (　) Year (　) Month
⓯	Various measures	Related documentation (already submitted / send later by mail) Visit/PR desired (yes / no) Meeting desired (yes / no)
⓰	Miscellaneous (questions, pending problems, unresolved issues, etc.)	

■ Precautions For Adoption

Failure to follow the precautions on the right may cause moderate injury and property damage, or in some circumstances,could lead to a serious accident. Always follow all listed precautions.

⚠ Cautions

- Read the accompanying Instruction Manual carefully prior to using the product.
- If applying to medical devices and other equipment affecting people's lives, please contact us beforehand and take appropriate safety measures.
- If applying to equipment that can have significant effects on society and the general public, please contact us beforehand.
- Do not use this product in an environment where vibration is present, such as in a moving vehicle or shipping vessel.
- Do not perform any retrofitting, re-engineering, or modification to this equipment.
- The products presented in this catalog are meant to be used for general industrial applications. If using for special applications related to aviation and space, nuclear power, electric power, submarine repeaters, etc., please contact us beforehand.

*For any question or inquiry regarding the above, contact our Sales Department.

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*Remarks: Specifications are subject to change without notice.

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